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Multiple-Scale Analysis of Boundary-Value Problems in Thick Multi-Level Junctions of Type 3:2:2
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Taras Mel'nyk • Dmytro Sadovyi

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Springer

Taras Mel'nyk<br>Faculty of Mechanics and Mathematics<br>Taras Shevchenko National University of Kyiv<br>Kyiv, Ukraine

Dmytro Sadovyi<br>Faculty of Mechanics and Mathematics<br>Taras Shevchenko National University of Kyiv<br>Kyiv, Ukraine

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## Preface

Multiple-scale analysis of boundary-value problems (elliptic and parabolic, linear and semilinear) in domains with very complicated structure is the main topic of this book. In the scientific literature such domains are called either domains with very high oscillating boundaries or thick junctions. Special kinds of such domains are considered in the book, namely thick multilevel junctions consisting of a cylinder on which thin annular discs from two different sets are $\varepsilon$-periodically and alternatively strung. The thin annular discs are divided into two sets (levels) depending on their geometric structure and boundary conditions imposed on their surfaces. Different Dirichlet, Neumann, and Robin (linear and nonlinear) boundary conditions are considered. The thin discs can have variable thickness vanishing at their edges, including the case when their boundaries are not Lipschitz.

Qualitatively different cases in the asymptotic behavior of solutions to these problems are discovered when the small parameter $\varepsilon$ tends to zero, i.e., when the number of attached thin discs of each level infinitely increases and their thickness vanish. Different asymptotic methods and approaches developed intensively during the past two decades are used to prove convergence theorems, to construct asymptotic approximations for the solutions, and to derive the corresponding homogenized problems.

Results presented here have already been published in our articles in mathematical journals, but we give here a complete and unified presentation including a full literature review on this topic. The text will be useful for researchers and graduate students in asymptotic analysis and applied mathematics as well as for physicists, chemists, and engineers interested in the investigation of different processes, including heat and mass transfer, in their applications.

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## Chapter 1 Introduction

## Motivation

A lot of modern engineering constructions and biological systems have complex geometric forms. The reason is that some physical properties of materials are controlled by their geometric construction. Therefore, studying the effect of the geometric structure of a material can help to improve some of its beneficial physical properties and reduce undesirable effects. Mathematical models for this study are boundary-value problems (BVPs) in complex domains: perforated domains, griddomains, thin domains with rapidly varying thickness, junctions of thin domains of different configurations, networks, etc.

A thick junction of the type $m: k: d$ is a union of some domain in $\mathbb{R}^{n}$ (called a junction's body) and a large number of thin domains, which are $\varepsilon$-periodically attached to some manifold on the boundary of the junction's body. This manifold is called a joint zone. The small parameter $\varepsilon$ characterizes the distance between neighboring thin domains and also their thickness. The type $m: k: d$ of a thick junction refers, respectively, to limiting dimensions (as $\varepsilon \rightarrow 0$ ) of the junction's body $(m)$, the joint zone $(k)$, and each of the attached thin domains $(d)$.

Various constructions shaped as thick junctions are successfully used in nanotechnologies, microtechnique, modern engineering constructions, for example, microstrip radiators, wide-bandgap semiconductors, efficient sensors (inertial, biological, chemical), signal processing filters, transistors, heat radiators [25, 40, 69, $71]$. Figure 1.1 shows heat radiators in the form of thick junctions; such radiators are used in order to radiate more heat from a given total volume. Also, many biological systems (e.g., viruses, intestinal lining) have the thick junction form.

Now engineering approaches are capable of creating freestanding objects with villi thickness to about 20 nm . Therefore, it is often impossible to solve BVPs in thick junctions directly with numerical methods, because this would require too much CPU resources considering a large number of components of thick junctions


Fig. 1.1 Heat radiators shaped as thick junctions of the type 3:2:2
(in some cases few thousands). Increase in the size of computational domains for thick multi-structures naturally leads to longer computing times and makes it very difficult to maintain an acceptable level of the accuracy.

Thus, the development of new mathematical tools is necessary. One of them is asymptotic analysis of BVPs in thick junctions as $\varepsilon \rightarrow 0$, i.e., when the number of attached thin domains infinitely increases and their thickness decreases to zero. Asymptotic results give us the possibility to replace the original problem in a thick junction by the corresponding homogenized problem that is simpler and then apply computer simulation. In addition, in some cases it is possible to construct accurate and numerically implementable asymptotic approximations.

Also with the help of asymptotic analysis, it is possible to find new unexpected properties of solutions to such problems, which in turn make it possible to mathematically justify different physical (or biological) phenomena of such structures (see e.g., "Literature review" in this Introduction and Conclusions to Chapters).

The main difficulties in the study of BVPs in thick junctions
Thick junctions have a special character of the connectedness: there are points in a thick junction that are at a short distance of order $\mathscr{O}(\varepsilon)$, but length of all curves, which connect these points in the junction, is of order $\mathscr{O}(1)$. As a result, there is no sequence of extension operators $\left\{E: W^{1, p}\left(D_{\varepsilon}\right) \mapsto W^{1, p}\left(\mathbb{R}^{n}\right)\right\}_{\varepsilon>0}$ whose norms are uniformly bounded in $\varepsilon$ (see e.g. [15, 79]) ; here $D_{\varepsilon}$ is some thick junction.

At the same time, the availability of a uniformly bounded family of extension operator is a typical supposition in overwhelming majority of the existing homogenization schemes for problems in perforated domains with the Neumann or Robin boundary conditions (see e.g., [59, 65, 73, 74]). The existence of such extensions for $\varepsilon$-periodically perforated domains was proved in [22, 124].

Also because of a such connectedness, it is impossible to apply the boundary trace embedding theorems in the Sobolev spaces $W^{1, p}\left(D_{\varepsilon}\right)$ with a constant that is independent of $\varepsilon$.

In addition, thick junctions are non-convex domains with non-smooth boundaries. Therefore, solutions of BVPs in such domains have only minimal $H^{1}$-smoothness, while the $H^{2}$-smoothness of solutions is necessary for some homogenization procedures (see e.g., [23]).

There are two ways to study BVPs in thick junctions. The first one consists of the proof of convergence results for solutions (so- called convergence theorems).

The second one is related to obtaining the formal asymptotics for a solution and its justification (establish an asymptotic error estimate). The corresponding homogenized problem is derived from the limit problems for each domain forming the thick junction with the help of solutions to junction-layer problems around the joint zone. However, junction-layer solutions have polynomial or logarithmic growth at infinity and do not decrease exponentially as in many boundary-layer problems. Their behavior depends on the junction type $m: k: d$, and they influence directly the leading terms of the asymptotics (see e.g., Chap. 5). This explains the introduction of such a classification.

It should be noted here that an important problem for each asymptotic method is its accuracy. Therefore, the proof of the error estimate for the discrepancy between the constructed approximation and the original solution is a general principle that has been applied to the analysis of the efficiency of the proposed asymptotic method. How to do this, if the junction-layer solutions grow at infinity was until recently an open question.

All those factors mentioned above create special difficulties in the asymptotic investigation of BVPs in thick junctions.

## Literature review

As far as we know, the first works in this direction were papers by E.Ya. Khruslov [60], V.P. Kotlyarov and E.Ya. Khruslov [64], V.O. Marchenko and E.Ya. Khruslov [73, Sect. 5], in which convergence theorems were proved for the Green functions of Neumann problems for the Helmholtz equation in unbounded thick junctions of type 3:2:1. This was done either under assumptions of the convergence of certain components of the problem, or in case when the junction's body is a half-space. It should be noted that thick junctions considering in those papers have no periodicity in the distribution of the thin domains forming the junction.

## Spectral problems

The limit equations describing acoustic vibrations in a porous medium, made periodically by narrow parallel channels or by thin parallel sheets in a solid body (the thick junctions of the type $3: 2: 1$ or $3: 2: 2$, respectively), were obtained by using the homogenization technique (two-scale asymptotic expansion method) in [8, 41, 130]. In these papers, the authors have established some new qualitative properties of the homogenized equations: the corresponding Helmholtz equation is no longer elliptic; the operator which corresponds to the spectral limit problem is non-compact and, as a result, ". . . an exhaustive study of the spectral properties will not be done" (see [41, Sect. 3, p. 163]). It should be noted that convergence theorems and asymptotic
estimates were not proved in these papers. The same results were obtained in [8] for problems in a thick junction of type 3:2:2.

Independently of the publications mentioned above, in the early 90 s the complete asymptotic analysis of the Neumann spectral problems for the Laplace operator in thick junctions of types $2: 1: 1$ in $\mathbb{R}^{2}$ and $2: 1: 1,3: 1: 1$ in $\mathbb{R}^{3}$ was carried out in [104-107]. Namely, the corresponding homogenized spectral problems were found, their spectrum structures were determined, with the help of the method of matching asymptotic expansions the asymptotic approximations for eigenfunctions and also for the eigenvalues were constructed, and the corresponding asymptotic error estimates were proved.

One of the main and unexpected results of these problems is as follows. The spectrum of the original problem is split into countable family of series with different limits that constitute the spectrum of the corresponding homogenized problem. So, for the Neumann spectral problem in a thick junction type 2:1:1 (see [104]) the limits of the eigenvalues from each series form the sequence of the discrete eigenvalues of the homogenized problem from a finite interval (these intervals are mutually disjoint) and the left ends of these intervals belong to the essential spectrum of the homogenized problem. Moreover, there are a countable set of gaps in the spectrum ( $a$ gap is a bounded open interval having an empty intersection with the spectrum, but its ends belong to it). Such complex asymptotic behavior of the eigenvalues substantiates mathematically the well-known "loss reduction" phenomenon in comb-like waveguides [56] (for more detail see [107, 108]).

The question of the existence of spectral gaps has been actively investigated in last time since it is very important for the description of wave propagations in different mediums (see [53] for a lot of examples and references on this topic). In the case when the thin rods forming a thick junction have various length, the structure of the essential spectrum is more complex [82, 84] and choosing appropriately different lengths of the thin rods one can build a thick junction with the given number of gaps in the spectrum.

It is turned out that type of a thick junction determines not only the structure of the boundary layer in the junction zone, but also the principal properties of the homogenized problem, in particular, the structure of its spectrum. So, if the limit dimensions of the junction's body and the contact zone differ by 1 (i.e., $m-k=$ 1 ), then it is possible to reduce the homogenized spectral problem to a spectral problem for some discontinuous self-adjoint operator-function. The spectrum of such operator-functions was studied in [51, 75, 108].

If we consider some boundary-value problem in a thick junction of the type $m: k: d$, where $m-k \neq 1$, then any transmission conditions are not reasonable in the joint zone for the corresponding homogenized problem in the Sobolev space $W^{1, p}$. For instance, if the junction in question is of type $3: 1: 1$, then the junction zone becomes a curve $\Gamma$ on the three-dimensional junction's body in the limit. In [105, 109], the spectral Neumann problem in a thick junction of type 3:1:1 was examined with simultaneous perturbation of the rigidity and density of the thin cylinders. Because of this some asymptotic "stratification" of the spectrum in question appears. The spectrum of the corresponding homogenized problem turns out to be related to the
spectrum of a certain integral operator on $\Gamma$. Without the perturbation of the rigidity and density of the thin cylinders, the spectral Neumann problem was considered in [78, 88]. For this problem, we have the loss of self-adjointness in the limit in general. In fact, three spectral problems form the asymptotics for the eigenvalues and eigenfunctions of this problem, namely, the Neumann spectral problem in the junction's body; a spectral problem in a plane domain that is filled up by the thin cylinders in the limit (each eigenvalue of this problem has infinite multiplicity); and a spectral problem for a singular integral operator given on $\Gamma$.

Dirichlet spectral problems with purely density perturbations $\varepsilon^{-\alpha}$ on the rods of a thick junction of type 2:1:1 were studied in [77, 80, 86]. Depending on the parameter $\alpha(\alpha<2, \alpha=2, \alpha>2)$, three qualitatively different cases in the asymptotic behavior of the eigenvalues and eigenfunctions were discovered. There are three kinds of vibrations, which are present in each of these cases: vibrations, whose energy is concentrated in the junction's body; vibrations, whose energy is concentrated on the thin rods; and vibrations (pseudo-vibrations) having quickly oscillating character, in which each thin rod can have its own frequency. The frequency range, where pseudo-vibrations can be present, is indicated using special characteristic

$$
\mathscr{T}:=\sup _{n \in \mathbb{N}} \limsup _{\varepsilon \rightarrow 0} \lambda_{n}(\varepsilon)
$$

called the threshold of low eigenvalues. The threshold of low eigenvalues is equal to $+\infty$ for majority spectral problems of the perturbation theory including problems with concentrated masses in the cases $\alpha<2$ and $\alpha=2$; if $\alpha>2$, then $\mathscr{T}=0$. For spectral problems in thick junctions, the threshold $\mathscr{T}$ can be equal to some positive number [104, 106, 107].

It is known that the asymptotic behavior of the spectrum of spectral boundaryvalue problems in perturbed domains essentially depends on boundary conditions [7, $57,76,124]$. Therefore, papers [81, 82, 84, 85] are devoted to the studying influence of different boundary conditions (Neumann, Robin, and Steklov) on the asymptotic behavior of eigenvalues of spectral problems in thick junctions of types 2:1:1, 3:2:1, and 3:2:2.

## Boundary-value problems

The first asymptotic results for the Neumann Laplacian in thick junctions in $\mathbb{R}^{N}$ of the type $N: N-1: 1$ were obtained in the thesis by R. Brizzi and J.P. Chalot in 1978. After 19 years, these results were published in [15]. There it was proved that if the boundaries of thin cylinders forming a thick junction of type 3:2:1 are rectilinear, then the solution extended by zero converges to the corresponding homogenized problem. This is explained by the fact that this extension preserves the weak derivative with respect to $x_{3}$ due to the rectilinearity of the boundaries of the cylinders along the $O x_{3}$ axis. This approach was used for homogeneous Neumann problems in [9, 10, 14, 24, 117] for monotone differential operators (in particular for the $p$-Laplacian) in thick junctions of the type $N: N-1: 1$ and $N-1: N-1: 1$, for the Ginzburg-Landau equation in a thick plane junction of type 2:2:1 [47], and for the wave equation [34].

Also in [15], the homogeneous Neumann problem was considered in a bounded plane domain whose boundary is waved by the function $x_{2}=h\left(x_{1} / \varepsilon\right)$, where $h$ must be a continuously differentiable periodic function and the reciprocal functions of $h$ on some intervals have to be existed to construct special extension operator. However, this extension does not preserve the space class of the solution (only in $H_{l o c}^{1}\left(\Omega_{1}^{+}\right)$, where $\Omega_{1}^{+} \subset \mathbb{R}^{2}$ is a domain that is filled up by the oscillating boundary in the limit) and it was constructed under the assumption that the right-hand side $f \in H^{1}\left(\Omega_{1}\right)$. Using this extension and a special transformation of a surface integral over the oscillating boundary, the nonhomogeneous Neumann problem

$$
-\Delta u_{\varepsilon}+u_{\varepsilon}=f \text { in } \Omega_{\varepsilon}, \quad \partial_{\nu_{\varepsilon}} u_{\varepsilon}=\varepsilon^{\lambda} \text { on } \partial \Omega_{\varepsilon},
$$

was studied in [43]. If $\lambda>1$, the same homogenized problem was obtained as in the corresponding homogeneous Neumann problem in [15]. If $\lambda=1$, an additional term appears in the right-hand side of the homogenized problem. And if $\lambda \in[0,1)$, the weak solution satisfies inequalities

$$
\exists c_{1}, c_{2} \in(0,+\infty) \forall \varepsilon: \frac{c_{1}}{\varepsilon^{1-\lambda}} \leq\left\|u_{\varepsilon}\right\|_{H^{1}\left(\Omega_{\varepsilon}\right)} \leq \frac{c_{2}}{\varepsilon^{1-\lambda}} .
$$

From these results, we again see that the asymptotic behavior of the solution essentially depends on the conditions given on the oscillating part of the boundary.

The scheme of the construction of the extension operator proposed in [15] is not applicable for thick junctions with thin rectilinear cylinders ("pillar type" domains) since the geometry of the oscillating boundary cannot be described by a function. In [79], a new scheme of the construction of extension operators $\left\{E: H^{1}\left(\Omega_{\varepsilon}\right) \mapsto\right.$ $\left.H^{1}(\Omega)\right\}_{\varepsilon>0}$ was developed for solutions of BVPs. The extension construction for the solution to the homogeneous Neumann problem for the Poisson equation in a thick junction of the type 3:2:1 needs weaker conditions for the right-hand side. In addition, this extension preserves the space class of the solution and the scheme is most general in conception and applicable for solutions of BVPs in thick junctions with more complex structure [29, 31, 32].

Moreover, with the help of the method of matching asymptotic expansions, the approximation for the solution is constructed and the corresponding asymptotic error estimate in the Sobolev space $H^{1}\left(\Omega_{\varepsilon}\right)$ is proved in [79]. Similar results were obtained in [83] for parabolic problems with the linear Robin condition $\partial_{\nu_{\varepsilon}} u_{\varepsilon}+\varepsilon u_{\varepsilon}=0$ given on the lateral surfaces of the thin cylinders, in [26] with the nonhomogeneous Robin condition

$$
\partial_{\nu_{\varepsilon}} u_{\varepsilon}+\varepsilon^{\alpha} u_{\varepsilon}=\varepsilon^{\beta} g_{\varepsilon}(x, t) \quad(\alpha, \beta \geq 1)
$$

given on the lateral boundaries of the thin rings of a thick junction of type 3:2:2, and in [90] for the Poisson equation with the nonlinear Robin boundary condition

$$
\partial_{\nu} u_{\varepsilon}+\varepsilon \kappa\left(u_{\varepsilon}\right)=0
$$

given on the lateral surfaces of the thin curvilinear cylinders of a thick junction of type $3: 2: 1$. In those papers, it was showed how Robin boundary conditions are transformed (as $\varepsilon \rightarrow 0$ ) in the corresponding terms of the homogenized problem. In addition, these researches and ones made for spectral problems show that the method of matching asymptotic expansions introduced by Il'in $[54,55]$ is a very effective tool in the study of BVPs in thick junctions.

Obviously, if the homogeneous Dirichlet condition given on the oscillating boundary of a thick junction and the $L^{p}$-norm of the right-hand side of a boundary-value problem is bounded with respect to the parameter $\varepsilon$, then the zero extension of the solution converges to zero in $L^{2}\left(\Omega^{+}\right)\left(\Omega^{+}\right.$is a domain that is filled up by the oscillating boundary in the limit). The asymptotic approximation for the solution to the homogeneous Dirichlet problem for the Poisson equation was constructed and the corresponding $H^{1}$-asymptotic estimate outside $\varepsilon$-layer of the joint zone of a plane thick junction of type $2: 1: 1$ was proved in [4]. It should be noted that the $H^{1}$-asymptotic estimates in the whole junction for the eigenfunctions of the Dirichlet Laplacian were derived in [80]. Using a boundary layer corrector, a first-order asymptotic approximation and $H^{1}$-asymptotic estimate (now in the whole junction) for the viscous incompressible flow governed by the stationary Stokes equations in a thick junction of type $3: 2: 1$ with the homogeneous Dirichlet conditions on the oscillating boundary were obtained in [5, 6].

The asymptotic behavior of the transverse displacement of a Kirchhoff-Love plate in the form of a thick junction of type 1:1:1 was investigated in [13]. The main difficulty in analyzing this problem is twofold and it is essentially due to the fourth order of the Kirchhoff-Love model. Deriving a priori estimates on the displacement for this operator and for the oscillating domain after rescaling is more intricate than for second-order problems. Second, as far as the homogenization process is concerned, the use of the method of oscillating test functions, introduced by Tartar in 1977 and partially written in [118], is also more complicated than for second-order problems since here we have to take into account also the oscillations of the second derivatives of the solution.

Using the two-scale convergence technique, the homogenized results are obtained for a two-dimensional electrostatic model in thick junctions of type 1:1:1 that simulate the rotor and the stator of this model [48].

In [11, 12], the new "unfolding technique" introduced in [21] is adapted to prove convergence theorems for solutions of the elasticity system in thick junctions of types 3:2:1 and 2:2:1, respectively, with the help of a decomposition of the displacement field in the thin rods. With the help of this approach the convergence results are deduced for the elliptic problems in thick junctions with different boundary conditions (homogeneous Neumann, nonhomogeneous Neumann, Robin) on the oscillating boundary (see [2, 72]).

The asymptotic behavior of second-order elliptic and parabolic Neumann problems in thick junctions $\Omega_{\varepsilon}$ of the type $N: N-1: 1$ under the following assumptions for the right-hand side:

$$
f_{\varepsilon} \in L^{2}(\Omega), \quad \exists c>0 \forall \varepsilon: \int_{\Omega_{\varepsilon}}\left(1+\left|f_{\varepsilon}\right|\right) \ln \left(1+\left|f_{\varepsilon}\right|\right) d x \leq c
$$

was studied in [44, 45]. If the the right-hand side $f_{\varepsilon} \in L^{1}(\Omega)$ and if no periodicity is assumed on the distribution of the cylindrical vertical teeth of a thick junction, the asymptotic behavior of the solution to an elliptic homogeneous Neumann problem was investigated in [46].

The homogenization of optimal control problems for elliptic, parabolic, and wave equations with homogeneous Neumann boundary conditions in thick junctions of the type $N: N-1: 1$ with different cost functionals was made in [28, 35, 61, 62]. With the help of the unfolding method, the homogenization of optimal control problems in thick junctions with the homogeneous Neumann conditions on the oscillating boundary were made in [119, 120, 126].

The Signorini conditions most closely correspond to the modeling of different processes in domains with the complex boundary structure since in fact it is impossible to control boundary conditions on a such boundary. The classical Signorini conditions contain two alternative linear boundary conditions (Dirichlet or Neumann) and it is unknown which of these conditions is satisfied for each point of the boundary. Homogenization of both elliptic and parabolic Signorini boundary-value problems in thick junctions of types $2: 1: 1$ and $3: 2: 1$ was made in [58, 101, 103], where it was showed that the Signorini conditions are transformed (as $\varepsilon \rightarrow 0$ ) in differential inequalities in the region that is filled up by the thin domains.

In [102], the following nonlinear boundary conditions of the Signorini type:

$$
\begin{equation*}
u_{\varepsilon} \leq g, \quad \partial_{\nu} u_{\varepsilon}+\varepsilon^{\alpha} h\left(u_{\varepsilon}\right) \leq 0, \quad\left(u_{\varepsilon}-g\right)\left(\partial_{\nu} u_{\varepsilon}+\varepsilon^{\alpha} h\left(u_{\varepsilon}\right)\right)=0 \tag{1.1}
\end{equation*}
$$

on the lateral surfaces of the thin cylinders of a thick junction were considered. Here the parameter $\alpha \in \mathbb{R}$, the function $h$ describing the nonlinearity belongs to $W_{l o c}^{1, \infty}(\mathbb{R})$ and there exist positive constants $c_{1}$ and $c_{2}$ such that $c_{1} \leq h^{\prime}(s) \leq c_{2}$ for a.e. $s \in \mathbb{R}$, and $h(0)=0$ (so-called the zero-absorption condition) if $\alpha<1$. We see that the passage to the limit is accompanied by special intensity factor $\varepsilon^{\alpha}$ in the boundary conditions. Two qualitatively different cases in the asymptotic behavior of the solution are established depending on the value of the parameter $\alpha$, namely $\alpha \geq 1$ and $\alpha<1$. For each case, the convergence theorem is proved.

In addition, the convergence of the energy integrals for elliptic Signorini problems were obtained in those two cases. It was pointed out in [134] that in fact there is only one natural definition of homogenization for functionals that are defined on reflexive spaces and grow faster than the norm-the definition via the convergence of energies. Therefore, the proof of the convergence of the energy integrals is a very important result that makes it possible to study optimal control problems in thick junctions by using the direct method of the calculus of variations.

A nonlinear monotone problem with nonlinear Signorini boundary conditions

$$
\left\{\begin{array}{l}
u_{\varepsilon}(x) \leq g(x), \quad \mathbf{A}\left(x, D u_{\varepsilon}(x)\right) \cdot v_{\varepsilon}(x)+\varepsilon^{\lambda} h\left(x, u_{\varepsilon}(x)\right) \leq 0, \\
\left(u_{\varepsilon}(x)-g(x)\right)\left(\mathbf{A}\left(x, D u_{\varepsilon}(x)\right) \cdot v_{\varepsilon}(x)+\varepsilon^{\lambda} h\left(x, u_{\varepsilon}\right)\right)=0
\end{array}\right.
$$

on the lateral surfaces of the thin rectilinear cylinders of a thick junction of the type $N: N-1: 1$ is considered in $[49,50]$. The main assumption for the monotone function $h$ with respect the second variable is as follows:
$\exists \eta>0, \eta_{1} \in W^{1, \frac{p}{p-1}}\left(\Omega^{+}\right):|h(x, s)| \leq \eta|s|^{p-1}+\eta_{1}(x)$, a.e. $x \in \Omega^{+}, \quad \forall s \in \mathbb{R}$.
If $\lambda \geq 1$ the corresponding homogenized problem is nonstandard since it is given by a variational inequality coupled to an algebraic system in the region filled up by the thin cylinders [49]. For $\lambda \in(0,1)$, the additional assumption

$$
\exists \delta>0: \delta|s|^{p} \leq h(x, t) s, \quad \text { a.e. } x \in \Omega^{+}, \quad \forall s \in \mathbb{R} .
$$

is needed to prove the convergence theorem [50]; the limit problem consists of a boundary-value problem in the junction's body and also an algebraic system in the region filled up by the thin cylinders. In the case $\lambda<0$, the convergence results are obtained under more strong assumption on the vector-function $\mathbf{A}$ (see [50]).

## Thick multilevel junctions

Successful applications of thick-junction constructions have stimulated active studying of BVPs in thick junctions with more complex structures. A thick multilevel junction is a thick junction in which the thin domains are divided into a finite number of levels depending on their geometric structure and boundary conditions imposed on their boundaries. Besides, the thin domains from each level $\varepsilon$-periodically alternate along the joint zone.

For the first time, a boundary-value problem in a plane thick multilevel junction of type 2:1:1 was considered in [87], where the asymptotic behavior of eigenvalues and eigenfunctions was analyzed (see also [89, 91]). In [33], with the help of the special multilevel extension operator the convergence theorem was proved for the solution to the Poisson equation in a plane two-level junction with homogeneous Robin boundary conditions at the boundaries of the thin rods. Using the method of matched asymptotic expansions, the first terms of the asymptotics were constructed for solutions both to elliptic and to parabolic BVPs with different varying types of boundary conditions in thick multilevel junctions of types 2:1:1 and 3:2:1 in [27, 36, $39,114,115]$, and in addition, the corresponding asymptotic estimates in the Sobolev space $H^{1}\left(\Omega_{\varepsilon}\right)$ (in $L^{2}\left(0, T ; H^{1}\left(\Omega_{\varepsilon}\right)\right)$ for parabolic problems) were proved there. Homogenization of a semilinear Signorini problem in a thick multilevel junction of type 3:2:1, was made in [102].

Using the Buttazzo-Dal Maso abstract scheme for variational convergence of constrained minimization problems, the asymptotic analysis of optimal control problems (linear and quasilinear) with inhomogeneous perturbed Robin boundary conditions in multilevel junctions of types $2: 1: 1$ and $3: 2: 1$ was made in [37, 38]. Qualitatively different cases in the asymptotic behavior of the solutions were discovered and an interesting application for an optimal control problem involving a thick one-level junction with cascade controls is presented in [38].

From the results obtained in these papers, it follows that physical processes in thick multilevel junctions behave as a "many-phase system" in the region which is filled up by the thin domains from each level in the limit.

## Thick cascade junctions

By contrast with the papers that studied BVPs in thick multilevel junctions with the thin offshoots of finite length, new effects emerge for BVPs in thick cascade junctions (it is a thick multilevel junction in which the thin domains of the first level have the fixed length of order $\mathscr{O}(1)$ and the thin domains of the second one vanish as $\varepsilon \rightarrow 0)$. For such problems new kind of inhomogeneous conjugation conditions appeared in the corresponding homogenized problem at the joint zone, which take into account the geometry of the thin domains of the vanishing level and boundary conditions given on their boundaries (see [95-97], where the homogenization theorems and the convergence of the energy integrals were proved for BVPs with different boundary conditions in thick cascade junctions of types 2:1:1 and 3:2:1). In [100], similar results were obtained in a plane thick cascade junction in which the thin rectangles from the second level have the length of order $\varepsilon^{\alpha},(0<\alpha<1)$, i.e., the length of a rectangle from the second level is small, but considerably larger than the alternation period $\varepsilon$.

BVPs in new kind of thick cascade junctions were studied in [16, 17]. Such junctions consist of a body and a large number of thin rectangles (cylinders) joining to the body through the thin random transmission zone with rapidly oscillating boundary. Assuming the inhomogeneous Robin boundary conditions with perturbed coefficients to be set on the boundaries of the thin cylinders and with random perturbed coefficients on the boundary of the transmission zone, the homogenization theorems and the convergence of the respective energy integrals were proved there. It is shown that there are three qualitatively different cases in the asymptotic behavior of the solutions and the energy integrals.

A rich collection of new results on asymptotic analysis of spectral problems in thick cascade junctions with concentrated masses on the thin rods of the second vanishing level (the density is order $\mathscr{O}\left(\varepsilon^{-\alpha}\right)(\alpha>0)$ on the thin rods from the second level and $\mathscr{O}(1)$ outside of them) are obtained in [18-20, 98, 99]. In contrast with [86], five qualitatively different cases in the asymptotic behavior of eigen-magnitudes (as $\varepsilon \rightarrow 0$ ) are discovered, namely the case of "light" concentrated masses ( $\alpha \in$ $(0,1)$ ), "middle" concentrated masses ( $\alpha=1$ ), and "heavy" concentrated masses $(\alpha \in(1,+\infty))$ that is divided into "slightly heavy" concentrated masses $(\alpha \in(1,2))$, "intermediate heavy" concentrated masses ( $\alpha=2$ ), and "very heavy" concentrated masses $(\alpha>2)$.

If $\alpha \in(0,1)$, then the spectrum of the homogenized problem coincides with the spectrum of the problem in the domain without concentrated masses (see, for instance, [81, 106] mentioned above). The concentrated masses bring the influence only from the second terms of the asymptotic expansions for the eigen-elements. Concentrated masses first manifest themselves in the homogenized spectral problem for $\alpha=1$. Namely, we observe an additional summand with a spectral parameter in the jump of derivatives at the joint zone. If $\alpha>1$, then the concentrated masses begin to play
a principal role in the asymptotic behavior of the eigenvalues and eigenfunctions. A fundamental difference between this case and the previous ones is that all eigenvalues decay at the rate of $\varepsilon^{\alpha-1}$. The corresponding eigen-vibrations have a new type of the skin effect (surface waves appearing in the solid) that was called spatial-skin effect. It means that the vibrations of the thin long rods of the first level repeat the shape of the vibrations of the joint zone. For $\alpha \geq 2$, the spatial-skin effect for the corresponding eigenfunctions is strengthened; in addition, the geometry of the junction's body and thin rectangles of the first level has a smaller influence on the asymptotic behavior of the eigenvalues. Therefore, the case of "heavy" concentrated masses is divided into three ones.

For all these cases, the Hausdorff, low- and high-frequency convergences of the spectrum to the spectrum of the corresponding homogenized problem as $\varepsilon \rightarrow 0$ were proved, the leading terms of the asymptotics both for the eigenfunctions and eigenvalues were constructed and justified.

## Thick junctions with the branched fractal structure

In [92, 93], the first author have begun to study asymptotic properties of solutions to semilinear parabolic initial-boundary-value problems in thick fractal junctions (or thick junctions with branched structure). A thick fractal junction is the union of the junction's body and a lot of thin trees situated $\varepsilon$-periodically along the joint zone. The trees have finite number of branching levels. In particular, the following nonlinear Robin boundary condition $\partial_{\nu} v_{\varepsilon}+\varepsilon^{\alpha_{i}} \mu\left(t, x_{2}, v_{\varepsilon}\right)=\varepsilon^{\beta} g_{\varepsilon}$ on the branch boundaries of the $i$ th branching layer was considered in [92]; $\left\{\alpha_{i}\right\}$ and $\beta$ are real parameters. The asymptotic analysis of such problems was made as $\varepsilon \rightarrow 0$, i.e., when the number of the thin trees infinitely increases and their thickness vanishes. Namely, for each such problem a corresponding homogenized problem was found and the existence and uniqueness of its solution in an anisotropic Sobolev space of multi-sheeted functions were proved. Also the asymptotic approximation for the solution was constructed and the corresponding asymptotic estimate in the space $C\left([0, T] ; L^{2}\left(\Omega_{\varepsilon}\right)\right) \cap L^{2}\left(0, T ; H^{1}\left(\Omega_{\varepsilon}\right)\right)$ was proved.

Using the unfolding operator method, convergence results for an optimal control problem involving a linear parabolic problem with the homogeneous Neumann condition in a thick junction with branched structure are obtained in [1]; and more general results for an optimal control problem involving a linear elliptic problem with the controls on the oscillating part are obtained in [3].

## Overview of the book

In spite of significant achievements in studying BVPs in thick junctions, problems in thick multilevel junctions of type 3:2:2 are not studied properly. Therefore, this book is devoted to the study of the asymptotic behavior of solutions to BVPs in such thick multilevel junctions. The results presented here have already been published in our articles [110-113, 127-129], but we give here a complete and unified presentation.

The Dirichlet, Neumann, and Robin (Fourier) boundary conditions are considered on the boundaries of the thin annular discs that strung on a fixed cylinder that is the junction's body of the thick multilevel junction $\Omega_{\varepsilon}$. Additionally Robin boundary
conditions depend on perturbation parameters. We study the influence of various combinations of such boundary conditions given on the surfaces of the thin discs from different levels, as well as the influence of the perturbation parameters on the asymptotic behavior of solutions of BVPs in $\Omega_{\varepsilon}$.

In Chap. 2, convergence theorems are proved for solutions to linear elliptic BVPs in $\Omega_{\varepsilon}$. Here we consider two BVPs, the first one is with various alternating perturbed Robin boundary conditions, and the second one is with alternating Neumann and Dirichlet boundary conditions on the surfaces of the thin discs. The convergence of the energy integrals for each problem is also proved. As noted above, this is a very useful result that gives possibility directly obtain results for optimal control problems involving thick multilevel junctions of type 3:2:2.

In Chap. 3, we consider the case when the thin domains of a thick junction can have sharp edges, i.e., their thickness tends to zero polynomially with the exponent $1+\gamma$ while approaching the edges (here $\gamma>-1$ is a parameter). Three qualitatively different cases in the asymptotic behavior of the solution are discovered depending on the edge form, namely rounded edges $\gamma \in(-1,0)$, linear wedges $\gamma=0$, and very sharp edges $\gamma>0$ (in this case the boundary is not Lipshitz). Nonstandard and new techniques are proposed to get the corresponding homogenized problems (untypical in the cases $\gamma=0$ and $\gamma>0$ ). The obtained results mathematically justify an interesting physical effect for heat radiators (see conclusions to this chapter).

It should be noted here that thick junctions are domains with Lipshitz boundary in all papers mentioned in this review (in some articles the oscillating boundaries must be smooth).

In Chap. 4, the method proposed in Chap. 2 is broadened for semilinear parabolic BVPs in $\Omega_{\varepsilon}$. Here we show how to apply the Minty-Browder method to homogenize nonlinear Robin conditions that have special intensity factor $\varepsilon^{\alpha}$, where the parameter $\alpha \in \mathbb{R}$ and its significant impacts on the asymptotic behavior of the solutions.

In Chap. 5, approximation techniques are demonstrated for semilinear elliptic and parabolic problems in $\Omega_{\varepsilon}$ with various alternating Robin boundary conditions. With the help of special junction-layer solutions, whose behavior is determined by type $3: 2: 2$, and the method of matched asymptotic expansions, approximation functions are constructed for the solutions and the corresponding asymptotic estimates in Sobolev spaces are proved. These estimates show the influence of the given data and parameters on the asymptotic behavior of the solutions.

It should be noted that the results obtained in each chapter are discussed, including their physical interpretations, in Conclusions to each chapter.

## Chapter 2 <br> Homogenization of Linear Elliptic Problems

### 2.1 Statement of Problems

Let $r_{0}, r_{1}, r_{2}, l_{1}, l_{2}$ be fixed positive numbers such that $r_{0}<r_{1} \leq r_{2}$ and $l_{1}<l_{2}<1$; and let $h_{i}:\left[r_{0}, r_{i}\right] \mapsto(0,1)$ be piecewise smooth functions satisfying the following conditions:

$$
\begin{gathered}
0<l_{i}-\frac{h_{i}(s)}{2}, \quad l_{i}+\frac{h_{i}(s)}{2}<1 \quad \forall s \in\left[r_{0}, r_{i}\right], i=1,2, \\
l_{1}+\frac{h_{1}(s)}{2}<l_{2}-\frac{h_{2}(s)}{2} \quad \forall s \in\left[r_{0}, r_{1}\right] .
\end{gathered}
$$

These inequalities imply that for all $s \in\left[r_{0}, r_{i}\right]$ the intervals

$$
I_{i}(s):=\left(l_{i}-\frac{h_{i}(s)}{2}, l_{i}+\frac{h_{i}(s)}{2}\right), \quad i=1,2
$$

are contained inside $(0,1)$ and $\overline{I_{1}(s)} \cap \overline{I_{2}(s)}=\emptyset$.
Let us introduce a cylindrical coordinate system $\left(r, x_{2}, \theta\right)$ in $\mathbb{R}^{3}$ :

$$
x=\left(r \cos \theta, x_{2}, r \sin \theta\right), \quad r=\sqrt{x_{1}^{2}+x_{3}^{2}}, \quad x_{2} \in \mathbb{R}, \quad \theta \in[0,2 \pi)
$$

Remark 2.1 Hereinafter passing to the cylindrical coordinate system, we will keep the same notations for functions, i.e., $\varphi(x)=\varphi\left(r, x_{2}, \theta\right)$ if $\left(r, x_{2}, \theta\right)$ are the corresponding cylindrical coordinates of the point $x=\left(x_{1}, x_{2}, x_{3}\right) \in \mathbb{R}^{3}$.

Let $N$ be a large positive integer and $l$ be a fixed positive number; then $\varepsilon=l / N$ is a small parameter. We denote by $I_{\varepsilon}^{(i)}(j, a)$ the interval


Fig. 2.1 A cross section of the thick junction $\Omega_{\varepsilon}$ of type 3:2:2 $(N=12)$

$$
\left(\varepsilon\left(j+l_{i}-\frac{a}{2}\right), \varepsilon\left(j+l_{i}+\frac{a}{2}\right)\right)
$$

of the length $\varepsilon a$, where $i \in\{1,2\}, a \in(0,1)$, and $j \in\{0,1, \ldots, N-1\}$. Obviously, for every $i \in\{1,2\}$ and $r \in\left[r_{0}, r_{i}\right]$ the intervals $\left\{I_{\varepsilon}^{(i)}\left(j, h_{i}(r)\right)\right\}_{j=\overline{0, N-1}}$ are $\varepsilon$-periodically situated inside $(0, l)$.

A thick multilevel junction $\Omega_{\varepsilon}$ (see Fig. 2.1) consists of a cylinder

$$
\Omega_{0}=\left\{x \in \mathbb{R}^{3}: 0<x_{2}<l, r<r_{0}\right\}
$$

and a large number of thin annular discs

$$
\Omega_{\varepsilon}^{(1)}=\bigcup_{j=0}^{N-1} \Omega_{\varepsilon}^{(1)}(j), \quad \Omega_{\varepsilon}^{(2)}=\bigcup_{j=0}^{N-1} \Omega_{\varepsilon}^{(2)}(j),
$$

i.e., $\Omega_{\varepsilon}=\Omega_{0} \cup \Omega_{\varepsilon}^{(1)} \cup \Omega_{\varepsilon}^{(2)}$. Here the $j$ th thin disc from the $i$ th level is defined as follows:

$$
\Omega_{\varepsilon}^{(i)}(j):=\left\{x \in \mathbb{R}^{3}: x_{2} \in I_{\varepsilon}^{(i)}\left(j, h_{i}(r)\right), \quad r_{0} \leq r<r_{i}\right\},
$$

where $i=1,2 ; j=\overline{0, N-1}$.
Remark 2.2 Here the junction's body is the 3-dimensional cylinder $\Omega_{0}$, the joint zone is its lateral surface, and each of the attached thin annular discs is shrunk into an annulus as $\varepsilon \rightarrow 0$. Thus, the type of the thick junction $\Omega_{\varepsilon}$ is 3:2:2.

The parameter $\varepsilon$ characterizes distance between neighboring thin discs, their quantity, and their thickness. The number of the discs equals $2 N$, they are divided into two levels $\Omega_{\varepsilon}^{(1)}$ and $\Omega_{\varepsilon}^{(2)}$, and the discs from each level $\varepsilon$-periodically alternate.

In what follows we will often use the following notations:

- $\partial \Omega_{\varepsilon}^{(i)}(j) \cap\left\{r_{0}<r<r_{i}\right\}$ is the union of two lateral surfaces of the disc $\Omega_{\varepsilon}^{(i)}(j)$;
- $\partial \Omega_{\varepsilon}^{(i)}(j) \cap\left\{r=r_{i}\right\}$ is the outer edge of $\Omega_{\varepsilon}^{(i)}(j)$;
- $\Omega_{\varepsilon}^{(i)}(j) \cap\left\{r=r_{0}\right\}$ is the inner edge of $\Omega_{\varepsilon}^{(i)}(j)$;
- $\partial \Omega_{\varepsilon}^{(i)}(j) \cap\left\{r>r_{0}\right\}$ is the part of the boundary of $\Omega_{\varepsilon}^{(i)}(j)$ except of the inner edge;
- $\partial \Omega_{\varepsilon} \cap\left\{r=r_{0}\right\}$ is the part of the lateral surface of the cylinder $\Omega_{0}$ situated between the inner edges of the thin discs;
- $\partial \Omega_{0} \cap\left\{r<r_{0}\right\}$ are the bases of the cylinder $\Omega_{0}$;
- $\Omega^{\prime}=\partial \Omega_{0} \cap\left\{r=r_{0}\right\}$ is the joint zone of the thick multilevel junction $\Omega_{\varepsilon}$.

We consider two linear elliptic BVPs in $\Omega_{\varepsilon}$. The first one is

$$
\begin{cases}-\Delta_{x} u_{\varepsilon}(x)=f_{\varepsilon}(x), & x \in \Omega_{\varepsilon},  \tag{2.1}\\ \partial_{\nu} u_{\varepsilon}(x)+\varepsilon^{\alpha} k_{1} u_{\varepsilon}(x)=\varepsilon^{\beta} g_{\varepsilon}(x), & x \in \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}, \\ \partial_{\nu} u_{\varepsilon}(x)+\varepsilon k_{2} u_{\varepsilon}(x)=\varepsilon^{\beta} g_{\varepsilon}(x), & x \in \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}, \\ \partial_{\nu} u_{\varepsilon}(x)+k_{2} u_{\varepsilon}(x)=0, & x \in \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}, \\ \partial_{\nu} u_{\varepsilon}(x)=0, & x \in \partial \Omega_{\varepsilon} \cap\left\{r=r_{0}\right\}, \\ \partial_{\nu} u_{\varepsilon}(x)=q_{\varepsilon}(x), & x \in \partial \Omega_{0} \cap\left\{r<r_{0}\right\},\end{cases}
$$

with alternating singularly perturbed Robin boundary conditions on the surfaces of the thin discs from both levels; the second one is

$$
\begin{cases}-\Delta_{x} v_{\varepsilon}(x)=f_{\varepsilon}(x), & x \in \Omega_{\varepsilon},  \tag{2.2}\\ \partial_{\nu} v_{\varepsilon}(x)=\varepsilon g_{\varepsilon}(x), & x \in \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}, \\ v_{\varepsilon}(x)=0, & x \in \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}, \\ \partial_{\nu} v_{\varepsilon}(x)=0, & x \in \partial \Omega_{\varepsilon} \cap\left\{r=r_{0}\right\}, \\ \partial_{\nu} v_{\varepsilon}(x)=q_{\varepsilon}(x), & x \in \partial \Omega_{0} \cap\left\{r<r_{0}\right\} .\end{cases}
$$

with alternating inhomogeneous Neumann and homogeneous Dirichlet boundary conditions Here $\partial_{v}=\partial / \partial v$ is the outward normal derivative; $k_{1} \geq 0, k_{2}>0$; and parameters $\alpha \geq 1, \beta \geq 1$.

Remark 2.3 (Comments to the statement) In a typical interpretation, solutions to BVPs represent the density of some quantity (chemical concentration, temperature, electronic potential) at equilibrium within a domain, where a boundary-value problem is considered. In many physical problems, the flow across the boundary surface is proportional to the difference between the surrounding density $g$ and the density $u$ just inside of the domain. As a result, we get the linear Robin boundary condition $\partial_{\nu} u+k_{0} u=g$ on the boundary (see [125] for more detail). Here, in the book, we
will interpret solutions as temperature inside $\Omega_{\varepsilon}$. Then $k_{0}$ is a positive heat transfer coefficient.

There are intensity factors in $\varepsilon^{\alpha}, \varepsilon$, and $\varepsilon^{\beta}$ in the boundary conditions of the problem (2.1). They usually appear after the nondimensionalization of mathematical models in thin domains (see e.g. [94]). As will be shown below, the asymptotic behavior of the solution depends essentially on the parameters $\alpha$ and $\beta$. Moreover, two cases are qualitatively different, namely when they are equal to 1 and when they greater than 1 . Therefore, for simplicity, we take $\alpha=1$ in the boundary condition on $\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}$ (it can also mean that discs from the second level have different physical properties). The case $\alpha<1$ is considered in Chap. 4. If $k_{1}=0$, then we have Neumann boundary conditions in (2.1).

Clearly, the outer edges of the thin discs from the second level are more exposed to outer environment than the other parts of the boundaries of the thin discs from both levels (see Fig. 2.1). Thus, it is natural to impose distinct boundary conditions on those parts. In (2.1), we impose Robin boundary conditions on the edges of $\Omega_{\varepsilon}^{(2)}$ with the heat transfer coefficient $k_{2}$.

Alternation of the thin discs from these two levels leads to rapid change of boundary conditions along the joint zone $\Omega^{\prime}$ in BVPs (2.1) and (2.2).

It is easy to see that the thin annular discs from the $i$ th level fill up the set

$$
\Omega^{(i)}=\left\{x \in \mathbb{R}^{3}: 0<x_{2}<l, r_{0} \leq r<r_{i}\right\} \text { as } \varepsilon \rightarrow 0(i=1,2)
$$

The aim of this chapter is to answer what will happen with BVPs (2.1) and (2.2) as $\varepsilon \rightarrow 0(N \rightarrow+\infty)$, i.e., when the number of the attached thin discs of each level infinitely increases and their thickness tends to zero. We should find the corresponding homogenized in each case, prove the convergence of solutions, and study the influence of the parameters $\alpha$ and $\beta$.

As for the given functions, we suppose that the following conditions take place:

- the functions $f_{\varepsilon}, f_{0} \in L^{2}\left(\Omega_{0} \cup \Omega^{(2)}\right)$, and

$$
\begin{equation*}
f_{\varepsilon} \longrightarrow f_{0} \text { strongly in } L^{2}\left(\Omega_{0} \cup \Omega^{(2)}\right) \text { as } \varepsilon \rightarrow 0 \tag{2.3}
\end{equation*}
$$

- the functions $g_{\varepsilon}, g_{0} \in H^{1}\left(\Omega^{(2)}\right)$, and

$$
\begin{equation*}
g_{\varepsilon} \xrightarrow{w} g_{0} \text { weakly in } H^{1}\left(\Omega^{(2)}\right) \text { as } \varepsilon \rightarrow 0 \tag{2.4}
\end{equation*}
$$

- the functions $q_{\varepsilon}, q_{0} \in L^{2}\left(\partial \Omega_{0} \cap\left\{r<r_{0}\right\}\right)$, and

$$
\begin{equation*}
q_{\varepsilon} \xrightarrow{w} q_{0} \text { weakly in } L^{2}\left(\partial \Omega_{0} \cap\left\{r<r_{0}\right\}\right) \text { as } \varepsilon \rightarrow 0 . \tag{2.5}
\end{equation*}
$$

Definition 2.1 A function $u_{\varepsilon} \in H^{1}\left(\Omega_{\varepsilon}\right)$ is called a weak solution to problem (2.1) if the integral identity

$$
\begin{equation*}
\left(u_{\varepsilon}, \varphi\right)_{1, \varepsilon}=\mathrm{L}_{1, \varepsilon}(\varphi) \tag{2.6}
\end{equation*}
$$

holds for all $\varphi \in H^{1}\left(\Omega_{\varepsilon}\right)$, where

$$
\begin{aligned}
&\left(u_{\varepsilon}, \varphi\right)_{1, \varepsilon}=\int_{\Omega_{\varepsilon}} \nabla_{x} u_{\varepsilon} \cdot \nabla_{x} \varphi d x+\varepsilon^{\alpha} k_{1} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}} u_{\varepsilon} \varphi d \sigma_{x} \\
&+\varepsilon k_{2} \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}} u_{\varepsilon} \varphi d \sigma_{x}+k_{2} \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}} u_{\varepsilon} \varphi d \sigma_{x}
\end{aligned}
$$

and

$$
\mathrm{L}_{1, \varepsilon}(\varphi)=\int_{\Omega_{\varepsilon}} f_{\varepsilon} \varphi d x+\varepsilon^{\beta} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\} \cup \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}} g_{\varepsilon} \varphi d \sigma_{x}+\int_{\partial \Omega_{0} \cap\left\{r<r_{0}\right\}} q_{\varepsilon} \varphi d \tilde{x} .
$$

Remark 2.4 Hereinafter $\tilde{x}=\left(x_{1}, x_{3}\right)$.
Consider a Sobolev space

$$
H^{1}\left(\Omega_{\varepsilon} ; \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}\right):=\left\{\varphi \in H^{1}\left(\Omega_{\varepsilon}\right):\left.\varphi\right|_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}}=0\right\} .
$$

Hereinafter $\left.\varphi\right|_{S}$ denotes either the trace of a function $\varphi$ on a surface $S \subset \mathbb{R}^{3}$ or the restriction of $\varphi$ on a domain $S \subset \mathbb{R}^{3}$.

Definition 2.2 A function $v_{\varepsilon} \in H^{1}\left(\Omega_{\varepsilon} ; \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}\right)$ is called a weak solution to problem (2.2) if it satisfies the identity

$$
\begin{equation*}
\left(v_{\varepsilon}, \varphi\right)_{2, \varepsilon}=\mathrm{L}_{2, \varepsilon}(\varphi) \tag{2.7}
\end{equation*}
$$

for all functions $\varphi \in H^{1}\left(\Omega_{\varepsilon} ; \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}\right)$, where

$$
\begin{gathered}
\left(v_{\varepsilon}, \varphi\right)_{2, \varepsilon}=\int_{\Omega_{\varepsilon}} \nabla_{x} v_{\varepsilon} \cdot \nabla_{x} \varphi d x \\
\mathrm{~L}_{2, \varepsilon}(\varphi)=\int_{\Omega_{\varepsilon}} f_{\varepsilon} \varphi d x+\varepsilon \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}} g_{\varepsilon} \varphi d \sigma_{x}+\int_{\partial \Omega_{0} \cap\left\{r<r_{0}\right\}} q_{\varepsilon} \varphi d \tilde{x} .
\end{gathered}
$$

### 2.2 Auxiliary Statements and a Priori Estimates

### 2.2.1 Auxiliary Statements

It is easy to check that for a.e. $x \in \partial \Omega_{\varepsilon}^{(i)} \cap\left\{r_{0}<r<r_{i}\right\}$ the outward unit normal to the lateral surface of the thin disc from the $i$ th level is

$$
\begin{equation*}
\nu(x)=\left(N_{\varepsilon}^{(i)}(r)\right)^{-1}\left(-\frac{\varepsilon \partial_{x_{1}} h_{i}(r)}{2}, \pm 1,-\frac{\varepsilon \partial_{x_{3}} h_{i}(r)}{2}\right), \quad i=1,2, \tag{2.8}
\end{equation*}
$$

where $N_{\varepsilon}^{(i)}(r)=\sqrt{1+4^{-1} \varepsilon^{2}\left|h_{i}^{\prime}(r)\right|^{2}}$, and " + " (or " - ") corresponds to the right (or left) part of the lateral surface of the thin disc $\Omega_{\varepsilon}^{(i)}(j)$. Further we will be using the following integral identity proved in [32]:

$$
\begin{equation*}
\frac{\varepsilon}{2} \int_{\partial \Omega_{\varepsilon}^{(i)} \cap\left\{r_{0}<r<r_{i}\right\}} \frac{h_{i}(r) \varphi}{N_{\varepsilon}^{(i)}(r)} d \sigma_{x}=\int_{\Omega_{\varepsilon}^{(i)}} \varphi d x-\varepsilon \int_{\Omega_{\varepsilon}^{(i)}} Y_{i}\left(\frac{x_{2}}{\varepsilon}\right) \partial_{x_{2}} \varphi d x \tag{2.9}
\end{equation*}
$$

for any $\varphi \in H^{1}\left(\Omega_{\varepsilon}^{(i)}\right)$; here $Y_{i}(s)=-s+[s]+l_{i}$ and $[s]$ is the integer part of $s \in \mathbb{R}$.
Identity (2.9) and the estimate $\max _{\mathbb{R}}\left|Y_{i}(s)\right| \leq 2$ provide the inequalities

$$
\begin{gather*}
\|\varphi\|_{L^{2}\left(\partial \Omega_{\varepsilon}^{(i)} \cap\left\{r_{0}<r<r_{i}\right\}\right)} \leq C_{0} \varepsilon^{-\frac{1}{2}}\|\varphi\|_{H^{1}\left(\Omega_{\varepsilon}^{(i)}\right)},  \tag{2.10}\\
\int_{\Omega_{\varepsilon}^{(i)}} \varphi^{2} d x \leq C_{1}\left(\varepsilon^{2} \int_{\Omega_{\varepsilon}^{(i)}}\left|\nabla_{x} \varphi\right|^{2} d x+\varepsilon \int_{\partial \Omega_{\varepsilon}^{(i)} \cap\left\{r_{0}<r<r_{i}\right\}} \varphi^{2} d \sigma_{x}\right) \tag{2.11}
\end{gather*}
$$

for all $\varphi \in H^{1}\left(\Omega_{\varepsilon}^{(i)}\right), \quad i=1$, 2. Obviously, inequality (2.11) for functions $\varphi \in$ $H^{1}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}\right)$ looks like

$$
\begin{equation*}
\int_{\Omega_{\varepsilon}^{(2)}} \varphi^{2} d x \leq C_{1} \varepsilon^{2} \int_{\Omega_{\varepsilon}^{(2)}}\left|\nabla_{x} \varphi\right|^{2} d x \tag{2.12}
\end{equation*}
$$

Remark 2.5 Hereafter all constants $c_{i}, C_{i}$ in inequalities are positive and independent of $\varepsilon$.

Lemma 2.1 For any function $\varphi \in H^{1}\left(\Omega_{\varepsilon}^{(i)}\right)$, the following inequalities take place:

$$
\begin{gather*}
\|\varphi\|_{L^{2}\left(\partial \Omega_{\varepsilon}^{(i)} \cap\left\{r=r_{i}\right\}\right)} \leq C_{2}\|\varphi\|_{H^{1}\left(\Omega_{\varepsilon}^{(i)}\right)},  \tag{2.13}\\
\|\varphi\|_{L^{2}\left(\Omega_{\varepsilon}^{(i)} \cap\left\{r=r_{0}\right\}\right)} \leq C_{3}\|\varphi\|_{H^{1}\left(\Omega_{\varepsilon}^{(i)}\right)},  \tag{2.14}\\
\|\varphi\|_{L^{2}\left(\Omega_{\varepsilon}^{(i)}\right)} \leq C_{4}\left(\left\|\mid \nabla_{x} \varphi\right\|_{L^{2}\left(\Omega_{\varepsilon}^{(i)}\right)}+\|\varphi\|_{L^{2}\left(\Omega_{\varepsilon}^{(i)} \cap\left\{r=r_{0}\right\}\right)}\right), \quad i=1,2 . \tag{2.15}
\end{gather*}
$$

Proof We prove (2.13) by using the technique of [96, Lemma 2.1]. Fix $\delta>0$ such that the interval $\left(\check{x}_{\varepsilon}, \hat{x}_{\varepsilon}\right)$ is contained inside $\Omega_{\varepsilon}^{(1)}(j)$ (see Fig. 2.2), where $\hat{x}_{\varepsilon}=\left(r_{1}, \varepsilon(j+\right.$ $\left.\left.l_{1}-\frac{h_{1}\left(r_{1}\right)}{2}\right), \theta\right), \check{x}_{\varepsilon}=\left(r_{1}-\delta, \varepsilon\left(j+l_{1}-\frac{h_{1}\left(r_{1}\right)}{4}\right), \theta\right)$. Obviously, $\delta$ depends only on the function $h_{1}(r)$; here $j \in\{0, \ldots, N-1\}$, and $\theta \in[0,2 \pi)$.

For any function $\varphi \in C^{\infty}\left(\overline{\Omega_{\varepsilon}^{(1)}}\right), r \in\left(r_{1}-\delta, r_{1}\right)$, and $x_{2} \in I_{\varepsilon}^{(1)}\left(j, h_{1}(r)\right)$, we have

$$
\varphi\left(r_{1}, x_{2}, \theta\right)=\int_{\left(r,\left(x_{2}+\varepsilon\left(j+l_{1}\right)\right) / 2, \theta\right)}^{\left(r_{1}, x_{2}, \theta\right)} \partial_{s} \varphi d s+\varphi\left(r,\left(x_{2}+\varepsilon\left(j+l_{1}\right)\right) / 2, \theta\right)
$$

where $s$ is a natural parameter of the interval $\left(\left(r,\left(x_{2}+\varepsilon\left(j+l_{1}\right)\right) / 2, \theta\right),\left(r_{1}\right.\right.$, $\left.\left.x_{2}, \theta\right)\right)$. Squaring this equality and using the Cauchy-Schwartz inequality, we get

Fig. 2.2 A cross section of the thin $\operatorname{disc} \Omega_{\varepsilon}^{(1)}(j)$

$x_{2}$

$$
\varphi^{2}\left(r_{1}, x_{2}, \theta\right) \leq c_{0} \int_{\left(r,\left(x_{2}+\varepsilon\left(j+l_{1}\right)\right) / 2, \theta\right)}^{\left(r_{1}, x_{2}, \theta\right)}\left|\nabla_{x} \varphi\right|^{2} d s+2 \varphi^{2}\left(r,\left(x_{2}+\varepsilon\left(j+l_{1}\right)\right) / 2, \theta\right)
$$

Now integrating this inequality in $r \in\left(r_{1}-\delta, r_{1}\right), x_{2} \in I_{\varepsilon}^{(1)}\left(j, h_{1}(r)\right)$, and $\theta \in$ $[0,2 \pi)$, then summing over $j \in\{0, \ldots, N-1\}$, we arrive (2.13). By the closure, it remains valid for all $\varphi \in H^{1}\left(\Omega_{\varepsilon}^{(1)}\right)$.

Similarly, we prove (2.13) for the thin discs of the second level and the other estimates (2.14) and (2.15). The Lemma is proved.

If $\mathscr{S}$ is a Lebesgue-measurable subset of $\mathbb{R}^{3}$ (resp. $\mathbb{R}^{2}$ ), the characteristic function of $\mathscr{S}$ in $\mathbb{R}^{3}$ (resp. $\mathbb{R}^{2}$ ) will be denoted by $\chi_{\mathscr{S}}$. It is known (see e.g. [31]) that

$$
\left.\begin{array}{ll}
\chi_{\Omega_{\varepsilon}^{(i)}}(x) & \rightharpoonup h_{i}(r) \text { weakly in } L^{2}\left(\Omega^{(i)}\right),  \tag{2.16}\\
\chi_{\Omega_{\varepsilon}^{(i)} \cap\left\{r=r_{0}\right\}}(x) \rightharpoonup h_{i}\left(r_{0}\right) \text { weakly in } L^{2}\left(\Omega^{\prime}\right),
\end{array}\right\} \quad \text { as } \varepsilon \rightarrow 0 \quad(i=1,2) .
$$

With the help of identity (2.9), the first convergence in (2.16), and the fact that

$$
\begin{equation*}
N_{\varepsilon}^{(i)}(r)=1+\mathscr{O}(\varepsilon), \quad \varepsilon \rightarrow 0, \quad i=1,2, \tag{2.17}
\end{equation*}
$$

it is easy to prove the following lemma.
Lemma 2.2 Assume (2.4). Then

$$
\varepsilon \int_{\partial \Omega_{\varepsilon}^{(i)} \cap\left\{r_{0}<r<r_{i}\right\}} g_{\varepsilon} \varphi d \sigma_{x} \longrightarrow 2 \int_{\Omega^{(i)}} g_{0} \varphi d x \quad \text { as } \varepsilon \rightarrow 0 \quad \forall \varphi \in H^{1}\left(\Omega^{(i)}\right)(i=1,2) .
$$

### 2.2.2 A Priori Estimates

Obviously, the bilinear forms $(\cdot, \cdot)_{1, \varepsilon}$ and $(\cdot, \cdot)_{2, \varepsilon}$ introduced in Definitions 2.1 and 2.2 define scalar products in the corresponding spaces.

Let $\|\cdot\|_{1, \varepsilon}$ be a new norm in the Sobolev space $H^{1}\left(\Omega_{\varepsilon}\right)$ produced by $(\cdot, \cdot)_{1, \varepsilon}$. Similarly to [27, Lemma 2.1], we can prove that the norms $\|\cdot\|_{1, \varepsilon}$ and $\|\cdot\|_{H^{1}\left(\Omega_{\varepsilon}\right)}$ are uniformly equivalent with respect to $\varepsilon$ in $H^{1}\left(\Omega_{\varepsilon}\right)$, i.e., there exist positive constants $\varepsilon_{0}, C_{5}$, and $C_{6}$ such that

$$
\begin{equation*}
C_{5}\|\varphi\|_{1, \varepsilon} \leq\|\varphi\|_{H^{1}\left(\Omega_{\varepsilon}\right)} \leq C_{6}\|\varphi\|_{1, \varepsilon}, \quad \forall \varepsilon \in\left(0, \varepsilon_{0}\right), \forall \varphi \in H^{1}\left(\Omega_{\varepsilon}\right) . \tag{2.18}
\end{equation*}
$$

With the help of (2.12), it is easy to check (see e.g. [79, Lemma 1]) that there exist constants $\varepsilon_{0}$ and $C_{7}$ such that for all $\varepsilon \in\left(0, \varepsilon_{0}\right)$ and $\varphi \in H^{1}\left(\Omega_{\varepsilon} ; \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}\right)$

$$
\begin{equation*}
\|\varphi\|_{2, \varepsilon} \leq\|\varphi\|_{H^{1}\left(\Omega_{\varepsilon}\right)} \leq C_{7}\|\varphi\|_{2, \varepsilon}, \tag{2.19}
\end{equation*}
$$

where the norm $\|\cdot\|_{2, \varepsilon}$ is produced by $(\cdot, \cdot)_{2, \varepsilon}$.
Clearly that the functional $\mathrm{L}_{1, \varepsilon}: H^{1}\left(\Omega_{\varepsilon}\right) \mapsto \mathbb{R}$ is linear. Exploiting the CauchySchwartz inequality, inequalities (2.10) and (2.13), we derive

$$
\left|\mathrm{L}_{1, \varepsilon}(\varphi)\right| \leq C_{8}\left(\left\|f_{\varepsilon}\right\|_{L^{2}\left(\Omega_{\varepsilon}\right)}+\left\|q_{\varepsilon}\right\|_{L^{2}\left(\partial \Omega_{0} \cap\left\{r<r_{0}\right\}\right)}+\varepsilon^{\beta-1}\left\|g_{\varepsilon}\right\|_{H^{1}\left(\Omega^{(2)}\right)}\right)\|\varphi\|_{H^{1}\left(\Omega_{\varepsilon}\right)},
$$

whence on the grounds of (2.18) it follows that

$$
\left|\mathrm{L}_{1, \varepsilon}(\varphi)\right| \leq C_{9}\left(\left\|f_{\varepsilon}\right\|_{L^{2}\left(\Omega_{\varepsilon}\right)}+\left\|q_{\varepsilon}\right\|_{L^{2}\left(\partial \Omega_{0} \cap\left\{r<r_{0}\right\}\right)}+\varepsilon^{\beta-1}\left\|g_{\varepsilon}\right\|_{H^{1}\left(\Omega^{(2)}\right)}\right)\|\varphi\|_{1, \varepsilon} .
$$

Using the Riesz representation theorem, we can prove that the problem (2.1) has a unique weak solution satisfying the estimate

$$
\begin{equation*}
\left\|u_{\varepsilon}\right\|_{H^{1}\left(\Omega_{\varepsilon}\right)} \leq C_{10}\left(\left\|f_{\varepsilon}\right\|_{L^{2}\left(\Omega_{\varepsilon}\right)}+\left\|q_{\varepsilon}\right\|_{L^{2}\left(\partial \Omega_{0} \cap\left\{r<r_{0}\right\}\right)}+\varepsilon^{\beta-1}\left\|g_{\varepsilon}\right\|_{H^{1}\left(\Omega^{(2)}\right)}\right) . \tag{2.20}
\end{equation*}
$$

Similarly with the help of (2.19), we show that there exists a unique weak solution to the problem (2.2), which satisfies the estimate

$$
\begin{equation*}
\left\|v_{\varepsilon}\right\|_{H^{1}\left(\Omega_{\varepsilon}\right)} \leq C_{11}\left(\left\|f_{\varepsilon}\right\|_{L^{2}\left(\Omega_{\varepsilon}\right)}+\left\|q_{\varepsilon}\right\|_{L^{2}\left(\partial \Omega_{0} \cap\left\{r<r_{0}\right\}\right)}+\left\|g_{\varepsilon}\right\|_{H^{1}\left(\Omega^{(1)}\right)}\right) . \tag{2.21}
\end{equation*}
$$

### 2.3 Convergence Theorems

### 2.3.1 Convergence Theorem for Problem (2.1)

For every $\varepsilon$ and for every function $\varphi \in L^{2}\left(\Omega_{\varepsilon}^{(i)}\right)$, we set

$$
\widetilde{\varphi}^{(i)}(x)=\left\{\begin{array}{ll}
\varphi(x), & x \in \Omega_{\varepsilon}^{(i)}, \\
0, & x \in \Omega^{(i)} \backslash \Omega_{\varepsilon}^{(i)}
\end{array} \quad(i=1,2) .\right.
$$

Obviously, if $\varphi \in H^{1}\left(\Omega_{\varepsilon} ; \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}\right)$, then $\widetilde{\varphi}^{(2)} \in H^{1}\left(\Omega^{(2)}\right)$.
Let us introduce a space of Sobolev space $\widetilde{\mathbf{H}}$ of anisotropic multi-sheeted functions. A multi-sheeted function

$$
\mathbf{p}(x):=\left(p_{0}, p_{1}, p_{2}\right)= \begin{cases}p_{0}(x), & x \in \Omega_{0}, \\ p_{1}(x), & x \in \Omega^{(1)}, \\ p_{2}(x), & x \in \Omega^{(2)},\end{cases}
$$

belongs to $\widetilde{\mathbf{H}}$ if $p_{0} \in H^{1}\left(\underset{\sim}{\Omega_{0}}\right), p_{i} \in \widetilde{H}^{1}\left(\Omega^{(i)}\right), i=1,2$, and $\left.p_{0}\right|_{\Omega^{\prime}}=\left.p_{1}\right|_{\Omega^{\prime}}=\left.p_{2}\right|_{\Omega^{\prime}}$.
Obviously, the space $\widetilde{\mathbf{H}}$ continuously and densely embedded in the Hilbert space $\mathbf{L}$ of multi-sheeted functions whose components belong to the corresponding $L^{2}$ spaces, i.e., $\mathbf{p} \in \mathbf{L}$ if $p_{0} \in L^{2}\left(\Omega_{0}\right), p_{i} \in L^{2}\left(\Omega^{(i)}\right), i=1$, 2. The scalar product in $\mathbf{L}$ defined as follows:

$$
(\mathbf{p}, \mathbf{q})_{\mathbf{L}}=\int_{\Omega_{0}} p_{0} q_{0} d x+\sum_{i=1}^{2} \int_{\Omega^{(i)}} h_{i}(r) p_{i} q_{i} d x
$$

and in $\widetilde{\mathbf{H}}$ by the formula

$$
\begin{aligned}
(\mathbf{p}, \mathbf{q}) \widetilde{\mathbf{H}} & =\int_{\Omega_{0}} \nabla_{x} p_{0} \cdot \nabla_{x} q_{0} d x+\sum_{i=1}^{2} \int_{\Omega^{(i)}} h_{i}(r) \nabla_{\tilde{x}} p_{i} \cdot \nabla_{\tilde{x}} q_{i} d x \\
& +2 \delta_{\alpha, 1} k_{1} \int_{\Omega^{(1)}} p_{1} q_{1} d x+2 k_{2} \int_{\Omega^{(2)}} p_{2} q_{2} d x+k_{2} h_{2}\left(r_{2}\right) \int_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}} p_{2} q_{2} d \sigma_{x},
\end{aligned}
$$

where $\mathbf{p}=\left(p_{0}, p_{1}, p_{2}\right), \mathbf{q}=\left(q_{0}, q_{1}, q_{2}\right), \delta_{i, j}$ is the Kronecker symbol.
Theorem 2.1 Assume (2.3)-(2.5). Then for the weak solution $u_{\varepsilon}$ to problem (2.1) the following limit relations hold:

$$
\left.\begin{array}{r}
u_{\varepsilon} \rightharpoonup u_{0} \quad \text { weakly in } H^{1}\left(\Omega_{0}\right),  \tag{2.22}\\
\widetilde{u}_{\varepsilon}^{(1)} \rightharpoonup h_{1} u_{1} \text { weakly in } L^{2}\left(\Omega^{(1)}\right), \\
\widetilde{u}_{\varepsilon}^{(2)} \rightharpoonup h_{2} u_{2} \text { weakly in } L^{2}\left(\Omega^{(2)}\right)
\end{array}\right\} \quad \text { as } \varepsilon \rightarrow 0,
$$

where the function $\mathbf{u}=\left(u_{0}, u_{1}, u_{2}\right) \in \widetilde{\mathbf{H}}$ is a weak solution to the problem

$$
\begin{cases}-\Delta_{x} u_{0}(x)=f_{0}(x), & x \in \Omega_{0},  \tag{2.23}\\ \partial_{\nu} u_{0}(x)=q_{0}(x), & x \in \partial \Omega_{0} \cap\left\{r<r_{0}\right\}, \\ -\operatorname{div}_{\tilde{x}}\left(h_{1}(r) \nabla_{\tilde{x}} u_{1}(x)\right)+2 k_{1} \delta_{\alpha, 1} u_{1}(x) & \\ \multicolumn{1}{c}{=h_{1}(r) f_{0}(x)+2 \delta_{\beta, 1} g_{0}(x),} & x \in \Omega^{(1)}, \\ \partial_{\nu} u_{1}(x)=0, & x \in \partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}, \\ -\operatorname{div}_{\tilde{x}}\left(h_{2}(r) \nabla_{\tilde{x}} u_{2}(x)\right)+2 k_{2} u_{2}(x) & \\ \quad=h_{2}(r) f_{0}(x)+2 \delta_{\beta, 1} g_{0}(x), & x \in \Omega^{(2)}, \\ \partial_{\nu} u_{2}(x)+k_{2} u_{2}(x)=0, & x \in \partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}, \\ u_{0}(x)=u_{1}(x)=u_{2}(x), & x \in \Omega^{\prime}, \\ \partial_{r} u_{0}(x)=\sum_{i=1}^{2} h_{i}\left(r_{0}\right) \partial_{r} u_{i}(x), & x \in \Omega^{\prime} .\end{cases}
$$

Besides, the following energy convergence takes place:

$$
\begin{equation*}
E_{1, \varepsilon}\left(u_{\varepsilon}\right):=\left(u_{\varepsilon}, u_{\varepsilon}\right)_{1, \varepsilon} \longrightarrow(\mathbf{u}, \mathbf{u})_{\widetilde{\mathbf{H}}}=: E_{1}(\mathbf{u}) \quad \varepsilon \rightarrow 0 \tag{2.24}
\end{equation*}
$$

Problem (2.23) is called a homogenized problem for problem (2.1).
Definition 2.3 A multi-sheeted function $\mathbf{u} \in \widetilde{\mathbf{H}}$ is called a weak solution to problem (2.23) if

$$
\begin{equation*}
(\mathbf{u}, \mathbf{p})_{\tilde{\mathbf{H}}}=\mathrm{L}_{1}(\mathbf{p}) \quad \forall \mathbf{p} \in \widetilde{\mathbf{H}} \tag{2.25}
\end{equation*}
$$

where

$$
\mathrm{L}_{1}(\mathbf{p})=\int_{\Omega_{0}} f_{0} p_{0} d x+\int_{\partial \Omega_{0} \cap\left\{r<r_{0}\right\}} q_{0} p_{0} d \tilde{x}+\sum_{i=1}^{2} \int_{\Omega^{(i)}}\left(h_{i}(r) f_{0}+2 \delta_{\beta, 1} g_{0}\right) p_{i} d x .
$$

It is easy to verify that $L_{1}$ is a continuous functional in $\widetilde{\mathbf{H}}$. Then the Riesz theorem supplies the existence and uniqueness of a weak solution to problem (2.23).

Proof 1. Relations (2.20), (2.13), (2.3), (2.4), and (2.5) imply the uniform (with respect to $\varepsilon$ ) boundedness of the following quantities: $\left\|u_{\varepsilon}\right\|_{H^{1}\left(\Omega_{0}\right)},\left\|\widetilde{u}_{\varepsilon}^{(i)}\right\|_{L^{2}\left(\Omega^{(i)}\right)}$,

$\left.\widetilde{\varphi}(x)\right|_{\partial \Omega_{\varepsilon}^{(i)} \cap\left\{r=r_{i}\right\}}:= \begin{cases}\left.\varphi(x)\right|_{\partial \Omega_{\varepsilon}^{(i)} \cap\left\{r=r_{i}\right\}}, & x \in \partial \Omega_{\varepsilon}^{(i)} \cap\left\{r=r_{i}\right\}, \\ 0, & x \in\left(\partial \Omega^{(i)} \cap\left\{r=r_{i}\right\}\right) \backslash\left(\partial \Omega_{\varepsilon}^{(i)} \cap\left\{r=r_{i}\right\}\right)\end{cases}$
$\varphi \in H^{1}\left(\Omega_{\varepsilon}^{(i)}\right), i=1,2$., Therefore, there exists a subsequence $\left\{\varepsilon^{\prime}\right\} \subset\{\varepsilon\}$ (again denoted by $\varepsilon$ ) such that

$$
\begin{array}{cll}
u_{\varepsilon} & \rightharpoonup u_{0} & \text { weakly in } H^{1}\left(\Omega_{0}\right), \\
\widetilde{u}_{\varepsilon}^{(i)} & \rightharpoonup \widetilde{u}_{i}:=h_{i} u_{i} & \\
\text { weakly in } L^{2}\left(\Omega^{(i)}\right),  \tag{2.26}\\
\widetilde{\partial_{x_{k}} u_{\varepsilon}}{ }^{(i)} \rightharpoonup \widetilde{u}_{i, k}:=h_{i} u_{i, k} & & \text { weakly in } L^{2}\left(\Omega^{(i)}\right), \\
\left.\widetilde{u}_{\varepsilon}\right|_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}} & \rightharpoonup \widetilde{u}_{r_{2}}:=h_{2}\left(r_{2}\right) u_{r_{2}} & \text { weakly in } L^{2}\left(\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}\right)
\end{array}
$$

as $\varepsilon \rightarrow 0$, the functions $u_{0}, u_{i}, u_{i, k}, u_{r_{2}}$ will be defined later; $i=1,2 ; k=1,2,3$.
2. At first we find $u_{i, 2}$. Consider the following test functions:

$$
\begin{aligned}
& \Phi_{1}(x)= \begin{cases}0, & x \in \Omega_{0} \cup \Omega_{\varepsilon}^{(2)}, \\
\varepsilon Y_{1}\left(\frac{x_{2}}{\varepsilon}\right) \varphi_{1}(x), & x \in \Omega_{\varepsilon}^{(1)},\end{cases} \\
& \Phi_{2}(x)= \begin{cases}0, & x \in \Omega_{0} \cup \Omega_{\varepsilon}^{(1)}, \\
\varepsilon Y_{2}\left(\frac{x_{2}}{\varepsilon}\right) \varphi_{2}(x), & x \in \Omega_{\varepsilon}^{(2)},\end{cases}
\end{aligned}
$$

where $\varphi_{i} \in C_{0}^{\infty}\left(\Omega^{(i)}\right), i=1,2$, are arbitrary functions and the function $Y_{2}$ is defined in (2.9). Obviously, $\Phi_{i} \in H^{1}\left(\Omega_{\varepsilon}\right)$ and

$$
\nabla_{x} \Phi_{i}(x)=\left(0,-\varphi_{i}(x), 0\right)+\varepsilon Y_{i}\left(\frac{x_{2}}{\varepsilon}\right) \nabla_{x} \varphi_{i}(x), \quad x \in \Omega_{\varepsilon}^{(i)}, i=1,2 .
$$

Substituting the function $\Phi_{1}$ into identity (2.6), we get

$$
\begin{aligned}
&\left|\int_{\Omega_{\varepsilon}^{(1)}} \partial_{x_{2}} u_{\varepsilon} \varphi_{1} d x\right| \leq \varepsilon\left(\int_{\Omega_{\varepsilon}^{(1)}}\left|\nabla_{x} u_{\varepsilon} \cdot \nabla_{x} \varphi_{1}\right| d x+\varepsilon^{\alpha} k_{1} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}}\left|u_{\varepsilon} \varphi_{1}\right| d \sigma_{x}\right. \\
&\left.+\int_{\Omega_{\varepsilon}^{(1)}}\left|f_{\varepsilon} \varphi_{1}\right| d x+\varepsilon^{\beta} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}}\left|g_{\varepsilon} \varphi_{1}\right| d \sigma_{x}\right) .
\end{aligned}
$$

Passing to the limit in this inequality and taking into account (2.26), (2.20), (2.10), (2.13), (2.3), (2.4), and that $\alpha, \beta \geq 1$, we obtain

$$
\int_{\Omega^{(1)}} h_{1}(r) u_{1,2} \varphi_{1} d x=0 \quad \forall \varphi_{1} \in C_{0}^{\infty}\left(\Omega^{(1)}\right),
$$

whence $u_{1,2}=0$ a.e. in $\Omega^{(1)}$. Similarly, using $\Phi_{2}$, we get that $u_{2,2}=0$ a.e. in $\Omega^{(2)}$.
Now integrating by parts and taking into account (2.8), we derive the identity

$$
\int_{\Omega_{\varepsilon}^{(1)}} \partial_{x_{k}} u_{\varepsilon} \psi d x=-\int_{\Omega_{\varepsilon}^{(1)}} u_{\varepsilon} \partial_{x_{k}} \psi d x-\frac{\varepsilon}{2} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r_{0}<r<r_{1}\right\}}\left(N_{\varepsilon}^{(1)}(r)\right)^{-1} \partial_{x_{k}} h_{1} u_{\varepsilon} \psi d \sigma_{x},
$$

where $k=1,3$ and $\psi \in C_{0}^{\infty}\left(\Omega^{(1)}\right)$. Using (2.9) and the zero extension operators, we rewrite this identity as follows:

$$
\begin{align*}
& \int_{\Omega^{(1)}}{\widetilde{\partial_{x_{k}}} u_{\varepsilon}^{(1)} \psi d x=}^{(1)} \int_{\Omega^{(1)}} \widetilde{u}_{\varepsilon}^{(1)}\left(\partial_{x_{k}} \psi+\partial_{x_{k}} \ln h_{1}(r) \psi\right) d x \\
&+\varepsilon \int_{\Omega_{\varepsilon}^{(1)}} Y_{1}\left(\frac{x_{2}}{\varepsilon}\right) \partial_{x_{k}} \ln h_{1}(r) \partial_{x_{2}}\left(u_{\varepsilon} \psi\right) d x, \quad k=1,3 \tag{2.27}
\end{align*}
$$

Evidently the last integral in (2.27) vanishes as $\varepsilon \rightarrow 0$. The limits of the rest ones can be found with the help of (2.26). As a result, we have

$$
\int_{\Omega^{(1)}} u_{1, k} h_{1}(r) \psi d x=-\int_{\Omega^{(1)}} u_{1} \partial_{x_{k}}\left(h_{1}(r) \psi\right) d x \quad \forall \psi \in C_{0}^{\infty}\left(\Omega^{(1)}\right),
$$

whence it follows the existence of the weak derivatives $\partial_{x_{k}} u_{1}$ and $u_{1, k}=\partial_{x_{k}} u_{1}$ a.e. $\Omega^{(1)}, k=1,3$. Similarly we can show that $\partial_{x_{k}} u_{2}=u_{2, k}$ a.e. in $\Omega^{(2)}, k=1,3$.

Let us find $u_{r_{2}}$. Direct calculations give that

$$
\begin{equation*}
\partial_{x_{1}}\left(r^{-1} \cos \theta\right)+\partial_{x_{3}}\left(r^{-1} \sin \theta\right)=0 . \tag{2.28}
\end{equation*}
$$

Consider an arbitrary function $\psi \in C^{\infty}\left(\overline{\Omega^{(2)}}\right)$ such that $\left.\psi\right|_{\Omega^{\prime}}=0$. Integrating by parts in $\Omega_{\varepsilon}^{(2)}$ and bearing in mind (2.8) and (2.28), we derive the identity

$$
\begin{aligned}
& \int_{\Omega_{\varepsilon}^{(2)}} r^{-1} \partial_{r} u_{\varepsilon} \psi d x=\int_{\Omega_{\varepsilon}^{(2)}} r^{-1}\left(\partial_{x_{1}} u_{\varepsilon} \cos \theta+\partial_{x_{3}} u_{\varepsilon} \sin \theta\right) \psi d x \\
&=-\int_{\Omega_{\varepsilon}^{(2)}} r^{-1} u_{\varepsilon} \partial_{r} \psi d x+r_{2}^{-1} \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}} u_{\varepsilon} \psi d \sigma_{x} \\
&-\frac{\varepsilon}{2} \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}}\left(N_{\varepsilon}^{(2)}(r)\right)^{-1} r^{-1} h_{2}^{\prime}(r) u_{\varepsilon} \psi d \sigma_{x} .
\end{aligned}
$$

With the help of (2.9) and the zero extensions, we rewrite it as

$$
\begin{align*}
r_{2}^{-1} \int_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}} & \left.\widetilde{u}_{\varepsilon}\right|_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}} \psi d \sigma_{x} \\
= & \int_{\Omega^{(2)}} r^{-1}\left(\widetilde{\partial_{r}} u_{\varepsilon}^{(1)} \psi+\widetilde{u}_{\varepsilon}^{(1)} \partial_{r} \psi+\left(\ln h_{2}(r)\right)^{\prime} \widetilde{u}_{\varepsilon}^{(1)} \psi\right) d x \\
& \quad-\varepsilon \int_{\Omega_{\varepsilon}^{(2)}} Y_{2}\left(\frac{x_{2}}{\varepsilon}\right) r^{-1}\left(\ln h_{2}(r)\right)^{\prime} \partial_{x_{2}}\left(u_{\varepsilon} \psi\right) d x . \tag{2.29}
\end{align*}
$$

Evidently, the last integral vanishes in (2.29) as $\varepsilon \rightarrow 0$. The limits of the other ones can be found with (2.26). As a result, we get

$$
r_{2}^{-1} h_{2}\left(r_{2}\right) \int_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}} u_{r_{2}} \psi d \sigma_{x}=\int_{\Omega^{(2)}} r^{-1} \partial_{r}\left(h_{2}(r) u_{2} \psi\right) d x .
$$

After integrating by parts, we obtain

$$
\int_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}} u_{r_{2}} \psi d \sigma_{x}=\int_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}} u_{2} \psi d \sigma_{x} \quad \forall \psi \in C^{\infty}\left(\overline{\Omega^{(2)}}\right),\left.\psi\right|_{\Omega^{\prime}}=0
$$

whence it follows that $u_{r_{2}}=\left.u_{2}\right|_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}}$ a..e. in $\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}$.
3. Let us find conjugation conditions on the joint zone. The first relation in (2.26) and compactness of the trace operator imply that

$$
\begin{equation*}
\left.\left.u_{\varepsilon}\right|_{\Omega^{\prime}} \longrightarrow u_{0}\right|_{\Omega^{\prime}} \text { strongly in } L^{2}\left(\Omega^{\prime}\right) \tag{2.30}
\end{equation*}
$$

Similarly as we have deduced (2.29), we can prove that the following identity:

$$
\begin{align*}
-r_{0}^{-1} \int_{\Omega^{\prime}} \chi_{\Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{0}\right\}} u_{\varepsilon} \psi d \sigma_{x} & =\int_{\Omega^{(1)}} r^{-1}\left(\widetilde{\partial_{r} u_{\varepsilon}^{(1)}} \psi+\widetilde{u}_{\varepsilon}^{(1)} \partial_{r} \psi+\left(\ln h_{1}(r)\right)^{\prime} \widetilde{u}_{\varepsilon}^{(1)} \psi\right) d x \\
& -\varepsilon \int_{\Omega_{\varepsilon}^{(1)}} Y_{1}\left(\frac{x_{2}}{\varepsilon}\right) r^{-1}\left(\ln h_{1}(r)\right)^{\prime} \partial_{x_{2}}\left(u_{\varepsilon} \psi\right) d x \tag{2.31}
\end{align*}
$$

for any $\psi \in C^{\infty} \overline{\left(\Omega^{(1)}\right)},\left.\psi\right|_{\partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}}=0$. Utilizing the second relation in (2.16), (2.30) and (2.26), we can pass to the limit in (2.31). As a result, we get

$$
-\frac{h_{1}\left(r_{0}\right)}{r_{0}} \int_{\Omega^{\prime}} u_{0} \psi d \sigma_{x}=\int_{\Omega^{(1)}} r^{-1} \partial_{r}\left(h_{1}(r) u_{1} \psi\right) d x=-\frac{h_{1}\left(r_{0}\right)}{r_{0}} \int_{\Omega^{\prime}} u_{1} \psi d \sigma_{x}
$$

whence $\left.u_{0}\right|_{\Omega^{\prime}}=\left.u_{1}\right|_{\Omega^{\prime}}$ a.e. in $\Omega^{\prime}$.
Repeating the same assertions for the thin discs from the second level, we obtain

$$
\begin{equation*}
\left.u_{0}\right|_{\Omega^{\prime}}=\left.u_{1}\right|_{\Omega^{\prime}}=\left.u_{2}\right|_{\Omega^{\prime}} \text { a.e. in } \Omega^{\prime} . \tag{2.32}
\end{equation*}
$$

On the grounds of (2.32) and results obtained in the second item, we can claim that the multi-sheeted function $\mathbf{u}=\left(u_{0}, u_{1}, u_{2}\right)$ belongs to $\widetilde{\mathbf{H}}$.
4. Consider a multi-sheeted function $\mathbf{p}=\left(p_{0}, p_{1}, p_{2}\right)$, where $p_{0} \in C^{\infty}\left(\bar{\Omega}_{0}\right)$, $p_{i} \in C^{\infty}\left(\overline{\Omega^{(i)}}\right), i=1,2$, are arbitrary functions such that $\left.p_{0}\right|_{\Omega^{\prime}}=\left.p_{1}\right|_{\Omega^{\prime}}=\left.p_{2}\right|_{\Omega^{\prime}}$. Then the function

$$
\Phi(x)=\left.\mathbf{p}\right|_{\Omega_{\varepsilon}}(x):= \begin{cases}p_{0}(x), & x \in \Omega_{0} \\ p_{1}(x), & x \in \Omega_{\varepsilon}^{(1)}, \\ p_{2}(x), & x \in \Omega_{\varepsilon}^{(2)}\end{cases}
$$

belongs to $H^{1}\left(\Omega_{\varepsilon}\right)$. Substituting $\Phi$ in (2.6) and utilizing the zero extensions, we get

$$
\begin{gathered}
\varepsilon k_{2} \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}} u_{\varepsilon} p_{2} d \sigma_{x}+\left.k_{2} \int_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}} \tilde{u}_{\varepsilon}\right|_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}} p_{2} d \sigma_{x} \\
=\int_{\Omega_{0}} f_{\varepsilon} p_{0} d x+\sum_{i=1}^{2}\left(\int_{\Omega^{(i)}} \chi_{\Omega_{\varepsilon}^{(i)}} f_{\varepsilon} p_{i} d x+\varepsilon^{\beta} \int_{\partial \Omega_{\varepsilon}^{(i)} \cap\left\{r_{0}<r<r_{i}\right\}} g_{\varepsilon} p_{i} d \sigma_{x}\right) \\
+\varepsilon^{\beta} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{1}\right\}} g_{\varepsilon} p_{1} d \sigma_{x}+\int_{\partial \Omega_{0} \cap\left\{r<r_{0}\right\}} q_{\varepsilon} p_{0} d \tilde{x},
\end{gathered}
$$

 (2.3), (2.4), (2.5), (2.16), and Lemma 2.2, this equality is transformed $(\varepsilon \rightarrow 0)$ in (2.25) for the function $\mathbf{u}$. By approximation the obtained identity holds for any function $\mathbf{p} \in \widetilde{\mathbf{H}}$. Hence, the function $\mathbf{u}$ is the unique weak solution to problem (2.23).
5. Due to the uniqueness of this solution, the above assertions are true for any subsequence $\left\{\varepsilon^{\prime}\right\}$ chosen at the beginning of the proof. Thus the limits $(2.22)$ hold.
6. It remains to prove the convergence (2.24) of the energy integral $E_{1, \varepsilon}\left(u_{\varepsilon}\right)$ to the energy integral $E_{1}(\mathbf{u})$ of the homogenized problem. Using (2.6), we get

$$
\begin{gather*}
E_{1, \varepsilon}\left(u_{\varepsilon}\right)=\mathrm{L}_{1, \varepsilon}\left(u_{\varepsilon}\right)=\int_{\Omega_{0}} f_{\varepsilon} u_{\varepsilon} d x+\varepsilon^{\beta} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{1}\right\}} g_{\varepsilon} u_{\varepsilon} d \sigma_{x} \\
+\int_{\partial \Omega_{0} \cap\left\{r<r_{0}\right\}} q_{\varepsilon} u_{\varepsilon} d \tilde{x}+\sum_{i=1}^{2}\left(\int_{\Omega^{(i)}} f_{\varepsilon} \widetilde{u}_{\varepsilon}^{(i)} d x+\varepsilon^{\beta} \int_{\partial \Omega_{\varepsilon}^{(i)} \cap\left\{r_{0}<r<r_{i}\right\}} g_{\varepsilon} u_{\varepsilon} d \sigma_{x}\right) . \tag{2.33}
\end{gather*}
$$

Taking into account (2.9), (2.26), (2.4), and compact embedding $H^{1}\left(\Omega^{(i)}\right) \subset L^{2}$ $\left(\Omega^{(i)}\right)$, similarly as in Lemma 2.2 we prove

$$
\varepsilon \int_{\partial \Omega_{\varepsilon}^{(i)} \cap\left\{r_{0}<r<r_{i}\right\}} g_{\varepsilon} u_{\varepsilon} d \sigma_{x} \longrightarrow 2 \int_{\Omega^{(i)}} g_{0} u_{i} d x \quad \text { as } \varepsilon \rightarrow 0, i=1,2 .
$$

The limits of the rest of the summands in (2.33) can be found with the help of (2.3), (2.4), (2.5), (2.26), and (2.13). Thus,

$$
\lim _{\varepsilon \rightarrow 0} E_{1, \varepsilon}\left(u_{\varepsilon}\right)=\mathrm{L}_{1}(\mathbf{u})=E_{1}(\mathbf{u})
$$

### 2.3.2 Convergence Theorem for Problem (2.2)

Let us introduce Sobolev spaces $H^{1}\left(\Omega_{0} ; \Omega^{\prime}\right)=\left\{\varphi \in H^{1}\left(\Omega_{0}\right):\left.\varphi\right|_{\Omega^{\prime}}=0\right\}$ and $\widetilde{H}^{1}\left(\Omega^{(i)} ; \Omega^{\prime}\right)=\left\{\varphi \in \widetilde{H}^{1}\left(\Omega^{(i)}\right):\left.\varphi\right|_{\Omega^{\prime}}=0\right\}, i=1,2$, with the scalar products

$$
\begin{gathered}
(u, v)_{2,0}=\int_{\Omega_{0}} \nabla_{x} u \cdot \nabla_{x} v d x \quad \forall u, v \in H^{1}\left(\Omega_{0} ; \Omega^{\prime}\right) \\
(u, v)_{2, i}=\int_{\Omega^{(i)}} h_{i}(r) \nabla_{\tilde{x}} u \cdot \nabla_{\tilde{x}} v d x \quad \forall u, v \in \widetilde{H}^{1}\left(\Omega^{(i)} ; \Omega^{\prime}\right) .
\end{gathered}
$$

Theorem 2.2 Assume (2.3)-(2.5). Then for the weak solution $v_{\varepsilon}$ to problem (2.2) the following limit relations hold:

$$
\left.\begin{array}{r}
v_{\varepsilon} \rightharpoonup v_{0} \quad \text { weakly in } H^{1}\left(\Omega_{0}\right),  \tag{2.34}\\
\widetilde{v}_{\varepsilon}^{(1)} \rightharpoonup h_{1} v_{1} \text { weakly in } L^{2}\left(\Omega^{(1)}\right), \\
\widetilde{v}_{\varepsilon}^{(2)} \rightharpoonup 0 \quad \text { weakly in } H^{1}\left(\Omega^{(2)}\right)
\end{array}\right\} \quad \text { as } \varepsilon \rightarrow 0,
$$

where $v_{0} \in H^{1}\left(\Omega_{0} ; \Omega^{\prime}\right)$ is a weak solution to the problem

$$
\begin{cases}-\Delta_{x} v_{0}(x)=f_{0}(x), & x \in \Omega_{0},  \tag{2.35}\\ \partial_{\nu} v_{0}(x)=q_{0}(x), & x \in \partial \Omega_{0} \cap\left\{r<r_{0}\right\}, \\ v_{0}(x)=0, & x \in \Omega^{\prime},\end{cases}
$$

and $v_{1} \in \widetilde{H}^{1}\left(\Omega^{(1)} ; \Omega^{\prime}\right)$ is a weak solution to the problem

$$
\begin{cases}-\operatorname{div}_{\tilde{x}}\left(h_{1}(r) \nabla_{\tilde{x}} v_{1}(x)\right)=h_{1}(r) f_{0}(x)+2 g_{0}(x), & x \in \Omega^{(1)},  \tag{2.36}\\ \partial_{\nu} v_{1}(x)=0, & x \in \partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}, \\ v_{1}(x)=0, & x \in \Omega^{\prime} .\end{cases}
$$

Besides, the following energy convergence (as $\varepsilon \rightarrow 0)$ takes place:

$$
\begin{equation*}
E_{2, \varepsilon}\left(v_{\varepsilon}\right):=\left(v_{\varepsilon}, v_{\varepsilon}\right)_{2, \varepsilon} \longrightarrow\left(v_{0}, v_{0}\right)_{2,0}+\left(v_{1}, v_{1}\right)_{2,1}=: E_{2,0}\left(v_{0}\right)+E_{2,1}\left(v_{1}\right) . \tag{2.37}
\end{equation*}
$$

Both problems (2.35) and (2.36) form the homogenized problem for problem (2.2).
Definition 2.4 A function $v \in H^{1}\left(\Omega_{0} ; \Omega^{\prime}\right)$ is called a weak solution to problem (2.35) if the integral identity

$$
\begin{equation*}
(v, \varphi)_{2,0}=\mathrm{L}_{2,0}(\varphi):=\int_{\Omega_{0}} f_{0} \varphi d x+\int_{\partial \Omega_{0} \cap\left\{r<r_{0}\right\}} q_{0} \varphi d \tilde{x} \tag{2.38}
\end{equation*}
$$

holds for all $\varphi \in H^{1}\left(\Omega_{0} ; \Omega^{\prime}\right)$.
Definition 2.5 A function $v \in \widetilde{H}^{1}\left(\Omega^{(1)} ; \Omega^{\prime}\right)$ is called a weak solution to problem (2.36) if the identity

$$
\begin{equation*}
(v, \varphi)_{2,1}=\mathrm{L}_{2,1}(\varphi):=\int_{\Omega^{(1)}}\left(h_{1}(r) f_{0}+2 g_{0}\right) \varphi d x \tag{2.39}
\end{equation*}
$$

is valid for every $\varphi \in \widetilde{H}^{1}\left(\Omega^{(1)} ; \Omega^{\prime}\right)$.
Using the Riesz representation theorem, it is easy to check that these problems have unique weak solutions.

Proof 1. Estimate (2.21) and (2.3)-(2.5) imply that the quantities
are uniformly bounded with respect to $\varepsilon$. Hence there exists a subsequence $\left\{\varepsilon^{\prime}\right\} \subset\{\varepsilon\}$ (again denoted by $\{\varepsilon\}$ ) such that

$$
\left.\begin{array}{rlr}
v_{\varepsilon} & \rightharpoonup v_{0} & \text { weakly in } H^{1}\left(\Omega_{0}\right),  \tag{2.40}\\
\widetilde{v}_{\varepsilon}^{(1)} & \rightharpoonup \widetilde{v}_{1}:=h_{1} v_{1} & \text { weakly in } L^{2}\left(\Omega^{(1)}\right), \\
{\widetilde{\partial_{x_{k}}} v_{\varepsilon}^{(1)}}_{v_{\varepsilon}}^{\widetilde{v}_{\varepsilon}^{(2)}} \rightharpoonup \widetilde{v}_{1, k}:=h_{1} v_{1, k} & \text { weakly in } L^{2}\left(\Omega^{(1)}\right) \\
& \text { weakly in } H^{1}\left(\Omega^{(2)}\right),
\end{array}\right\} \quad \text { as } \varepsilon \rightarrow 0(k=1,2,3),
$$

where the functions $v_{0}, v_{1}, v_{1, k}, v_{2}$ will be defined later.
2. From (2.12) and (2.21) it follows that

$$
\left\|\widetilde{v}_{\varepsilon}^{(2)}\right\|_{L^{2}\left(\Omega^{(2)}\right)}^{2} \leq c_{0} \varepsilon^{2} \int_{\Omega_{\varepsilon}^{(2)}}\left|\nabla_{x} v_{\varepsilon}\right|^{2} d x \leq c_{0} \varepsilon^{2}
$$

whence we deduce that $v_{2}=0$ a.e. in $\Omega^{(2)}$.
Similarly as in steps 2 and 3 in the proof of Theorem 2.1 we can show that

- $v_{1,2}=0$ a.e. in $\Omega^{(1)}$;
- there exist weak derivatives $\partial_{x_{k}} v_{1}, k=1,3$, and $\partial_{x_{k}} v_{1}=v_{1, k}$ a.e. in $\Omega^{(1)}$;
- $\left.v_{0}\right|_{\Omega^{\prime}}=\left.v_{1}\right|_{\Omega^{\prime}}=\left.v_{2}\right|_{\Omega^{\prime}}$ a.e. in $\Omega^{\prime}$.

Since $v_{2}=0$ a.e. in $\Omega^{(2)},\left.v_{0}\right|_{\Omega^{\prime}}=\left.v_{1}\right|_{\Omega^{\prime}}=0$ a.e. in $\Omega^{\prime}$.
3. Let us consider arbitrary functions $\varphi_{0} \in C^{\infty}\left(\overline{\Omega_{0}}\right)$ and $\varphi_{1} \in C^{\infty}\left(\overline{\Omega^{(1)}}\right)$ such that $\varphi_{0}=\varphi_{1}=0$ in some neighborhood of $\Omega^{\prime}$. With the help of these functions, we define a function

$$
\Phi(x)= \begin{cases}\varphi_{0}(x), & x \in \Omega_{0} \\ \varphi_{1}(x), & x \in \Omega_{\varepsilon}^{(1)} \\ 0, & x \in \Omega_{\varepsilon}^{(2)}\end{cases}
$$

Obviously, $\Phi \in H^{1}\left(\Omega_{\varepsilon} ; \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}\right)$. Integral identity (2.7) with the test function $\Phi$ looks like

$$
\begin{array}{r}
\int_{\Omega_{0}} \nabla_{x} v_{\varepsilon} \cdot \nabla_{x} \varphi_{0} d x+\int_{\Omega^{(1)}}{\widetilde{\nabla_{x}} v_{\varepsilon}^{(1)}}^{(1)} \nabla_{x} \varphi_{1} d x=\int_{\Omega_{0}} f_{\varepsilon} \varphi_{0} d x+\int_{\Omega^{(1)}} \chi_{\Omega_{\varepsilon}^{(1)}} f_{\varepsilon} \varphi_{1} d x \\
+\varepsilon \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}} g_{\varepsilon} \varphi_{1} d \sigma_{x}+\int_{\partial \Omega_{0} \cap\left\{r<r_{0}\right\}} q_{\varepsilon} \varphi_{0} d \tilde{x}
\end{array}
$$

Passing to the limit in the last identity and taking into account (2.40), (2.3), (2.4), (2.5), (2.16), (2.13), and Lemma 2.2, we get

$$
\left(v_{0}, \varphi_{0}\right)_{2,0}+\left(v_{1}, \varphi_{1}\right)_{2,1}=\mathrm{L}_{2,0}\left(\varphi_{0}\right)+\mathrm{L}_{2,1}\left(\varphi_{1}\right)
$$

Evidently, this identity is equivalent to the following two identities: (2.38) (for $v_{0}$ and for all $\varphi_{0} \in C^{\infty}\left(\overline{\Omega_{0}}\right), \varphi_{0}=0$ in some neighborhood of $\Omega^{\prime}$ ) and (2.39) (for $v_{1}$ and for all $\varphi_{1} \in C^{\infty}\left(\overline{\Omega^{(1)}}\right), \varphi_{1}=0$ in some neighborhood of $\left.\Omega^{\prime}\right)$. By the closure, identity (2.38) holds for every $\varphi_{0} \in H^{1}\left(\Omega_{0} ; \Omega^{\prime}\right)$, and identity (2.39) holds for every $\varphi_{1} \in \widetilde{H}^{1}\left(\Omega^{(1)} ; \Omega^{\prime}\right)$. Thus, $v_{0}$ is the unique weak solution to problem (2.35) and $v_{1}$ is the unique weak solution to problem (2.36).

Due to the uniqueness of these solutions, the above assertions are true for any subsequence $\left\{\varepsilon^{\prime}\right\}$ chosen at the beginning of the proof. Thus the limits (2.34) hold.
4. In order to prove (2.37), we first note from (2.7) that

$$
\begin{gathered}
E_{2, \varepsilon}\left(v_{\varepsilon}\right)=\int_{\Omega_{\varepsilon}}\left|\nabla_{x} v_{\varepsilon}\right|^{2} d x \\
=\int_{\Omega_{0}} f_{\varepsilon} v_{\varepsilon} d x+\sum_{i=1}^{2} \int_{\Omega^{(i)}} f_{\varepsilon} \widetilde{v}_{\varepsilon}^{(i)} d x+\varepsilon \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}} g_{\varepsilon} v_{\varepsilon} d \sigma_{x}+\int_{\partial \Omega_{0} \cap\left\{r<r_{0}\right\}} q_{\varepsilon} v_{\varepsilon} d \tilde{x} .
\end{gathered}
$$

Passing to the limit as $\varepsilon \rightarrow 0$ in this equality and taking into account (2.3), (2.4), (2.5), (2.40), (2.16), (2.13), (2.9), we deduce

$$
\lim _{\varepsilon \rightarrow 0} E_{2, \varepsilon}\left(v_{\varepsilon}\right)=\mathrm{L}_{2,0}\left(v_{0}\right)+\mathrm{L}_{2,1}\left(v_{1}\right)
$$

Taking (2.38) and (2.39) into account, we get (2.37). The theorem is proved.

### 2.4 Conclusions to this Chapter

The results obtained in this chapter show that boundary conditions on the surfaces of the thin discs, geometric structure of the discs, the parameters $\alpha$ and $\beta$ significantly influence the asymptotic behavior (as $\varepsilon \rightarrow 0$ ) of solutions to BVPs in thick multilevel junctions of type 3:2:2.

1. In case of the alternating Robin boundary conditions (problem (2.1)), the solution to the corresponding homogenized problem (2.23) is the multi-sheeted function $\mathbf{u}=\left(u_{0}, u_{1}, u_{2}\right)$ whose components are the first terms of the asymptotics for the solution $u_{\varepsilon}$ to problem (2.1). The homogenized problem (2.23) contains three different differential equations, namely the Poisson equation in the junction's body $\Omega_{0}$, and two homogenized differential equations with respect to only two variables $x_{1}$ and $x_{3}$ in the domains $\Omega^{(1)}$ and $\Omega^{(2)}$, respectively (the variable $x_{2}$ is involved here as a parameter). This is a consequence of the type of the thick junction $\Omega_{\varepsilon}$. In addition,

- the functions $h_{1}$ and $h_{2}$ appear as coefficients in the differential equations in $\Omega^{(1)}$ and $\Omega^{(2)}$ as well as in the second conjugation condition on $\Omega^{\prime}$ :

$$
\partial_{r} u_{0}=h_{1}\left(r_{0}\right) \partial_{r} u_{1}+h_{2}\left(r_{0}\right) \partial_{r} u_{2}
$$

(recall that these functions describe relative thickness of the thin discs);

- the Robin boundary conditions are transformed into the zero-order terms $2 \delta_{\alpha, 1} k_{1} u_{1}, 2 k_{2} u_{2}$, and $2 \delta_{\beta, 1} g_{0}$ of the homogenized differential equations in $\Omega^{(1)}$ and $\Omega^{(2)}$. These terms show the influence of the parameters $\alpha$ and $\beta$. If $\alpha>1$, then the summand $2 \delta_{\alpha, 1} k_{1} u_{1}$ vanishes. From physical point of view, this means that thermal conductivity on the surfaces of the thin discs from the first level is so small that we can neglect the heat exchange on this part of the boundary. If $\beta>1$, then the temperature outside can be neglected.

2. In case of the alternating Neumann and Dirichlet boundary conditions (problem (2.2)) the zero extension $\widetilde{v}_{\varepsilon}^{(2)}$ of the solution tends to zero (see the last limit in (2.34)). As a result, the starting problem (2.2) is split (as $\varepsilon \rightarrow 0$ ) into two independent problems (2.35) and (2.36) that form together the homogenized problem for problem (2.2). This union is justified by the energy convergence (2.37) as well. In addition, next terms of the asymptotics for $v_{\varepsilon}$ depend on the solutions to problems (2.35) and (2.36).
3. The convergence of the energy integrals can be used to study optimal control problems in thick multilevel junctions of type 3:2:2 (see subparagraph "Boundaryvalue problems" in the Introduction, p. 8).
4. The obtained results may be easily applied to problems in thick $m$-level junctions of type $3: 2: 2$, where $m \geq 3$. Clearly, the presence of the homogeneous Dirichlet conditions on the surfaces of thin discs at least one of the levels leads to the splitting the starting problem into $m+1$ independent boundary-value problems as $\varepsilon \rightarrow 0$. If the Neumann or Fourier are given on the surfaces of thin discs of all levels, then the corresponding homogenized problem will contain $m+1$ differential equations that are bound by the conjugation conditions on $\Omega^{\prime}$; the solution of the homogenized problem will be some $m$-sheeted function.

# Chapter 3 <br> Homogenization of Elliptic Problems in Thick Junctions with Sharp Edges 

### 3.1 Statement of the Problem

In this chapter we suppose that $h_{2}(r)=h_{2}\left(r_{0}\right)=: h_{2}, r \in\left[r_{0}, r_{2}\right]$, where $h_{2} \in$ $(0,1)$ is a fixed number, $h_{1}:\left[r_{0}, r_{1}\right) \mapsto(0,1)$ is a smooth function in $\left[r_{0}, r_{1}\right)$, and there exists $\delta_{1}>0$ such that

$$
\begin{equation*}
h_{1}(r)=\left(r_{1}-r\right)^{1+\gamma} \quad \forall r \in\left[r_{1}-\delta_{1}, r_{1}\right], \tag{3.1}
\end{equation*}
$$

where $\gamma>-1$ is a parameter. Also we suppose that $h_{1}(s)$ is constant in some neighborhood of $r_{0}$, i.e., there exists a positive constant $\delta_{0}$ such that $h_{1}(r)=h_{1}\left(r_{0}\right)$ for all $r \in\left[r_{0}, r_{0}+\delta_{0}\right]$.

According to these assumptions the thick junction $\Omega_{\varepsilon}$, described in Sect. 2.1, looks like in Fig. 3.1 (in case $\gamma>0$ ). In accordance with (3.1) geometric structure of the edges of the thin discs $\left\{\Omega_{\varepsilon}^{(1)}(j)\right\}_{j=0}^{N-1}$ significantly depends on $\gamma$ (see Fig. 3.2).

In $\Omega_{\varepsilon}$, we consider a linear elliptic boundary-value problem

$$
\begin{cases}-\Delta_{x} u_{\varepsilon}(x)=f_{\varepsilon}(x), & x \in \Omega_{\varepsilon},  \tag{3.2}\\ \partial_{v} u_{\varepsilon}(x)=0, & x \in \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\} \cup \partial \Omega_{\varepsilon} \cap\left\{r=r_{0}\right\}, \\ \partial_{\nu} u_{\varepsilon}(x)+\varepsilon \kappa u_{\varepsilon}(x)=0, & x \in \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}, \\ u_{\varepsilon}(x)=q_{\varepsilon}(x), & x \in \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}, \\ \left.\partial_{x_{2}}^{p} u_{\varepsilon}\right|_{x_{2}=0}=\left.\partial_{x_{2}}^{p} u_{\varepsilon}\right|_{x_{2}=l}, & p=0,1, x \in \partial \Omega_{0} \cap\left\{r<r_{0}\right\} .\end{cases}
$$

Remark 3.1 Hereinafter, we use the precedence (from highest to lowest) for the set operators $\backslash, \cap, \cup, \times$.

In (3.2) $\kappa$ is a positive constant. Except (2.3), for the right-hand side $f_{\varepsilon}$ in the case $\gamma=0$ we suppose that there exist positive constants $\varepsilon_{0}, C_{0}$ such that


Fig. 3.1 The cross section of the thick junction $\Omega_{\varepsilon}$ of type 3:2:2 $(\gamma>0, N=12)$

$$
\begin{equation*}
\int_{\Omega_{\varepsilon}} F_{\varepsilon}^{2}(x) d x<C_{0} \tag{3.3}
\end{equation*}
$$

for all $\varepsilon \in\left(0, \varepsilon_{0}\right)$, where $F_{\varepsilon}(x)=\varepsilon^{-1}\left(\overleftrightarrow{f_{\varepsilon}}\left(x+\varepsilon \bar{e}_{2}\right)-\overleftrightarrow{f_{\varepsilon}}(x)\right), \quad \bar{e}_{2}=(0,1,0)$, and $\overleftrightarrow{\varphi}$ is the $l$-periodic extension of a function $\varphi: \Omega_{\varepsilon} \rightarrow \mathbb{R}$ along the axis $O x_{2}$.

The functions $q_{\varepsilon}, q_{0} \in H^{\frac{3}{2}}\left(\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}\right)$ and

$$
\begin{equation*}
q_{\varepsilon} \xrightarrow{w} q_{0} \text { weakly in } H^{\frac{3}{2}}\left(\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}\right) \text { as } \varepsilon \rightarrow 0 . \tag{3.4}
\end{equation*}
$$

Consider a Sobolev space

$$
H_{\mathrm{per}}^{1}\left(\Omega_{\varepsilon}\right):=\left\{\varphi \in H^{1}\left(\Omega_{\varepsilon}\right): \varphi\left(x_{1}, 0, x_{3}\right)=\varphi\left(x_{1}, l, x_{3}\right), r<r_{0}\right\}
$$

Remark 3.2 Here and further we denote by $\varphi\left(x_{1}, 0, x_{3}\right)$ and $\varphi\left(x_{1}, l, x_{3}\right)$ the traces of $\varphi$ on the left and right bases of the cylinder $\Omega_{0}$.

Definition 3.1 If $\gamma \in(-1,0]$, then a function $u_{\varepsilon} \in H_{\text {per }}^{1}\left(\Omega_{\varepsilon}\right)$ is called a weak solution to problem (3.2) if $\left.u_{\varepsilon}\right|_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}}=q_{\varepsilon}$ and the integral identity

$$
\begin{equation*}
\int_{\Omega_{\varepsilon}} \nabla_{x} u_{\varepsilon} \cdot \nabla_{x} \varphi d x+\varepsilon \kappa \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}} u_{\varepsilon} \varphi d \tilde{x}=\int_{\Omega_{\varepsilon}} f_{\varepsilon} \varphi d x \tag{3.5}
\end{equation*}
$$

holds for all functions $\varphi \in H_{\text {per }}^{1}\left(\Omega_{\varepsilon}\right)$ such that $\left.\varphi\right|_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}}=0$.


Fig. 3.2 Cross sections of the edges of the thin discs from the first level

Let

$$
R_{\alpha}^{\beta}=\left\{x \in \mathbb{R}^{3}: r \in(\alpha, \beta), x_{2} \in(0, l)\right\},
$$

where $0 \leq \alpha<\beta$. We denote by $C_{\text {per }}^{\infty}\left(\overline{\Omega_{\varepsilon}}, \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{1}\right\}\right)$ the set of smooth functions $\varphi: \overline{\Omega_{\varepsilon}} \mapsto \mathbb{R}$ vanishing in some subset $\Omega_{\varepsilon}^{(1)} \cap R_{r_{1}-\alpha}^{r_{1}}$ (not necessarily the same for all functions) that are $l$-periodic in $x_{2}$. The closure of $C_{\text {per }}^{\infty}\left(\overline{\Omega_{\varepsilon}}, \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{1}\right\}\right)$ in $H^{1}\left(\Omega_{\varepsilon}\right)$ denotes by $H_{\text {per }}^{1}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{1}\right\}\right)$.

Remark 3.3 In case $\gamma=0$, we conclude that $H_{\text {per }}^{1}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{1}\right\}\right)=H_{\text {per }}^{1}$ ( $\Omega_{\varepsilon}$ ) (see Corollary 3.1). But if $\gamma>0$ then the boundary $\partial \Omega_{\varepsilon}$ is not Lipschitz, and we cannot state that these spaces coincide (see [67]).

Definition 3.2 In case $\gamma>0$, we say that a function $u_{\varepsilon} \in H_{\text {per }}^{1}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(1)} \cap\{r=\right.$ $\left.r_{1}\right\}$ ) is a weak solution to problem (3.2) if $\left.u_{\varepsilon}\right|_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}}=q_{\varepsilon}$ and integral identity (3.5) holds for all $\varphi \in H_{\text {per }}^{1}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{1}\right\}\right)$ such that $\left.\varphi\right|_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}}=0$.

### 3.2 Auxiliary Statements

### 3.2.1 Cases of Rounded and Linear Edges

In these cases, the boundary of $\Omega_{\varepsilon}$ is Lipschitz (see Fig.3.2a, b). Clearly, for a.e. $x \in \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}$ the outward unit normal at $x$ is defined by (2.8) and the integral identity (2.9) holds. For thin discs from the second level the identity (2.9) has the form

$$
\begin{equation*}
\frac{\varepsilon h_{2}}{2} \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}} \varphi d \tilde{x}=\int_{\Omega_{\varepsilon}^{(2)}} \varphi d x-\varepsilon \int_{\Omega_{\varepsilon}^{(2)}} Y_{2}\left(\frac{x_{2}}{\varepsilon}\right) \partial_{x_{2}} \varphi d x \quad \forall \varphi \in H^{1}\left(\Omega_{\varepsilon}\right) \tag{3.6}
\end{equation*}
$$

Lemma 3.1 For $\gamma \in(-1,0]$, there exist positive constants $\varepsilon_{0}, C_{0}$ such that for all $\varepsilon \in\left(0, \varepsilon_{0}\right)$ and $\varphi \in H^{1}\left(\Omega_{\varepsilon}\right)$ the estimate (2.10) holds.

Proof Let $\varphi \in C^{\infty}\left(\overline{\Omega_{\varepsilon}}\right)$. We choose a fixed $\alpha \in\left(0, \frac{\delta_{1}}{2}\right)$ such that

$$
\begin{equation*}
\min _{r \in\left[r_{0}, r_{1}-\alpha\right]} h_{1}(r)=h_{1}\left(r_{1}-\alpha\right)=\alpha^{1+\gamma} . \tag{3.7}
\end{equation*}
$$

Similarly as in [32], we can prove the following identity:

$$
\frac{\varepsilon}{2} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\} \cap R_{r_{0}^{r}}^{r_{1}-\alpha}} \frac{h_{1}(r) \psi}{N_{\varepsilon}^{(1)}(r)} d \sigma_{x}=\int_{\Omega_{\varepsilon}^{(1)} \cap R_{r_{0}}^{r_{1}-\alpha}} \psi d x-\varepsilon \int_{\Omega_{\varepsilon}^{(1)} \cap R_{r_{0}^{r}}^{r_{1}-\alpha}} Y_{1}\left(\frac{x_{2}}{\varepsilon}\right) \partial_{x_{2}} \psi d x
$$

for all $\psi \in H^{1}\left(\Omega_{\varepsilon}\right)$. Taking into account (3.7), the last identity, and the facts that $\max _{\mathbb{R}}\left|Y_{1}\right| \leq 2$ and $\max _{\left[r_{0}, r_{1}-\alpha\right]}\left|h_{1}^{\prime}\right| \leq c_{0} \alpha^{\gamma}$, we derive

$$
\begin{equation*}
\|\varphi\|_{L^{2}\left(\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\} \cap R_{r_{0}}^{r_{1}-\alpha}\right)} \leq c_{1} \alpha^{-\frac{1}{2}} \varepsilon^{-\frac{1}{2}}\|\varphi\|_{H^{1}\left(\Omega_{\varepsilon}^{(1)} \cap R_{r_{0}}^{r_{1}-\alpha}\right)} \quad \forall \varphi \in H^{1}\left(\Omega_{\varepsilon}\right) \tag{3.8}
\end{equation*}
$$

Let $\left(r, x_{2}, \theta\right)$ be the cylindric coordinates of $x \in \partial \Omega_{\varepsilon}^{(1)}(j) \cap\left\{r>r_{0}\right\} \cap R_{r_{1}-\alpha}^{r_{1}}$. Using (3.1) we get

$$
r=r_{1}-\left|\frac{2\left(x_{2}-\varepsilon\left(j+l_{1}\right)\right)}{\varepsilon}\right|^{\frac{1}{1+\gamma}}=: \rho_{\varepsilon}\left(x_{2}\right), \quad x_{2} \in I_{\varepsilon}^{(1)}\left(j, h_{1}\left(r_{1}-\alpha\right)\right)
$$

Consider the following obvious inequality:

$$
\left.\varphi^{2}\right|_{r=\rho_{\varepsilon}\left(x_{2}\right)} \leq 2 \alpha \int_{r_{1}-2 \alpha}^{\rho_{\varepsilon}\left(x_{2}\right)}\left(\partial_{r} \varphi\right)^{2} d r+2 \varphi^{2}(x), \quad x \in \Omega_{\varepsilon}^{(1)}(j) \cap R_{r_{1}-\alpha}^{r_{1}} .
$$

Multiplying this inequality by the surface element of $\left(\partial \Omega_{\varepsilon}^{(1)}(j) \cap\left\{r>r_{0}\right\} \cap R_{r_{1}-\alpha}^{r_{1}}\right)$ and integrating it over $r \in\left(r_{1}-2 \alpha, \rho_{\varepsilon}\left(x_{2}\right)\right), x_{2} \in I_{\varepsilon}^{(1)}\left(j, h_{1}\left(r_{1}-\alpha\right)\right), \theta \in[0,2 \pi)$, we deduce

$$
\begin{equation*}
\|\varphi\|_{L^{2}\left(\partial \Omega_{\varepsilon}^{(1)}(j) \cap\left\{r_{0}<r<r_{1}\right\} \cap R_{r_{1}-\alpha}^{1_{1}}\right)} \leq c_{2} \varepsilon^{-\frac{1}{2}} \alpha^{-\frac{1+\nu}{2}}\|\varphi\|_{H^{1}\left(\Omega_{\varepsilon}^{(1)}(j) \cap R_{r_{1}-2 \alpha}^{r_{1}}\right)} \tag{3.9}
\end{equation*}
$$

for all $j=0, \ldots, N-1$. Inequalities (3.9) together with (3.8) provide the desired inequality. By the closure the estimate (2.10) remains valid for all $\varphi \in H^{1}\left(\Omega_{\varepsilon}\right)$.

Similar as in [121, Lemma 4.1] we prove the following statement.
Lemma 3.2 In case $\gamma \in(-1,0)$ there exist positive constants $\varepsilon_{0}, C_{0}$ such that for all $\varepsilon \in\left(0, \varepsilon_{0}\right)$ and $\varphi \in H^{1}\left(\Omega_{\varepsilon}\right)$ the following inequality holds:

$$
\left\|h_{1}^{-1} \varphi\right\|_{L^{2}\left(\Omega_{\varepsilon}^{(1)}\right)} \leq C_{1}\|\varphi\|_{H^{1}\left(\Omega_{\varepsilon}^{(1)}\right)}
$$

### 3.2.2 Case of Very Sharp Edges

In this case, the boundary of $\Omega_{\varepsilon}$ is not Lipschitz (see Fig. 3.2c). First we prove some properties of functions from the space $H_{\text {per }}^{1}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{1}\right\}\right)$ for $\gamma \geq 0$.
Lemma 3.3 Every function $\varphi \in H_{\mathrm{per}}^{1}\left(\Omega_{\varepsilon}\right)$ such that
(1) $|\varphi| \leq C_{2}\left|\ln \left(r_{1}-r\right)\right|^{1 / 2}$ a.e. in some subset $\Omega_{\varepsilon}^{(1)} \cap R_{r_{1}-\delta}^{r_{1}}$ for $\gamma=0$, or
(2) $|\varphi| \leq C_{2}\left(r_{1}-r\right)^{-\gamma / 2}$ a.e. in some subset $\Omega_{\varepsilon}^{(1)} \cap R_{r_{1}-\delta}^{r_{1}}$ for $\gamma>0$, belongs to $H_{\mathrm{per}}^{1}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{1}\right\}\right)$. Here $\delta$ is some positive number.
Proof For the proof we will use the approach of [133, Theorem 1]. Let $\varphi$ be an arbitrary function that satisfies the Lemma's assumptions. Consider a cutoff function

$$
\chi_{\alpha}(r)= \begin{cases}1, & r \leq r_{1}-\alpha_{1} \\ (\ln |\ln \alpha|)^{\eta}-\left(\ln \left|\ln \left(r_{1}-r\right)\right|\right)^{\eta}, & r_{1}-\alpha_{1}<r \leq r_{1}-\alpha, \\ 0, & r_{1}-\alpha<r<r_{1}\end{cases}
$$

where $\eta \in(0,1 / 2), \alpha_{1}$ is defined from the equality

$$
(\ln |\ln \alpha|)^{\eta}-\left(\ln \left|\ln \alpha_{1}\right|\right)^{\eta}=1
$$

and $\alpha$ is some positive number and it is so small that $\alpha_{1} \in(0, \delta)$. It is easy to verify that $\chi_{\alpha} \varphi \in H_{\text {per }}^{1}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{1}\right\}\right)$. Then we have

$$
\begin{aligned}
& \left\|\varphi-\chi_{\alpha} \varphi\right\|_{H^{1}\left(\Omega_{\varepsilon}\right)}^{2}=\left\|\varphi\left(1-\chi_{\alpha}\right)\right\|_{H^{1}\left(\Omega_{\varepsilon}\right)}^{2}=\int_{\Omega_{\varepsilon}^{(1)}} \varphi^{2}\left(1-\chi_{\alpha}\right)^{2} d x \\
& \quad+\int_{\Omega_{\varepsilon}^{(1)}}\left|\nabla_{x} \varphi\right|^{2}\left(1-\chi_{\alpha}\right)^{2} d x+2 \int_{\Omega_{\varepsilon}^{(1)}} \nabla_{x} \varphi \cdot \nabla_{x}\left(1-\chi_{\alpha}\right) \varphi\left(1-\chi_{\alpha}\right) d x \\
& +\int_{\Omega_{\varepsilon}^{(1)}} \varphi^{2}\left|\nabla_{x}\left(1-\chi_{\alpha}\right)\right|^{2} d x=: I_{\varepsilon, 1}(\alpha, \varphi)+I_{\varepsilon, 2}(\alpha, \varphi)+2 I_{\varepsilon, 3}(\alpha, \varphi)+I_{\varepsilon, 4}(\alpha, \varphi) .
\end{aligned}
$$

It is easy to see that $I_{\varepsilon, 1}(\alpha, \varphi) \rightarrow 0$ and $I_{\varepsilon, 2}(\alpha, \varphi) \rightarrow 0$ as $\alpha \rightarrow 0$ since $\left(1-\chi_{\alpha}\right)^{2} \leq$ $1, \lim _{\alpha \rightarrow 0}\left(1-\chi_{\alpha}\right)^{2}=0$, and $\|\varphi\|_{H^{1}\left(\Omega_{\varepsilon}\right)}<+\infty$.

If $\gamma=0$, then with the help of the first condition of the lemma and (3.1) we derive

$$
\begin{aligned}
I_{\varepsilon, 4}(\alpha, \varphi) & =\int_{\Omega_{\varepsilon}^{(1)} \cap R_{r_{1}-\alpha \alpha_{1}}^{r_{1}-\alpha}} \varphi^{2}\left|\nabla_{x}\left(1-\chi_{\alpha}\right)\right|^{2} d x \\
\leq & c_{0} \int_{\Omega_{\varepsilon}^{(1)} \cap R_{r_{1}-\alpha_{1}}^{r_{1}-\alpha}} \frac{\left|\ln \left(r_{1}-r\right)\right| d x}{\left(r_{1}-r\right)^{2}\left|\ln \left(r_{1}-r\right)\right|^{2}\left(\ln \left|\ln \left(r_{1}-r\right)\right|\right)^{2-2 \eta}} \\
\leq & c_{1} \int_{r_{1}-\alpha_{1}}^{r_{1}-\alpha} \frac{r d r}{\left(r_{1}-r\right)\left|\ln \left(r_{1}-r\right)\right|\left(\ln \left|\ln \left(r_{1}-r\right)\right|\right)^{2-2 \eta}} \longrightarrow 0 \text { as } \alpha \rightarrow 0 .
\end{aligned}
$$

If $\gamma>0$, then by the same way we get

$$
\begin{aligned}
I_{\varepsilon, 4}(\alpha, \varphi) & =\int_{\Omega_{\varepsilon}^{(1)} \cap R_{r_{1}-\alpha_{1}}^{r_{1}-\alpha}} \varphi^{2}\left|\nabla_{x}\left(1-\chi_{\alpha}\right)\right|^{2} d x \\
\leq & c_{2} \int_{\Omega_{\varepsilon}^{(1)} \cap R_{r_{1}-\alpha_{1}}^{r_{1}-\alpha}} \frac{\left(r_{1}-r\right)^{-\gamma} d x}{\left(r_{1}-r\right)^{2}\left|\ln \left(r_{1}-r\right)\right|^{2}\left(\ln \left|\ln \left(r_{1}-r\right)\right|\right)^{2-2 \eta}} \\
& \quad \leq c_{3} \int_{r_{1}-\alpha_{1}}^{r_{1}-\alpha} \frac{r d r}{\left(r_{1}-r\right)\left|\ln \left(r_{1}-r\right)\right|^{2}} \longrightarrow 0 \text { as } \alpha \rightarrow 0 .
\end{aligned}
$$

Since $\left|I_{\varepsilon, 3}(\alpha, \varphi)\right| \leq \sqrt{I_{\varepsilon, 2}(\alpha, \varphi) I_{\varepsilon, 4}(\alpha, \varphi)}, \lim _{\alpha \rightarrow 0}\left|I_{\varepsilon, 3}(\alpha, \varphi)\right|=0$.
Thus, $\chi_{\alpha} \varphi \rightarrow \varphi$ strongly in $H^{1}\left(\Omega_{\varepsilon}\right)$ as $\alpha \rightarrow 0$ and consequently $\varphi \in$ $H_{\text {per }}^{1}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{1}\right\}\right)$.

Corollary 3.1 If $\gamma \geq 0$, then any function $\varphi \in C^{\infty}\left(\overline{\Omega_{\varepsilon}}\right)$ such that $\varphi\left(x_{1}, 0, x_{3}\right)=$ $\varphi\left(x_{1}, l, x_{3}\right)$ can be approximated with a sequence from $C_{\text {per }}^{\infty}\left(\overline{\Omega_{\varepsilon}}, \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{1}\right\}\right)$ in the standard norm of $H^{1}\left(\Omega_{\varepsilon}\right)$.

### 3.2.3 A Priori Estimate

Similarly as in [27], we can prove that the norms $\|\cdot\|_{H^{1}\left(\Omega_{\varepsilon}\right)}$ and

$$
\|\varphi\|_{\varepsilon}:=\left(\int_{\Omega_{\varepsilon}}\left|\nabla_{x} \varphi\right|^{2} d x+\varepsilon \kappa \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}} \varphi^{2} d \tilde{x}\right)^{\frac{1}{2}}
$$

are uniformly in $\varepsilon$ equivalent in $H_{\text {per }}^{1}\left(\Omega_{\varepsilon}\right)$ (in $H_{\text {per }}^{1}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{1}\right\}\right)$ ) for all $\gamma \in(-1,0](\gamma>0)$, i.e., there exist positive constants $\varepsilon_{0}, C_{3}, C_{4}$ such that $C_{3}\|\varphi\|_{H^{1}\left(\Omega_{\varepsilon}\right)} \leq\|\varphi\|_{\varepsilon} \leq C_{4}\|\varphi\|_{H^{1}\left(\Omega_{\varepsilon}\right)}$ for all $\varepsilon \in\left(0, \varepsilon_{0}\right)$ and $\varphi \in H_{\text {per }}^{1}\left(\Omega_{\varepsilon}\right) \quad(\varphi \in$ $\left.H_{\text {per }}^{1}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{1}\right\}\right)\right)$.

Since $q_{\varepsilon} \in H^{\frac{3}{2}}\left(\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}\right)$, there exists a function $q_{\varepsilon} \in H^{1}\left(\Omega_{\varepsilon}\right)$ such that $\left\|q_{\varepsilon}\right\|_{H^{1}\left(\Omega_{\varepsilon}\right)} \leq c_{0}\left\|q_{\varepsilon}\right\|_{H^{\frac{1}{2}}\left(\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}\right)}$ and $\operatorname{supp} q_{\varepsilon} \subset \Omega_{\varepsilon}^{(2)} \cap R_{r_{0}+\delta}^{r_{2}}$ for some $\delta>0$.

Then the function $v_{\varepsilon}=u_{\varepsilon}-q_{\varepsilon}$ satisfies the integral identity

$$
\begin{aligned}
\int_{\Omega_{\varepsilon}} \nabla_{x} v_{\varepsilon} & \cdot \nabla_{x} \varphi d x+\varepsilon \kappa \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}} v_{\varepsilon} \varphi d \tilde{x} \\
& =\int_{\Omega_{\varepsilon}} f_{\varepsilon} \varphi d x-\int_{\Omega_{\varepsilon}^{(2)}} \nabla_{x} q_{\varepsilon} \cdot \nabla_{x} \varphi d x-\varepsilon \kappa \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}} q_{\varepsilon} \varphi d \tilde{x}
\end{aligned}
$$

where $\varphi$ is arbitrary function from $H_{\text {per }}^{1}\left(\Omega_{\varepsilon}\right)$ such that $\left.\varphi\right|_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}}=0$ if $\gamma \in$ ( $-1,0]$, or $\varphi \in H_{\text {per }}^{1}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{1}\right\}\right)$ if $\gamma>0$. According to (2.3), (3.4), and (2.10), the right-hand side of the last identity is a linear continuous functional

$$
\mathrm{L}_{\varepsilon}(\varphi):=\int_{\Omega_{\varepsilon}} f_{\varepsilon} \varphi d x-\int_{\Omega_{\varepsilon}^{(2)}} \nabla_{x} q_{\varepsilon} \cdot \nabla_{x} \varphi d x-\varepsilon \kappa \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}} q_{\varepsilon} \varphi d \tilde{x}
$$

on $H_{\text {per }}^{1}\left(\Omega_{\varepsilon}\right)$ if $\gamma \in(-1,0]$, or on $H_{\text {per }}^{1}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{1}\right\}\right)$ if $\gamma>0$. Since the norm of the functional $\mathrm{L}_{\varepsilon}$ is uniformly bounded in $\varepsilon$, then due to the Riesz representation theorem we have the following statement.

Lemma 3.4 For all $\gamma>-1$ and $\varepsilon>0$, there exists a unique weak solution $u_{\varepsilon}$ to problem (3.2). In addition, there exist positive constants $\varepsilon_{0}, C_{5}$ such that for all $\varepsilon \in\left(0, \varepsilon_{0}\right)$ the following inequality holds:

$$
\left\|u_{\varepsilon}\right\|_{H^{1}\left(\Omega_{\varepsilon}\right)} \leq C_{1}\left(\left\|f_{\varepsilon}\right\|_{L^{2}\left(\Omega_{\varepsilon}\right)}+\left\|q_{\varepsilon}\right\|_{H^{\frac{1}{2}}\left(\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}\right)}\right) .
$$

### 3.2.4 Weighted Sobolev Spaces

Let $\widetilde{H}_{h_{1}}\left(\Omega^{(1)}\right)$ be the closure of $C^{\infty}\left(\overline{\Omega^{(1)}}\right)$ with the norm $\|\cdot\|_{h_{1}}$, where

$$
\|\varphi\|_{h_{1}}=\sqrt{\int_{\Omega^{(1)}}\left(h_{1}(r)\left|\nabla_{\tilde{x}} \varphi\right|^{2}+\varphi^{2}\right) d x}
$$

Now consider the space $C^{\infty}\left(\overline{\Omega^{(1)}}, \partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}\right)$ of smooth functions that vanish in some subset $\Omega^{(1)} \cap R_{r_{1}-\alpha}^{r_{1}}$. We introduce the space

$$
\widetilde{H}_{h_{1}}\left(\Omega^{(1)}, \partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}\right):=\left(\overline{\left.C^{\infty}\left(\overline{\Omega^{(1)}}, \partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}\right),\|\cdot\|_{h_{1}}\right), ~}\right.
$$

i.e., it is the closure of $C^{\infty}\left(\overline{\Omega^{(1)}}, \partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}\right)$ with the weighted norm $\|\cdot\|_{h_{1}}$.

According to (3.1), we have $H^{1}\left(\Omega^{(1)}\right) \subset \widetilde{H}_{h_{1}}\left(\Omega^{(1)}\right)$ for all $\gamma>-1$, and this embedding is continuous.

The following statement shows that functions from $\widetilde{H}_{h_{1}}\left(\Omega^{(1)}, \partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}\right)$ can tend to infinity as $r \rightarrow r_{1}$ in the case $\gamma \geq 0$.
Lemma 3.5 A function $\varphi \in \widetilde{H}_{h_{1}}\left(\Omega^{(1)}\right)$ such that
(1) $|\varphi| \leq C_{6}\left|\ln \left(r_{1}-r\right)\right|^{\frac{1}{2}}$ a.e. in some domain $\Omega^{(1)} \cap R_{r_{1}-\delta}^{r_{1}}$ in the case $\gamma=0$,
(2) $|\varphi| \leq C_{6}\left(r_{1}-r\right)^{-\frac{\gamma}{2}}$ a.e. in some domain $\Omega^{(1)} \cap R_{r_{1}-\delta}^{r_{1}}$ in the case $\gamma>0$,
belongs to the weighted Sobolev space $\widetilde{H}_{h_{1}}\left(\Omega^{(1)}, \partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}\right)$.
The proof of this statement is similar to the proof of the second statement in [133, Theorem 1]. This statement implies that any function from $C^{\infty}\left(\overline{\Omega^{(1)}}\right)$ can be approximated by functions from $C^{\infty}\left(\overline{\Omega^{(1)}}, \partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}\right)$ in the norm $\|\cdot\|_{h_{1}}$.

### 3.3 Special Multivalued Extension

In this section we construct a multivalued extension of the weak solution $u_{\varepsilon}$, which preserves $H^{1}$-smoothness of the solution in the case $\gamma=0$. First we extend the solution from the thin discs $\Omega_{\varepsilon}^{(1)}$ into the domain $\Omega^{(1)}$.
Theorem 3.1 If $\gamma=0$ and conditions (2.3), (3.3), and (3.4) hold, then there exist positive constants $\varepsilon_{0}, C_{0}$, and an extension $E_{u_{\varepsilon}}^{(1)} \in H^{1}\left(\Omega_{0} \cup \Omega^{(1)}\right)$ of the weak solution $u_{\varepsilon}$ to problem (3.2) such that for all $\varepsilon \in\left(0, \varepsilon_{0}\right)$ the following inequality holds:

$$
\begin{equation*}
\left\|E_{u_{\varepsilon}}^{(1)}\right\|_{H^{1}\left(\Omega^{(1)}\right)} \leq C_{0} \tag{3.10}
\end{equation*}
$$

Proof 1. Similarly as in [32], we can show that

$$
\begin{equation*}
\left\|U_{\varepsilon}\right\|_{H^{1}\left(\Omega_{\varepsilon}\right)} \leq c_{0}\left(\left\|F_{\varepsilon}\right\|_{L^{2}\left(\Omega_{\varepsilon}\right)}+\left\|q_{\varepsilon}\right\|_{H^{\frac{3}{2}}\left(\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}\right)}\right), \tag{3.11}
\end{equation*}
$$

where $U_{\varepsilon}(x)=\varepsilon^{-1}\left(\overleftrightarrow{u_{\varepsilon}}\left(x+\varepsilon \bar{e}_{2}\right)-\overleftrightarrow{u_{\varepsilon}}(x)\right)$.
2. Let

$$
\widehat{\Omega_{\varepsilon}^{(i)}(j)}:=\left\{x \in \mathbb{R}^{3}: \varepsilon h_{i}(r) / 2 \leq x_{2}-\varepsilon\left(j+l_{i}\right) \leq \varepsilon\left(1-h_{i}(r) / 2\right)\right\} .
$$

This set is situated between two neighboring thin $\operatorname{discs} \Omega_{\varepsilon}^{(i)}(j)$ and $\Omega_{\varepsilon}^{(i)}(j+1)$.
At first, we construct the extension $E_{u_{\varepsilon}}^{(1)}$ of $u_{\varepsilon}$ into $R_{r_{0}+\varepsilon}^{r_{1}}$ with the formula

$$
E_{u_{\varepsilon}}^{(1)}(x)=a_{\varepsilon}(j, \tilde{x})+b_{\varepsilon}(j, \tilde{x})\left(x_{2}-\varepsilon\left(j+l_{1}+h_{1}(r) / 2\right)\right),
$$

for all $x \in \widetilde{\Omega_{\varepsilon}^{(i)}(j)} \cap R_{r_{0}+\varepsilon}^{r_{1}}$ and $j=-1, \ldots, N-1$, where

$$
a_{\varepsilon}(j, \tilde{x})=\overleftrightarrow{u_{\varepsilon}}\left(x_{1}, \varepsilon\left(j+l_{1}+h_{1}(r) / 2\right), x_{3}\right)
$$

$$
b_{\varepsilon}(j, \tilde{x})=\frac{1}{\varepsilon\left(1-h_{1}(r)\right)}\left(\overleftrightarrow{u_{\varepsilon}}\left(x_{1}, \varepsilon\left(j+1+l_{1}-h_{1}(r) / 2\right), x_{3}\right)-a_{\varepsilon}(j, \tilde{x})\right)
$$

We choose $\alpha$ as in the proof of Lemma 3.1 (see (3.7)). Similarly to [32], we can show that

$$
\begin{align*}
\left\|E_{u_{\varepsilon}}^{(1)}\right\|_{H^{1}\left(R_{r_{0}+\varepsilon}^{1_{1}-\alpha}\right)}^{2} \leq c_{1}\left(\alpha ^ { - 1 } \left(\left\|U_{\varepsilon}\right\|_{H^{1}\left(\Omega_{\varepsilon}^{(1)}\right)}^{2}\right.\right. & \left.+\left\|u_{\varepsilon}\right\|_{H^{1}\left(\Omega_{\varepsilon}^{(1)}\right)}^{2}\right) \\
& \left.+\left\|F_{\varepsilon}\right\|_{L^{2}\left(\Omega_{\varepsilon}^{(1)}\right)}^{2}+\left\|f_{\varepsilon}\right\|_{L^{2}\left(\Omega_{\varepsilon}^{(1)}\right)}^{2}\right) . \tag{3.12}
\end{align*}
$$

3. Direct calculations give

$$
\left\|E_{u_{\varepsilon}}^{(1)}\right\|_{H^{1}\left(\Omega_{\varepsilon}^{(i)}(j) \cap R_{\left.r_{1}-\alpha\right)}^{r_{1}}\right.}^{2} \leq c_{2} \int_{R_{r_{1}-\alpha}^{r_{1}}}\left(\varepsilon\left(a_{\varepsilon}^{2}+\left|\nabla_{\tilde{x}} a_{\varepsilon}\right|^{2}\right)+\varepsilon^{3}\left(b_{\varepsilon}^{2}+\left|\nabla_{\tilde{x}} b_{\varepsilon}\right|^{2}\right)+\varepsilon b_{\varepsilon}^{2}\right) d x .
$$

Utilizing (3.9), we prove that

$$
\begin{aligned}
\varepsilon \int_{R_{r_{1}-\alpha}^{r_{1}}} & a_{\varepsilon}^{2} d x=\left.\varepsilon \int_{R_{r_{1}-\alpha}^{r_{1}}} u_{\varepsilon}^{2}\right|_{x_{2}=\varepsilon\left(h_{1}(r) / 2+j+l_{1}\right)} d x \\
& \leq c_{3} \varepsilon\left\|\left(N_{\varepsilon}^{(1)}(r)\right)^{-\frac{1}{2}} u_{\varepsilon}\right\|_{L^{2}\left(\Omega_{\varepsilon}^{(1)}(j) \cap R_{r_{1}-\alpha}^{r_{1}}\right)}^{2} \leq c_{4}\left\|u_{\varepsilon}\right\|_{H^{1}\left(\Omega_{\varepsilon}^{(1)}(j) \cap R_{r_{1}-2 \alpha}^{r_{1}}\right)}^{2}
\end{aligned}
$$

With the help of the inequality

$$
(v(s)-v(0))^{2} \leq s \int_{0}^{s}\left(v^{\prime}(t)\right)^{2} d t \text { for all } v \in H^{1}((0, s))
$$

and (3.9) we derive that

$$
\begin{gathered}
\varepsilon \int_{R_{r_{1}-\alpha}^{r_{1}}} b_{\varepsilon}^{2} d x \leq c_{5}\left(\left\|U_{\varepsilon}\right\|_{H^{1}\left(\Omega_{\varepsilon}^{(1)}(j) \cap R_{r_{1}-2 \alpha}^{r_{1}}\right.}^{2}+\left\|u_{\varepsilon}\right\|_{H^{1}\left(\Omega_{\varepsilon}^{(1)}(j) \cap R_{r_{1}-\alpha}^{r_{1}}\right)}^{2}\right) \\
\varepsilon \int_{R_{r_{1}-\alpha}^{r_{1}}}\left|\nabla_{\tilde{x}} a_{\varepsilon}\right|^{2} d x \leq c_{6}\left\|u_{\varepsilon}\right\|_{H^{2}\left(\Omega_{\varepsilon}^{(1)}(j) \cap R_{r_{1}-2 \alpha}^{r_{1}}\right)}^{2}, \\
\varepsilon^{3} \int_{R_{r_{1}-\alpha}^{r_{1}}}\left|\nabla_{\tilde{x}} b_{\varepsilon}\right|^{2} d x \leq c_{7} \varepsilon^{2}\left(\left\|U_{\varepsilon}\right\|_{H^{2}\left(\Omega_{\varepsilon}^{(1)}(j) \cap R_{r_{1}-2 \alpha}^{r_{1}}\right)}^{2}+\left\|u_{\varepsilon}\right\|_{H^{2}\left(\Omega_{\varepsilon}^{(1)}(j) \cap R_{r_{1}-2 \alpha}^{r_{1}}\right.}^{2}\right) .
\end{gathered}
$$

Consider the smooth cutoff function

$$
\chi(r)= \begin{cases}0, & r \in\left[0, r_{0}+\delta_{0} / 3\right], \\ 1, & r \in\left[r_{0}+2 \delta_{0} / 3, r_{1}\right] .\end{cases}
$$

Taking into account the properties of the function $h_{1}$ and so-called the second energy inequality (see [52, Sect. 8.2]), we conclude that

$$
\begin{aligned}
&\left\|u_{\varepsilon}\right\|_{H^{2}\left(\Omega_{\varepsilon}^{(1)}(j) \cap R_{r_{1}-2 \alpha}^{r_{1}}\right.} \leq\left\|\chi u_{\varepsilon}\right\|_{H^{2}\left(\Omega_{\varepsilon}^{(1)}(j) \cap R_{r_{0}+\delta_{0} / \beta}^{r_{1}}\right)} \\
& \leq c_{8}\left(\left\|u_{\varepsilon}\right\|_{H^{1}\left(\Omega_{\varepsilon}^{(1)}(j)\right)}+\left\|f_{\varepsilon}\right\|_{L^{2}\left(\Omega_{\varepsilon}^{(1)}(j)\right)}\right)
\end{aligned}
$$

and

$$
\left\|U_{\varepsilon}\right\|_{H^{2}\left(\Omega_{\varepsilon}^{(1)}(j) \cap R_{r_{1}-2 \alpha}^{r_{1}}\right)} \leq c_{9}\left(\left\|U_{\varepsilon}\right\|_{H^{1}\left(\Omega_{\varepsilon}^{(1)}(j)\right)}+\left\|F_{\varepsilon}\right\|_{L^{2}\left(\Omega_{\varepsilon}^{(1)}(j)\right)}\right) .
$$

Using those inequalities, we derive the estimate

$$
\begin{equation*}
\left\|E_{u_{\varepsilon}}^{(1)}\right\|_{H^{1}\left(R_{\left.r_{1}-\alpha\right)}^{r_{1}}\right.}^{2} \leq c_{1} 0\left(\left\|u_{\varepsilon}\right\|_{H^{1}\left(\Omega_{\varepsilon}^{(1)}\right)}^{2}+\left\|U_{\varepsilon}\right\|_{H^{1}\left(\Omega_{\varepsilon}^{(1)}\right)}^{2}+\left\|f_{\varepsilon}\right\|_{L^{2}\left(\Omega_{\varepsilon}^{(1)}\right)}^{2}+\left\|F_{\varepsilon}\right\|_{L^{2}\left(\Omega_{\varepsilon}^{(1)}\right)}^{2}\right) \tag{3.13}
\end{equation*}
$$

4. Now it remains to extend $E_{u_{\varepsilon}}^{(1)}$ into $\widetilde{\Omega_{\varepsilon}^{(1)}(j)} \cap R_{r_{0}}^{r_{0}+\varepsilon}$, where $j=-1, \ldots, N-1$. Similarly as in the third part of the proof of Theorem 2 in [31], we get

$$
\begin{equation*}
\left\|E_{u_{\varepsilon}}^{(1)}\right\|_{H^{1}\left(\Omega^{(1)}\right)} \leq c_{1} 1\left(\left\|E_{u_{\varepsilon}}^{(1)}\right\|_{H^{1}\left(\Omega_{\varepsilon}^{(1)} \cup R_{r_{0}+\varepsilon}^{r_{1}}\right)}+\left\|u_{\varepsilon}\right\|_{H^{1}\left(\Omega_{0}\right)}\right) . \tag{3.14}
\end{equation*}
$$

Thus, according to (2.3), (3.3), (3.4), Lemma 3.4, (3.11), (3.12), (3.13), and (3.14) the extension $E_{u_{\varepsilon}}^{(1)}(x), x \in \Omega^{(1)}$, satisfies the estimate of Theorem 3.1.

Next we construct the extension of $u_{\varepsilon}$ from the discs from the second level into $\Omega^{(2)}$.

Theorem 3.2 If $\gamma=0$ and conditions (2.3), (3.3), and (3.4) hold, then there exist positive constants $\varepsilon_{0}, C_{1}$ and an extension $E_{u_{\varepsilon}}^{(2)} \in H^{1}\left(\Omega_{0} \cup \Omega^{(2)}\right)$ of the weak solution $u_{\varepsilon}$ to problem (3.2) such that for all $\varepsilon \in\left(0, \varepsilon_{0}\right):\left.E_{u_{\varepsilon}}^{(2)}\right|_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}}=q_{\varepsilon}$ and

$$
\left\|E_{u_{\varepsilon}}^{(2)}\right\|_{H^{1}\left(\Omega^{(2)}\right)} \leq C_{1} .
$$

Proof By the same formulas as in the second part of the proof of Theorem 3.1, we construct the extension $E_{u_{\varepsilon}}^{(2)}$ of $u_{\varepsilon}$ into the domain $R_{r_{0}+\varepsilon}^{r_{2}-\varepsilon}$ such that

$$
\begin{aligned}
& \left\|E_{u_{\varepsilon}}^{(2)}\right\|_{H^{1}\left(R_{r_{0}+\varepsilon}^{2(-\varepsilon}\right)}^{2} \\
& \quad \leq c_{1} 2\left(\left\|u_{\varepsilon}\right\|_{H^{1}\left(\Omega_{\varepsilon}^{(2)}\right)}^{2}+\left\|U_{\varepsilon}\right\|_{H^{1}\left(\Omega_{\varepsilon}^{(2)}\right)}^{2}+\left\|f_{\varepsilon}\right\|_{L^{2}\left(\Omega_{\varepsilon}^{(2)}\right)}^{2}+\left\|F_{\varepsilon}\right\|_{L^{2}\left(\Omega_{\varepsilon}^{(2)}\right)}^{2}\right) \leq c_{1} 3 .
\end{aligned}
$$

Now we extend $u_{\varepsilon}$ into the outside of $\Omega^{(2)}$. Since $q_{\varepsilon} \in H^{\frac{1}{2}}\left(\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}\right)$, then there exist a constant $a>0$ and a function $\widetilde{q}_{\varepsilon} \in H^{1}\left(R_{r_{2}}^{r_{2}+a}\right)$ such that

$$
\left.\widetilde{q}_{\varepsilon}\right|_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}}=q_{\varepsilon} \quad \text { and }\left\|\widetilde{q}_{\varepsilon}\right\|_{H^{1}\left(R_{r_{2}^{2}}^{r_{2}+a}\right)} \leq c_{1} 4\left\|q_{\varepsilon}\right\|_{H^{\frac{1}{2}\left(\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}\right)}} .
$$

We henceforth regard that $E_{u_{\varepsilon}}^{(2)}(x)=\widetilde{q}_{\varepsilon}(x)$ for $x \in R_{r_{2}}^{r_{2}+a}$. Obviously, $E_{u_{\varepsilon}}^{(2)} \in H^{1}$ $\left(\Omega_{\varepsilon}^{(2)} \cup R_{r_{0}+\varepsilon}^{r_{2}-\varepsilon} \cup R_{r_{2}}^{r_{2}+a}\right)$ and

$$
\left\|E_{u_{\varepsilon}}^{(2)}\right\|_{H^{1}\left(R_{r_{2}^{\prime 2}}^{r+a}\right)}=\left\|\widetilde{q}_{\varepsilon}\right\|_{H^{1}\left(R_{r_{2}}^{r_{2}+a}\right)} \leq c_{1} 5\left\|q_{\varepsilon}\right\|_{H^{\frac{1}{2}}\left(\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}\right)} .
$$

Now it remains to extend $E_{u_{\varepsilon}}^{(2)}$ into $\widetilde{\Omega_{\varepsilon}^{(2)}(j)} \cap R_{r_{0}}^{r_{0}+\varepsilon}$ and $\widetilde{\Omega_{\varepsilon}^{(2)}(j)} \cap R_{r_{2}-\varepsilon}^{r_{2}}, j=$ $-1, \ldots, N-1$. Again we do this similarly as in the third part of the proof of Theorem 2 in [31] and get

$$
\left\|E_{u_{\varepsilon}}^{(2)}\right\|_{H^{1}\left(\Omega_{0} \cup \Omega^{(2)}\right)} \leq c_{1} 6\left(\left\|E_{u_{\varepsilon}}^{(2)}\right\|_{H^{1}\left(\Omega_{\varepsilon}^{(2)} \cup R_{r_{0}+\varepsilon}^{(2-\varepsilon} \cup R_{r_{2}}^{(2+a}\right)}+\left\|u_{\varepsilon}\right\|_{H^{1}\left(\Omega_{0}\right)}\right) .
$$

Thus, the desired extension is the restriction of $\left.E_{u_{\varepsilon}}^{(2)}\right|_{\Omega_{0} \cup \Omega^{(2)}}$.

With the help of the constructed extensions $E_{u_{\varepsilon}}^{(1)}$ and $E_{u_{\varepsilon}}^{(2)}$ we define a multivalued extension

$$
\begin{equation*}
\mathbf{E}_{u_{\varepsilon}}:=\left(\left.u_{\varepsilon}\right|_{\Omega_{0}},\left.E_{u_{\varepsilon}}^{(1)}\right|_{\Omega^{(1)}},\left.E_{u_{\varepsilon}}^{(2)}\right|_{\Omega^{(2)}}\right) \tag{3.15}
\end{equation*}
$$

of the solution $u_{\varepsilon}$ to problem (3.2), which belongs to the anisotropic Sobolev space of multivalued functions

$$
\begin{gathered}
\mathbf{H}_{\mathrm{per}}^{1}=\left\{\mathbf{p}=\left(p_{0}, p_{1}, p_{2}\right): p_{0} \in H_{\mathrm{per}}^{1}\left(\Omega_{0}\right), \quad p_{i} \in H^{1}\left(\Omega^{(i)}\right), \quad i=1,2,\right. \\
\left.\left.p_{0}\right|_{\Omega^{\prime}}=\left.p_{1}\right|_{\Omega^{\prime}}=\left.p_{2}\right|_{\Omega^{\prime}}\right\}
\end{gathered}
$$

with the scalar product

$$
(\mathbf{p}, \mathbf{q})_{\mathbf{H}_{\mathrm{per}}^{\mathrm{p}}}=\int_{\Omega_{0}}\left(\nabla_{x} p_{0} \cdot \nabla_{x} q_{0}+p_{0} q_{0}\right) d x+\sum_{i=1}^{2} \int_{\Omega^{(i)}}\left(\nabla_{x} p_{i} \cdot \nabla_{x} q_{i}+p_{i} q_{i}\right) d x
$$

where $\mathbf{p}=\left(p_{0}, p_{1}, p_{2}\right), \mathbf{q}=\left(q_{0}, q_{1}, q_{2}\right) \in \mathbf{H}_{\text {per }}^{1}$.
Lemma 3.4, Theorems 3.1, and 3.2 imply that in the case $\gamma=0$ there exist positive constants $\varepsilon_{0}, C_{2}$ such that for all $\varepsilon \in\left(0, \varepsilon_{0}\right)$ the multivalued extension $\mathbf{E}_{u_{\varepsilon}}$ of the solution $u_{\varepsilon}$ to problem (3.2) satisfies the inequality

$$
\begin{equation*}
\left\|\mathbf{E}_{u_{\varepsilon}}\right\|_{\mathbf{H}_{\text {per }}^{\prime}} \leq C_{2} \tag{3.16}
\end{equation*}
$$

where $\|\cdot\|_{\mathbf{H}_{\text {per }}^{1}}$ is a norm in $\mathbf{H}_{\text {per }}^{1}$ produced by the scalar product $(\cdot, \cdot)_{\mathbf{H}_{\text {per }}^{1}}$.

### 3.4 Convergence Theorems

### 3.4.1 The Case of Rounded Edges

Consider a space $H_{\text {per }}^{1}\left(\Omega_{0}\right)=\left\{\varphi \in H^{1}\left(\Omega_{0}\right): \varphi\left(x_{1}, 0, x_{3}\right)=\varphi\left(x_{1}, l, x_{3}\right), r<r_{0}\right\}$ and a space of multivalued functions

$$
\widetilde{\mathbf{H}}_{\mathrm{per}}=\left\{\mathbf{p}=\left(p_{0}, p_{1}, p_{2}\right) \in \widetilde{\mathbf{H}}: p_{0} \in H_{\mathrm{per}}^{1}\left(\Omega_{0}\right)\right\}
$$

(see definition of $\widetilde{\mathbf{H}}$ in Sect. 2.3.1).
Theorem 3.3 If $\gamma \in(-1,0)$, then

$$
\left.\begin{array}{rl}
u_{\varepsilon} & \xrightarrow{w} u_{0}  \tag{3.17}\\
{\text { weakly in } H^{1}\left(\Omega_{0}\right),}^{\widetilde{u}_{\varepsilon}^{(1)}} \xrightarrow{w} h_{1} u_{1} & \text { weakly in } L^{2}\left(\Omega^{(1)}\right), \\
\tilde{u}_{\varepsilon}^{(2)} & \xrightarrow{w} h_{2} u_{2} \\
\text { weakly in } L^{2}\left(\Omega^{(2)}\right)
\end{array}\right\} \text { as } \varepsilon \rightarrow 0,
$$

where $u_{\varepsilon}$ is the weak solution to problem (3.2) and the multivalued function $\mathbf{u}=$ $\left(u_{0}, u_{1}, u_{2}\right) \in \widetilde{\mathbf{H}}_{\text {per }}$ is a unique weak solution to the problem

$$
\begin{cases}-\Delta_{x} u_{0}=f_{0}, & x \in \Omega_{0},  \tag{3.18}\\ \partial_{x_{2}}^{p} u_{0}\left(x_{1}, 0, x_{3}\right)=\partial_{x_{2}}^{p} u_{0}\left(x_{1}, l, x_{3}\right), & p=0,1, x \in \partial \Omega_{0} \cap\left\{r<r_{0}\right\}, \\ -\div \tilde{x}\left(h_{1}(r) \nabla_{\tilde{x}} u_{1}\right)=h_{1}(r) f_{0}, & x \in \Omega^{(1)}, \\ \partial_{v} u_{1}=0, & x \in \partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}, \\ -h_{2} \Delta_{\tilde{x}} u_{2}+2 \kappa u_{2}=h_{2} f_{0}, & x \in \Omega^{(2)}, \\ u_{2}=q_{0}, & x \in \partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}, \\ u_{0}=u_{1}=u_{2}, & x \in \Omega^{\prime}, \\ \partial_{r} u_{0}=h_{1}\left(r_{0}\right) \partial_{r} u_{1}+h_{2} \partial_{r} u_{2}, & x \in \Omega^{\prime} .\end{cases}
$$

To give the definition of a weak solution to problem (3.18), we introduce an anisotropic weighted Sobolev space of multivalued functions

$$
\begin{gathered}
\widetilde{\mathbf{H}}_{h_{1}, \mathrm{per}}=\left\{\mathbf{p}=\left(p_{0}, p_{1}, p_{2}\right): p_{0} \in H_{\mathrm{per}}^{1}\left(\Omega_{0}\right), p_{1} \in \widetilde{H}_{h_{1}}\left(\Omega^{(1)}\right), p_{2} \in \widetilde{H}^{1}\left(\Omega^{(2)}\right)\right. \\
\left.\left.p_{0}\right|_{\Omega^{\prime}}=\left.p_{1}\right|_{\Omega^{\prime}}=\left.p_{2}\right|_{\Omega^{\prime}}\right\}
\end{gathered}
$$

equipped with the scalar product

$$
\begin{aligned}
(\mathbf{p}, \mathbf{q})_{\tilde{\mathbf{H}}_{1_{1}, \text { per }}} & =\int_{\Omega_{0}} \nabla_{x} p_{0} \cdot \nabla_{x} q_{0} d x+\int_{\Omega^{(1)}} h_{1}(r) \nabla_{\tilde{x}} p_{1} \cdot \nabla_{\tilde{x}} q_{1} d x \\
& +\int_{\Omega^{(2)}}\left(h_{2} \nabla_{\tilde{x}} p_{2} \cdot \nabla_{\tilde{x}} q_{2}+2 \kappa p_{2} q_{2}\right) d x
\end{aligned}
$$

and a linear functional

$$
\begin{equation*}
\mathrm{L}(\mathbf{p}):=\int_{\Omega_{0}} f_{0} p_{0} d x+\int_{\Omega^{(1)}} h_{1}(r) f_{0} p_{1} d x+h_{2} \int_{\Omega^{(2)}} f_{0} p_{2} d x, \quad \mathbf{p} \in \widetilde{\mathbf{H}}_{h_{1}, \mathrm{per}} \tag{3.19}
\end{equation*}
$$

According to (3.1), the embedding $\widetilde{\mathbf{H}}_{\text {per }} \subset \widetilde{\mathbf{H}}_{h_{1}, \text { per }}$ takes place.
Definition 3.3 $[\gamma \in(-1,0)]$ A multivalued function $\mathbf{u}=\left(u_{0}, u_{1}, u_{2}\right) \in \widetilde{\mathbf{H}}_{h_{1}, \text { per }}$ is called a weak solution to problem (3.18) if $\left.u_{2}\right|_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}}=q_{0}$ and

$$
\begin{equation*}
(\mathbf{u}, \mathbf{p})_{\widetilde{\mathbf{H}}_{h_{1}, \mathrm{per}}}=\mathrm{L}(\mathbf{p}) \quad \forall \mathbf{p}=\left(p_{0}, p_{1}, p_{2}\right) \in \widetilde{\mathbf{H}}_{h_{1}, \mathrm{per}},\left.\quad p_{2}\right|_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}}=0 \tag{3.20}
\end{equation*}
$$

Proof 1. Similarly as in the third part of the proof of Theorem 3.1, we prove that

$$
\left\|u_{\varepsilon}\right\|_{H^{2}\left(\Omega_{\varepsilon}^{(1)} \cap R_{r_{1}-\delta_{1}}^{r_{1}}\right)} \leq c_{0}\left(\left\|f_{\varepsilon}\right\|_{L^{2}\left(\Omega_{\varepsilon}^{(1)}\right)}+\left\|u_{\varepsilon}\right\|_{H^{1}\left(\Omega_{\varepsilon}^{(1)}\right)}\right) .
$$

According to this estimate, (3.1), Lemmas 3.2 and 3.4, the quantities
$\left\|u_{\varepsilon}\right\|_{H^{1}\left(\Omega_{0}\right)},\left\|h_{1}^{-1} \widetilde{u}_{\varepsilon}^{(1)}\right\|_{L^{2}\left(\Omega^{(1)}\right)},\left\|h_{1}^{-1}{\widetilde{\partial_{x_{k}} u_{\varepsilon}}}^{(1)}\right\|_{L^{2}\left(\Omega^{(1)}\right)},\left\|\widetilde{u}_{\varepsilon}^{(i)}\right\|_{L^{2}\left(\Omega^{(i)}\right)},\left\|{\widetilde{\partial_{x_{k}} u_{\varepsilon}}}_{(i)}\right\|_{L^{2}\left(\Omega^{(i)}\right)}$
are uniformly bounded with respect to $\varepsilon(i=1,2, k=1,2,3)$. Hence there exists a subsequence $\left\{\varepsilon^{\prime}\right\} \subset\{\varepsilon\}$ (again denoted by $\{\varepsilon\}$ ) such that
where the limits remain unknown and will be defined later.
Obviously, $u_{0} \in H_{\text {per }}^{1}\left(\Omega_{0}\right)$. It is easy to verify that $\widetilde{u}_{1}=h_{1}(r) u_{1}$ and $\widetilde{u}_{1, k}=$ $h_{1}(r) u_{1, k}$ a.e. in $\Omega^{(1)}, k=1,2,3$.
2. Repeating the assertions of the proof of Theorem 2.1, we can show that

- $u_{i, 2}=0$ a.e. in $\Omega^{(i)}, i=1,2$;
- there exist weak derivatives $\partial_{x_{k}} u_{i}=u_{i, k}$ for a.e. $x \in \Omega^{(i)}, i=1,2, k=1,3$;
- $\left.u_{0}\right|_{\Omega^{\prime}}=\left.u_{1}\right|_{\Omega^{\prime}}=\left.u_{2}\right|_{\Omega^{\prime}}$.

According to (2.28) and the Dirichlet boundary conditions on $\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}$, the integral identity

$$
\int_{\Omega_{\varepsilon}^{(2)}} r^{-1} \partial_{r}\left(u_{\varepsilon} \psi\right) d x=r_{2}^{-1} \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}} u_{\varepsilon} \psi d \sigma_{x}=r_{2}^{-1} \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}} q_{\varepsilon} \psi d \sigma_{x}
$$

holds for any $\psi \in C^{\infty}\left(\overline{\Omega^{(2)}}\right),\left.\psi\right|_{\Omega^{\prime}}=0$. Passing to the limit in this identity as $\varepsilon \rightarrow 0$ and taking into account (3.21), (3.4), and (2.16), we obtain
$h_{2} \int_{\Omega^{(2)}} r^{-1} \partial_{r}\left(u_{2}^{-} \psi\right) d x=h_{2} r_{2}^{-1} \int_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}} q_{0} \psi d \sigma_{x} \quad \forall \psi \in C^{\infty}\left(\overline{\Omega^{(2)}}\right),\left.\psi\right|_{\Omega^{\prime}}=0$,
whence integrating by parts, we derive that

$$
h_{2} r_{2}^{-1} \int_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}} u_{2} \psi d \sigma_{x}=h_{2} r_{2}^{-1} \int_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}} q_{0} \psi d \sigma_{x} \quad \forall \psi \in C^{\infty}\left(\overline{\Omega^{(2)}}\right),\left.\psi\right|_{\Omega^{\prime}}=0,
$$

i.e.,

$$
\begin{equation*}
\left.u_{2}\right|_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}}=q_{0} . \tag{3.22}
\end{equation*}
$$

3. Using the functions $u_{0}, u_{1}, u_{2}$, we define a multivalued function $\mathbf{u}=\left(u_{0}, u_{1}, u_{2}\right)$. It is clear that $\mathbf{u} \in \widetilde{\mathbf{H}}_{\text {per }}$. With the help of (3.6) we rewrite (3.5) in
a form

$$
\begin{align*}
& \int_{\Omega_{0}} \nabla_{x} u_{\varepsilon} \cdot \nabla_{x} p_{0} d x+\sum_{i=1}^{2} \int_{\Omega^{(i)}}{\widetilde{\nabla_{x}} u_{\varepsilon}^{(i)} \cdot \nabla_{x} p_{i} d x+\frac{2 \kappa}{h_{2}} \int_{\Omega^{(2)}} \widetilde{u}_{\varepsilon}^{(2)} p_{2} d x}^{-\frac{2 \kappa \varepsilon}{h_{2}} \int_{\Omega_{\varepsilon}^{(2)}} Y_{1}\left(\frac{x_{2}}{\varepsilon}\right) \partial_{x_{2}}\left(u_{\varepsilon} p_{2}\right) d x=\int_{\Omega_{0}} f_{\varepsilon} p_{0} d x+\sum_{i=1}^{2} \int_{\Omega^{(i)}} \chi_{\Omega_{\varepsilon}^{(i)}} f_{\varepsilon} p_{i} d x,}
\end{align*}
$$

where $\mathbf{p}=\left(p_{0}, p_{1}, p_{2}\right)$ is an arbitrary function from

$$
\begin{aligned}
\mathbf{C}_{\text {per }}^{\infty}\left(\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}\right):= & \left\{\mathbf{p}=\left(p_{0}, p_{1}, p_{2}\right) \in \widetilde{\mathbf{H}}_{\text {per }}^{1}: p_{0} \in C^{\infty}\left(\bar{\Omega}_{0}\right), p_{1} \in C^{\infty}\left(\overline{\Omega^{(1)}}\right),\right. \\
& \left.p_{2} \in C^{\infty}\left(\overline{\Omega^{(2)}}, \partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}\right)\right\} .
\end{aligned}
$$

Passing to the limit in (3.23) and taking (2.3), (3.21), and (2.16) into account, we obtain the identity

$$
(\mathbf{u}, \mathbf{p})_{\widetilde{\mathbf{H}}_{k_{1}, \text { per }}}=\mathrm{L}(\mathbf{p}) \quad \forall \mathbf{p} \in \mathbf{C}_{\text {per }}^{\infty}\left(\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}\right)
$$

where the functional L is defined in (3.19). Since $\mathbf{C}_{\text {per }}^{\infty}\left(\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}\right)$ is dense in the space of functions from $\widetilde{\mathbf{H}}_{h_{1} \text {,per }}$ such that $\left.p_{2}\right|_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}}=0$, we arrive at (3.20).
4. Let us verify that the functional $L$ is bounded, i.e.,

$$
|L(\mathbf{p})| \leq c_{5}\|\mathbf{p}\|_{\tilde{\mathbf{H}}_{h_{1}, \text { per }}} \quad \forall \mathbf{p}=\left(p_{0}, p_{1}, p_{2}\right) \in \widetilde{\mathbf{H}}_{h_{1}, \text { per }},\left.\quad p_{2}\right|_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}}=0
$$

where $\|\cdot\|_{\widetilde{\mathbf{H}}_{h_{1} \text { per }}}$ is a norm produced by the scalar product $(\cdot, \cdot)_{\widetilde{\mathbf{H}}_{h_{1}, \text { per }}}$. This together with (3.22) will imply that $\mathbf{u}$ is a unique weak solution to problem (3.18).

Obvious inequalities

$$
\int_{\Omega_{0}} p_{0}^{2} d x \leq c_{1}\left(\left\|p_{0}\right\|_{L^{2}\left(\Omega^{\prime}\right)}^{2}+\int_{\Omega_{0}}\left|\nabla_{\tilde{x}} p_{0}\right|^{2} d x\right)
$$

and

$$
\left\|p_{0}\right\|_{L^{2}\left(\Omega^{\prime}\right)}^{2}=\left\|p_{1}\right\|_{L^{2}\left(\Omega^{\prime}\right)}^{2}=\left\|p_{2}\right\|_{L^{2}\left(\Omega^{\prime}\right)}^{2} \leq c_{2} \int_{\Omega^{(2)}}\left(\left|\nabla_{\tilde{x}} p_{2}\right|^{2}+p_{2}^{2}\right) d x
$$

provide that

$$
\begin{equation*}
\left|\int_{\Omega_{0}} f_{0} p_{0} d x\right| \leq c_{3}\left\|f_{0}\right\|_{L^{2}\left(\Omega_{0}\right)}\|\mathbf{p}\|_{\widetilde{\mathbf{H}}_{h_{1}, \text { per }}} \tag{3.24}
\end{equation*}
$$

The second summand in (3.19) is estimated with the help of the Cauchy-Schwartz-Bunyakovsky inequality:

$$
\left|\int_{\Omega^{(1)}} h_{1}(r) f_{0} p_{1} d x\right| \leq c_{4}\left\|f_{0}\right\|_{L^{2}\left(r_{1}\right)}\left(\int_{\Omega^{(1)}} h_{1}(r) p_{1}^{2} d x\right)^{\frac{1}{2}}
$$

It is easy to see that

$$
\int_{\Omega^{(1)}} h_{1}(r) p_{1}^{2} d x \leq c_{5}\left(\left\|p_{1}\right\|_{L^{2}\left(\Omega^{\prime}\right)}^{2}+\int_{\Omega^{(1)}} h_{1}(r) \int_{r_{0}}^{r}\left(\left.\partial_{\xi} p_{1}\right|_{r=\xi}\right)^{2} d \xi d x\right)
$$

Using (3.1), we derive the estimate

$$
\int_{\Omega^{(1)}} \int_{r}^{r_{1}} h_{1}(\xi)\left(\partial_{r} p_{1}\right)^{2} d \xi d x \leq c_{5} \int_{\Omega^{(1)}} h_{1}(r)\left|\nabla_{\tilde{x}} p_{1}\right|^{2} d x .
$$

The last inequality and the Fubini theorem imply that

$$
\int_{\Omega^{(1)}} h_{1}(r) \int_{r_{0}}^{r}\left(\left.\partial_{\xi} p_{1}\right|_{r=\xi}\right)^{2} d \xi d x \leq c_{6} \int_{\Omega^{(1)}} h_{1}(r)\left|\nabla_{\tilde{x}} p_{1}\right|^{2} d x
$$

Taking into account (3.24) and the obtained inequalities, we conclude that

$$
\begin{equation*}
\left|\int_{\Omega^{(1)}} h_{1}(r) f_{0} p_{1} d x\right| \leq c_{7}\left\|f_{0}\right\|_{L^{2}\left(\Omega^{(1)}\right)}\|\mathbf{p}\|_{\widetilde{\mathbf{H}}_{h_{1}, \text { per }}} \tag{3.25}
\end{equation*}
$$

Understandably that the third summand in identity (3.19) can be estimated by $c_{8}\left\|f_{0}\right\|_{L^{2}\left(\Omega^{(2)}\right)}\|\mathbf{p}\|_{\tilde{\mathbf{H}}_{h_{1}, \text { per }}}$. This estimate together with (3.24) and (3.25) give the boundedness of $L$.
5. Since all of the above assertions remain valid for an arbitrary subsequence $\left\{\varepsilon^{\prime}\right\}$ chosen at the beginning of the proof, the uniqueness of a weak solution to problem (3.18) implies that relations (3.17) hold for the whole sequence $\{\varepsilon\}$.

### 3.4.2 The Case of Wedge Edges

Theorem 3.4 If $\gamma=0$, then the extension $\mathbf{E}_{u_{\varepsilon}}=\left(\left.u_{\varepsilon}\right|_{\Omega_{0}},\left.E_{u_{\varepsilon}}^{(1)}\right|_{\Omega^{(1)}},\left.E_{u_{\varepsilon}}^{(2)}\right|_{\Omega^{(2)}}\right)$ defined in (3.15) of the weak solution $u_{\varepsilon}$ to problem (3.2) satisfies the relations

$$
\begin{gather*}
\mathbf{E}_{u_{\varepsilon}} \xrightarrow{w} \mathbf{u} \text { weakly in } \mathbf{H}_{\mathrm{per}}^{1} \text { as } \varepsilon \rightarrow 0,  \tag{3.26}\\
\lim _{\mu \rightarrow 0} \lim _{\varepsilon \rightarrow 0} \int_{\partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}}\left(\left.E_{u_{\varepsilon}}^{(1)}\right|_{r=r_{1}-\mu}-\left.u_{1}\right|_{r=r_{1}}\right)^{2} d \sigma_{x}=0, \tag{3.27}
\end{gather*}
$$

where the multivalued function $\mathbf{u}=\left(u_{0}, u_{1}, u_{2}\right) \in \mathbf{H}_{\mathrm{per}}^{1}$ is a unique weak solution to the problem

$$
\begin{cases}-\Delta_{x} u_{0}=f_{0}, & x \in \Omega_{0},  \tag{3.28}\\ \partial_{x_{2}}^{p} u_{0}\left(x_{1}, 0, x_{3}\right)=\partial_{x_{2}}^{p} u_{0}\left(x_{1}, l, x_{3}\right), & p=0,1, x \in \partial \Omega_{0} \cap\left\{r<r_{0}\right\}, \\ -\div \tilde{x}\left(h_{1}(r) \nabla_{\tilde{x}} u_{1}\right)=h_{1}(r) f_{0}, & x \in \Omega^{(1)}, \\ -h_{2} \Delta_{\tilde{x}} u_{2}+2 \kappa u_{2}=h_{2} f_{0}, & x \in \Omega^{(2)}, \\ u_{2}=q_{0}, & x \in \partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}, \\ u_{0}=u_{1}=u_{2}, & x \in \Omega^{\prime}, \\ \partial_{r} u_{0}=h_{1}\left(r_{0}\right) \partial_{r} u_{1}+h_{2} \partial_{r} u_{2}, & x \in \Omega^{\prime} .\end{cases}
$$

Remark 3.4 The convergence (3.27) was introduced by Mikhailov in [116, Ch. IV].
Remark 3.5 If $\gamma \geq 0$, then due to Lemma 3.5, the embedding

$$
\begin{equation*}
C^{\infty}\left(\overline{\Omega^{(1)}}\right) \subset \widetilde{H}_{h_{1}}\left(\Omega^{(1)}, \partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}\right) \tag{3.29}
\end{equation*}
$$

takes place. This means that $\widetilde{H}_{h_{1}}\left(\Omega^{(1)}\right)=\widetilde{H}_{h_{1}}\left(\Omega^{(1)}, \partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}\right)$. Thus, the definition of a weak solution to problem (3.28) coincides with Definition 3.3. As a consequence, problem (3.28) has a unique weak solution.

The embedding (3.29) also implies that there is no need for any boundary conditions on $\partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}$ for uniqueness of a weak solution to problem (3.28) (the similar situation was in [133, §3] and [123]).

However, in the case $\gamma=0$ we will prove in Theorem 3.4 that the weak solution belongs to $\mathbf{H}_{\mathrm{per}}^{1}$ and, as a consequence, has a finite trace on $\partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}$ (see (3.27)).

Proof 1. With the help of (3.16), we can prove that there exists a subsequence $\left\{\varepsilon^{\prime}\right\} \subset\{\varepsilon\}$ (again denoted by $\{\varepsilon\}$ ) such that

$$
\left.\begin{array}{rl}
\mathbf{E}_{u_{\varepsilon}} & \xrightarrow{w} \mathbf{u}:=\left(u_{0}, u_{1}, u_{2}\right)  \tag{3.30}\\
\chi_{\Omega_{\varepsilon}^{(i)}} \partial_{x_{k}} E_{u_{\varepsilon}}^{(i)} \xrightarrow{w} u_{i, k} & \text { weakly in } \mathbf{H}_{\mathrm{per}}^{1}, \\
\text { weakly in } L^{2}\left(\Omega^{(i)}\right)
\end{array}\right\} \quad \text { as } \varepsilon \rightarrow 0,
$$

where $u_{0}, u_{i}, u_{i, k}, k=1,2,3, i=1,2$, will be defined later. From (3.4) and Theorem 3.2, it follows that $\left.u_{2}\right|_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}}=q_{0}$.

Compactness of the embedding $H^{1}\left(\Omega^{(i)}\right) \subset L^{2}\left(\Omega^{(i)}\right)$ and relations (2.16) and (3.30) imply that

$$
\left.\begin{array}{l}
\chi_{\Omega_{\varepsilon}^{(1)}} E_{u_{\varepsilon}}^{(1)} \xrightarrow{w} h_{1} u_{1} \text { weakly in } L^{2}\left(\Omega^{(1)}\right),  \tag{3.31}\\
\chi_{\Omega_{\varepsilon}^{(2)}} E_{u_{\varepsilon}}^{(2)} \xrightarrow{w} h_{2} u_{2} \text { weakly in } L^{2}\left(\Omega^{(2)}\right)
\end{array}\right\} \quad \text { as } \varepsilon \rightarrow 0 .
$$

2. Similarly as in the second part of the proof of Theorem 2.1, we show that $u_{i, 2}=0$ a.e. in $\Omega^{(i)}, i=1,2$. Next let us find $u_{i, 1}$ and $u_{i, 3}, i=1,2$.

By the same way as the identity (2.27) was proved, we deduce

$$
\begin{aligned}
& \int_{\Omega^{(1)}} \chi_{\Omega_{\varepsilon}^{(1)}} \partial_{x_{k}} E_{u_{\varepsilon}}^{(1)} \psi d x=-\int_{\Omega^{(1)}} \chi_{\Omega_{\varepsilon}^{(1)}} E_{u_{\varepsilon}}^{(1)}\left(\partial_{x_{k}} \psi+\partial_{x_{k}} \ln h_{1}(r) \psi\right) d x \\
& \quad+\varepsilon \int_{\Omega_{\varepsilon}^{(1)}} Y_{1}\left(\frac{x_{2}}{\varepsilon}\right) \partial_{x_{k}} \ln h_{1}(r) \partial_{x_{2}}\left(u_{\varepsilon} \psi\right) d x \quad \forall \psi \in C_{0}^{\infty}\left(\Omega^{(1)}\right), k=1,3 .
\end{aligned}
$$

Passing to the limit in this identity as $\varepsilon \rightarrow 0$ and taking (3.30) and (3.31) into account, we get the identity

$$
\int_{\Omega^{(1)}} u_{1, k} \psi d x=-\int_{\Omega^{(1)}} u_{1} \partial_{x_{k}}\left(h_{1}(r) \psi\right) d x \quad \forall \psi \in C_{0}^{\infty}\left(\Omega^{(1)}\right), k=1,3,
$$

which implies that $u_{1, k}=h_{1}(r) \partial_{x_{k}} u_{1}$ a.e. in $\Omega^{(1)}, k=1,3$. Similarly with the help of (3.6) we have that $u_{2, k}=h_{2} \partial_{x_{k}} u_{2}$ a.e. in $\Omega^{(2)}, k=1,3$.
3. Let us prove convergence (3.27). Let $\mu$ be any fixed number from ( $0, \frac{r_{1}-r_{0}}{4}$ ). Properties of the trace operator and the first relation in (3.30) imply that

$$
\left.\left.E_{u_{\varepsilon}}^{(1)}\right|_{\left\{r=r_{1}-\mu\right\}} \longrightarrow u_{1}\right|_{\left\{r=r_{1}-\mu\right\}} \text { strongly in } L^{2}\left(\left\{r=r_{1}-\mu\right\}\right) \text { as } \varepsilon \rightarrow 0 .
$$

This convergence and the inequality

$$
\left(\left.u_{1}\right|_{r=r_{1}-\mu}-\left.u_{1}\right|_{r=r_{1}}\right)^{2} \leq \mu \int_{r_{1}-\mu}^{r_{1}}\left(\partial_{r} u_{1}\right)^{2} d r
$$

provide convergence (3.27):

$$
\left\|\left.u_{1}\right|_{r=r_{1}-\mu}-\left.u_{1}\right|_{r=r_{1}}\right\|_{L^{2}\left(\partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}\right)} \leq c_{0} \mu^{\frac{1}{2}}\left\|u_{1}\right\|_{H^{1}\left(\Omega^{(1)}\right)} \longrightarrow 0 \text { as } \mu \rightarrow 0 .
$$

4. Utilizing (3.6) and the extension $\mathbf{E}_{u_{\varepsilon}}$, we rewrite identity (3.5) as follows

$$
\begin{align*}
& \int_{\Omega_{0}} \nabla_{x} u_{\varepsilon} \cdot \nabla_{x} p_{0} d x+\sum_{i=1}^{2} \int_{\Omega^{(i)}} \chi_{\Omega_{\varepsilon}^{(i)}} \nabla_{x} E_{u_{\varepsilon}}^{(i)} \cdot \nabla_{x} p_{i} d x+\frac{2 \kappa}{h_{2}} \int_{\Omega^{(2)}} \chi_{\Omega_{\varepsilon}^{(2)}} E_{u_{\varepsilon}}^{(2)} p_{2} d x \\
& -\frac{2 \kappa \varepsilon}{h_{2}} \int_{\Omega_{\varepsilon}^{(2)}} Y_{1}\left(\frac{x_{2}}{\varepsilon}\right) \partial_{x_{2}}\left(u_{\varepsilon} p_{2}\right) d x=\int_{\Omega_{0}} f_{\varepsilon} p_{0} d x+\sum_{i=1}^{2} \int_{\Omega^{(i)}} \chi_{\Omega_{\varepsilon}^{(i)}} f_{\varepsilon} p_{i} d x \tag{3.32}
\end{align*}
$$

with arbitrary multivalued test function $\mathbf{p}=\left(p_{0}, p_{1}, p_{2}\right)$ from the space

$$
\begin{array}{r}
\mathbf{C}_{\mathrm{per}}^{\infty}\left(\partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}, \partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}\right):=\left\{\mathbf{p}=\left(p_{0}, p_{1}, p_{2}\right) \in \mathbf{H}_{\mathrm{per}}^{1}:\right. \\
\left.p_{0} \in C^{\infty}\left(\overline{\Omega_{0}}\right), p_{i} \in C^{\infty}\left(\overline{\Omega^{(i)}}, \partial \Omega^{(i)} \cap\left\{r=r_{i}\right\}\right), i=1,2\right\} .
\end{array}
$$

Taking (2.3), (2.16), (3.30), and (3.31) into account and passing to the limit in (3.32), we derive the following identity:

$$
(\mathbf{u}, \mathbf{p})_{\widetilde{\mathbf{H}}_{h_{1}, \text { per }}}=\mathrm{L}(\mathbf{p}) \quad \forall \mathbf{p} \in \mathbf{C}_{\text {per }}^{\infty}\left(\partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}, \partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}\right) .
$$

Since $\mathbf{u} \in \mathbf{H}_{\text {per }}^{1}$, then the last identity remains valid for all $\mathbf{p}=\left(p_{0}, p_{1}, p_{2}\right) \in \widetilde{\mathbf{H}}_{h_{1}, \text { per }}$ such that $\left.p_{2}\right|_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}}=0$ (see Remark 3.5). Thus, $\mathbf{u} \in \mathbf{H}_{\text {per }}^{1}$ is a unique weak solution to problem (3.28).
5. Since all of the above assertions remain valid for arbitrary subsequence $\left\{\varepsilon^{\prime}\right\}$ chosen at the beginning of the proof, the uniqueness of a weak solution to problem (3.28) implies that relations (3.26) and (3.27) hold for the whole sequence $\{\varepsilon\}$.

### 3.4.3 The Case of Very Sharp Edges

The existence and uniqueness of the weak solution to problem (3.2) in the case $\gamma>0$ and some of its properties are justified in Remark 3.5.

We introduce a space $L_{\alpha}^{2}\left(\Omega^{(1)}\right):=\left\{\varphi \in L^{2}\left(\Omega^{(1)}\right):\left\|\left(r_{1}-r\right)^{\frac{\alpha}{2}} \varphi\right\|_{L^{2}\left(\Omega^{(1)}\right)}<\infty\right\}$, where $\alpha \in \mathbb{R}$, and a weighted Sobolev space of multivalued functions

$$
\begin{aligned}
\widetilde{\mathbf{H}}_{\gamma}:= & \left\{\mathbf{p}=\left(p_{0}, p_{1}, p_{2}\right): p_{0} \in H_{\mathrm{per}}^{1}\left(\Omega_{0}\right),\right. \\
& p_{1} \in L_{2 \gamma}^{2}\left(\Omega^{(1)}\right), \exists \partial_{x_{k}} p_{1} \in L_{2(1+\gamma)}^{2}\left(\Omega^{(1)}\right), k=1,3, \\
& \left.p_{2} \in \widetilde{H}^{1}\left(\Omega^{(2)}\right),\left.\quad p_{0}\right|_{\Omega^{\prime}}=\left.p_{1}\right|_{\Omega^{\prime}}=\left.p_{2}\right|_{\Omega^{\prime}}\right\} .
\end{aligned}
$$

Theorem 3.5 If $\gamma>0$, then there exists a subsequence $\left\{\varepsilon^{\prime}\right\} \subset\{\varepsilon\}$ such that the weak solution $u_{\varepsilon^{\prime}}$ to problem (3.2) satisfies the relations

$$
\left.\begin{array}{rl}
u_{\varepsilon^{\prime}}  \tag{3.33}\\
\tilde{u}_{\varepsilon^{\prime}}^{(1)} & \xrightarrow{w} u_{0} \\
h_{1} u_{1} & \text { weakly in } H^{1}\left(\Omega_{0}\right), \\
\tilde{u}_{\varepsilon^{\prime}}^{(2)} \xrightarrow{w} h_{2} u_{2} & \text { weakly in } L^{2}\left(\Omega^{(1)}\right),
\end{array}\right\} \text { as } \varepsilon^{\prime} \rightarrow 0
$$

where the multivalued function $\mathbf{u}:=\left(u_{0}, u_{1}, u_{2}\right)$ belongs to the space $\widetilde{\mathbf{H}}_{\gamma}$ and satisfies the following relations: $\left.u_{2}\right|_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}}=q_{0}$ and

$$
\begin{equation*}
(\mathbf{u}, \mathbf{p})_{\widetilde{\mathbf{H}}_{l_{1}, \text { per }}}=\mathrm{L}(\mathbf{p}) \tag{3.34}
\end{equation*}
$$

for all $\mathbf{p}=\left(p_{0}, p_{1}, p_{2}\right) \in \widetilde{\mathbf{H}}_{h_{1}, \text { per }}$ such that $p_{1}=0$ in some neighborhood of $\partial \Omega^{(1)} \cap$ $\left\{r=r_{1}\right\}$ (not necessarily the same for all functions) and $\left.p_{2}\right|_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}}=0$.

Proof Similarly as in [123, Lemma 4.1] we can prove that

$$
\left\|\left(r_{1}-r\right)^{-1} \varphi\right\|_{L^{2}\left(\Omega_{\varepsilon}^{(1)}\right)} \leq c_{0}\|\varphi\|_{H^{1}\left(\Omega_{\varepsilon}\right)} \quad \forall \varphi \in H_{\mathrm{per}}^{1}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{1}\right\}\right)
$$

According to Lemma 3.4 and the last estimate the quantities
where $i=\{1,2\}, k \in\{1,2,3\}$, are bounded uniformly with respect to $\varepsilon$. Thus, there exists a subsequence $\left\{\varepsilon^{\prime}\right\} \subset\{\varepsilon\}$ (again denoted by $\{\varepsilon\}$ ) such that

$$
\left.\begin{array}{rlr}
u_{\varepsilon} & \xrightarrow{w} u_{0} & \text { weakly in } H^{1}\left(\Omega_{0}\right),  \tag{3.35}\\
\left(r_{1}-r\right)^{-1} \tilde{u}_{\varepsilon}^{(1)} & \xrightarrow{w} w_{1} & \text { weakly in } L^{2}\left(\Omega^{(1)}\right), \\
\widetilde{u}_{\varepsilon}^{(i)} & \xrightarrow{w} \widetilde{u}_{i}:=h_{i} u_{i} & \text { weakly in } L^{2}\left(\Omega^{(i)}\right), \\
{\widetilde{\partial_{x_{k}}} u_{\varepsilon}(i)}^{l} \widetilde{u}_{i, k}:=h_{i} u_{i, k} & \text { weakly in } L^{2}\left(\Omega^{(i)}\right),
\end{array}\right\} \text { as } \varepsilon \rightarrow 0 .
$$

Here the limits remain unknown and will be defined later.
By the same assertions as in the proof of Theorem 2.1 we can show that

- $u_{i, 2}=0$ a.e. in $\Omega^{(i)}$, there exist weak derivatives $\partial_{x_{k}} u_{i}$ and $u_{i, k}=\partial_{x_{k}} u_{i}$ a.e. in $\Omega^{(i)}, k=1,3, i=1,2$;
- $\left.u_{0}\right|_{\Omega^{\prime}}=\left.u_{1}\right|_{\Omega^{\prime}}=\left.u_{2}\right|_{\Omega^{\prime}}$;
- $u_{0}\left(x_{1}, 0, x_{3}\right)=u_{0}\left(x_{1}, l, x_{3}\right), \quad x \in \partial \Omega_{0} \cap\left\{r<r_{0}\right\}$;
- $\left.u_{2}\right|_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}}=q_{0}$.

From (3.35) and (3.1) it follows that $w_{1}=\left(r_{1}-r\right)^{-1} h_{1}(r) u_{1} \in L^{2}\left(\Omega^{(1)}\right)$, i.e., $u_{1} \in L_{2 \gamma}^{2}\left(\Omega^{(1)}\right)$. Thus, $\partial_{x_{k}} u_{1} \in L_{2(1+\gamma)}^{2}\left(\Omega^{(1)}\right), k=1$, 3 . Thus, the multivalued function $\mathbf{u}=\left(u_{0}, u_{1}, u_{2}\right)$ belongs to the weighted space $\widetilde{\mathbf{H}}_{\gamma}$.

Consider arbitrary function $\mathbf{p}=\left(p_{0}, p_{1}, p_{2}\right) \in \widetilde{\mathbf{H}}_{h_{1}, \text { per }}$ such that $p_{1}=0$ in some neighborhood of $\partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}$ (not necessarily the same for all functions) and $\left.p_{2}\right|_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}}=0$. Then we define a test function

$$
\Phi(x)= \begin{cases}p_{0}(x), & x \in \Omega_{0}, \\ p_{1}(x), & x \in \Omega_{\varepsilon}^{(1)}, \\ p_{2}(x), & x \in \Omega_{\varepsilon}^{(2)} .\end{cases}
$$

Clearly, $\Phi \in H_{\text {per }}^{1}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{1}\right\}\right)$ and $\left.\Phi\right|_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}}=0$.
We rewrite the identity (3.5) with the test function $\Phi$ and obtain (3.23). Sending $\varepsilon$ to zero in (3.23), we obtain identity (3.34) for the multivalued function $\mathbf{u} \in \widetilde{\mathbf{H}}_{\gamma}$.

Remark 3.6 If $\mathbf{u} \in \widetilde{\mathbf{H}}_{h_{1}, \text { per }}$, then $\mathbf{u}$ is the unique weak solution to problem (3.28)) (see [133, §3]), and consequently convergence (3.33) hold for the whole sequence $\{\varepsilon\}$. Unfortunately, we could not prove that $\mathbf{u} \in \widetilde{\mathbf{H}}_{h_{1} \text {, per }}$.

### 3.5 Conclusions to this Chapter

The homogenized problems (3.18) and (3.28) are boundary-value problems for degenerate elliptic equations since the coefficient $h_{1}$ vanishes on the boundary
$\partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}$. The parameter $\gamma$ that described the degeneracy order plays a crucial role in the asymptotic behavior of the solution $u_{\varepsilon}$ to problem (3.2).

1. In the case $\gamma \in(-1,0)$, i.e., the first-level thin disks have rounded edges (cf. Fig. 3.2 a), the Neumann conditions on these edges are transformed into the same Neumann condition on $\partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}$. In fact, the homogenized problem (3.18) coincides with a homogenized problem as if $h_{1}(r)>0$ for all $\in\left[r_{0}, r_{1}\right]$ (cf., for example, the homogenized problem in [31]). This is confirmed also by the fact that the component $u_{1}$ of the multivalued solution to problem (3.18) belongs to the weighted Sobolev space $\widetilde{H}_{h_{1}}\left(\Omega^{(1)}\right)$ and as was shown in [133] each function from this space has the finite trace on $\partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}$ if $\gamma \in(-1,0)$.
2. If $\gamma \geq 0$, no boundary condition on $\partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}$ is required for establishing the existence and uniqueness of a solution to the homogenized problem (3.28) (cf. [133]). Moreover, some functions from the corresponding weighted Sobolev space may not have finite trace on $\partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}$ (see Lemma 3.5). However there is a significant difference between two cases $\gamma=0$ and $\gamma>0$.
If $\gamma=0$, i.e., the first-level thin disks have wedge edges (cf. Fig. 3.2 b), then the solution $\mathbf{u}$ to the homogenized problem (3.28) belongs to the "regular" space $\mathbf{H}_{\text {per }}^{1}$ and, as a consequence, the component $u_{1}$ has finite trace on $\partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}$ (see Theorem 3.4). In addition, the convergence of the traces (3.27) in sense of Mikhailov is established on this part of the boundary.
3. In the case of very sharp edges ( $\gamma>0$ ) we cannot assert that the component $u_{1}$ has a trace on $\partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}$ (cf. Remark 3.3) and its trace can even tend to infinity as $r \rightarrow r_{1}$ (see Lemma 3.5). As a consequence, we cannot establish uniqueness of a solution of the identity (3.34) in the space $\widetilde{\mathbf{H}}_{\gamma}$ and convergence (3.33) for the whole sequence (see Remark 3.6).
4. From physical point of view, the absence of conditions on $\partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}$ if $\gamma \geq 0$ means that the heat dissipates into environment while reaching the spikes. This is not true in the case $\gamma \in(-1,0)$. Thus, our results mathematically justify the following physical effect: heat radiators, shaped like a thick junction, radiate more heat if their thin joint domains have sharp edges.
5. The homogeneous Robin boundary conditions on the surfaces of the thin discs from the second level are transformed into the new summand $2 \kappa u_{2}$ in the corresponding partial differential equation (similarly as in Chap. 2). Also, we studied the behavior of the inhomogeneous Dirichlet conditions on edges as $\varepsilon \rightarrow 0$.
6. In this chapter, we have focused on studying the influence of the geometric structure of thin disks from the first level on the asymptotic behavior of the solution. Therefore, to avoid additional cumbersome calculations, we consider the homogeneous Neumann boundary condition. From calculations made here and in Chap. 2, it follows that the Robin boundary condition $\partial_{\nu} u_{\varepsilon}+\varepsilon k_{1} u_{\varepsilon}=0$ can be also considered (a term $2 k_{1} u_{1}$ appears in the corresponding differential equation).

# Chapter 4 <br> Homogenization of Semilinear Parabolic Problems 

Two semilinear parabolic problems in a thick two-level junction are considered. The first one is with different alternating nonlinear Robin boundary conditions and the other is with alternating Robin and Dirichlet conditions. In both problems, the passage to the limit is accompanied by a special intensity factor $\varepsilon^{\alpha}$ in the nonlinear term of the Robin conditions. The case of a big boundary interaction $(\alpha<1)$, which was not studied for the linear elliptic problem in Chap. 2, is examined. We establish qualitatively different cases in the asymptotic behavior of the solutions to those problems as $\varepsilon \rightarrow 0$ depending on the value of $\alpha$. The convergence theorems are proved using the method of special integral identity and zero-extension operators. The limits of nonlinear terms are found with the help of the Minty-Browder method.

### 4.1 Problem with Alternating Robin Boundary Conditions

### 4.1.1 Statement of the Problem

Let $T$ be a fixed positive number. We consider the following boundary-value problem in the thick junction $\Omega_{\varepsilon}$ described in Sect. 2.1:

$$
\begin{cases}\partial_{t} u_{\varepsilon}(t, x)-\Delta_{x} u_{\varepsilon}(t, x)+k_{0}\left(u_{\varepsilon}(t, x)\right)=f_{\varepsilon}, & (t, x) \in(0, T) \times \Omega_{\varepsilon},  \tag{4.1}\\ \partial_{\nu} u_{\varepsilon}(t, x)+\varepsilon^{\alpha} \kappa_{1}\left(u_{\varepsilon}(t, x)\right)=\varepsilon^{\beta} g_{\varepsilon}(t, x), & (t, x) \in(0, T) \times \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}, \\ \partial_{\nu} u_{\varepsilon}(t, x)+\varepsilon \kappa_{2}\left(u_{\varepsilon}(t, x)\right)=\varepsilon^{\beta} g_{\varepsilon}(t, x), & (t, x) \in(0, T) \times \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}, \\ \partial_{\nu} u_{\varepsilon}(t, x)=0, & (t, x) \in(0, T) \times \partial \Omega_{\varepsilon} \cap\left\{r=r_{0}\right\}, \\ \partial_{\nu} \varepsilon_{\varepsilon}(t, x)=q_{\varepsilon}(t, x), & (t, x) \in(0, T) \times \partial \Omega_{0} \cap\left\{r<r_{0}\right\}, \\ u_{\varepsilon}(0, x)=0, & x \in \Omega_{\varepsilon} .\end{cases}
$$

Here $\alpha \in \mathbb{R}, \beta \geq 1$ are perturbation parameters. The given functions $f_{\varepsilon}, g_{\varepsilon}, k_{0}, \kappa_{1}$, $\kappa_{2}$, and $q_{\varepsilon}$ satisfy the following conditions:

- the functions $f_{\varepsilon}, f_{0} \in L^{2}\left((0, T) \times \Omega_{0} \cup \Omega^{(2)}\right)$, and

$$
\begin{equation*}
f_{\varepsilon} \longrightarrow f_{0} \text { strongly in } L^{2}\left((0, T) \times \Omega_{0} \cup \Omega^{(2)}\right) \text { as } \varepsilon \rightarrow 0 \tag{4.2}
\end{equation*}
$$

- the functions $g_{\varepsilon}, g_{0} \in L^{2}\left(0, T ; H^{1}\left(\Omega^{(2)}\right)\right)$, and

$$
\begin{equation*}
g_{\varepsilon} \xrightarrow{w} g_{0} \text { weakly in } L^{2}\left(0, T ; H^{1}\left(\Omega^{(2)}\right)\right) \text { as } \varepsilon \rightarrow 0 ; \tag{4.3}
\end{equation*}
$$

- the functions $q_{\varepsilon}, q_{0} \in L^{2}\left((0, T) \times \partial \Omega_{0} \cap\left\{r<r_{0}\right\}\right)$, and

$$
\begin{equation*}
q_{\varepsilon} \xrightarrow{w} q_{0} \text { weakly in } L^{2}\left((0, T) \times \partial \Omega_{0} \cap\left\{r<r_{0}\right\}\right) \text { as } \varepsilon \rightarrow 0 ; \tag{4.4}
\end{equation*}
$$

- the functions $k_{0}, \kappa_{m}: \mathbb{R} \mapsto \mathbb{R}$ are Lipschitz-continuous, i.e., $k_{0}, \kappa_{m} \in W_{\mathrm{loc}}^{1, \infty}(\mathbb{R})$, and there exist positive constants $C_{0}$ and $C_{1}$ such that

$$
\begin{equation*}
C_{0} \leq k_{0}(s) \leq C_{1}, \quad C_{0} \leq \kappa_{m}^{\prime}(s) \leq C_{1}(m=1,2) \quad \text { for a.e. } s \in \mathbb{R} \tag{4.5}
\end{equation*}
$$

- if $\alpha<1$, then we additionally suppose that

$$
\begin{equation*}
\kappa_{1}(0)=0 . \tag{4.6}
\end{equation*}
$$

Remark 4.1 Robin's boundary condition means some interaction of a physical process occurring inside of a material with the external environment through its surface. In fact, very small activity holds always on the surface of some material (therefore Robin boundary conditions, in particular nonlinear ones, are more natural for applied mathematical problems). Many physical processes, especially in chemistry and medicine, have a monotonous nature. Therefore, it is natural to impose special monotonous assumptions for nonlinear terms. In our case, we propose simple assumptions (4.5) that are easy to verify. For instance, the functions

$$
k(s)=\lambda s+\sin s(\lambda>1) ; \quad k(s)=s+\arctan s ; \quad k(s)=\frac{\lambda s}{1+v s}(\lambda, v>0)
$$

satisfy (4.5). The last one corresponds to the Michaelis-Menten hypothesis in biochemical reactions and to the Langmuir kinetics adsorption models (e.g. [125]).

The case $\alpha<1$ corresponds to relatively high (of order $\varepsilon^{\alpha}$ ) heat transduction on the surfaces of the thin discs from the first level. The condition $\kappa_{1}(0)=0$ means that if the temperature is zero on the boundary at some moment, then there is no transduction on the surfaces. In many applications, this condition is called zeroabsorption condition.

Remark 4.2 Doubtless both the functions $k_{0}, \kappa_{1}, \kappa_{2}$ may also depend on $x$ and $t$ (cf. [92]). However, we have omitted this dependence to avoid cumbersome formulas.

Consider a space

$$
W_{T}\left(\Omega_{\varepsilon}\right)=\left\{\varphi \in L^{2}\left(0, T ; H^{1}\left(\Omega_{\varepsilon}\right)\right): \partial_{t} \varphi:=\varphi^{\prime} \in L^{2}\left(0, T ;\left(H^{1}\left(\Omega_{\varepsilon}\right)\right)^{*}\right)\right\} .
$$

It is known (e.g., [42, Theorem 1.17]) that $W_{T}\left(\Omega_{\varepsilon}\right) \subset C\left([0, T] ; L^{2}\left(\Omega_{\varepsilon}\right)\right)$.
Definition 4.1 A function $u_{\varepsilon} \in W_{T}\left(\Omega_{\varepsilon}\right)$ is called a weak solution to problem (4.1) if $u_{\varepsilon}(0, x)=0$ and the following integral identity takes place:

$$
\begin{equation*}
\mathrm{B}_{1, \varepsilon}\left(u_{\varepsilon}, \varphi\right)=\mathrm{L}_{1, \varepsilon}(\varphi) \quad \forall \varphi \in W_{T}\left(\Omega_{\varepsilon}\right), \tag{4.7}
\end{equation*}
$$

where

$$
\begin{aligned}
& \mathrm{B}_{1, \varepsilon}\left(u_{\varepsilon}, \varphi\right) \\
& \begin{aligned}
&:=\left.\int_{\Omega_{\varepsilon}}\left(u_{\varepsilon} \varphi\right)\right|_{t=T} d x+\int_{0}^{T}\left(-\left\langle\partial_{t} \varphi, u_{\varepsilon}\right\rangle_{H^{1}\left(\Omega_{\varepsilon}\right)}+\int_{\Omega_{\varepsilon}}\left(\nabla_{x} u_{\varepsilon} \cdot \nabla_{x} \varphi+k_{0}\left(u_{\varepsilon}\right) \varphi\right) d x\right. \\
&\left.+\varepsilon^{\alpha} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}} \kappa_{1}\left(u_{\varepsilon}\right) \varphi d \sigma_{x}+\varepsilon \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}} \kappa_{2}\left(u_{\varepsilon}\right) \varphi d \sigma_{x}\right) d t,
\end{aligned} \\
& \mathrm{~L}_{1, \varepsilon}(\varphi):=\int_{0}^{T}\left(\int_{\Omega_{\varepsilon}} f_{\varepsilon} \varphi d x+\int_{\partial \Omega_{0} \cap\left\{r<r_{0}\right\}} q_{\varepsilon} \varphi d \tilde{x}+\varepsilon^{\beta} \int_{\partial \Omega_{\varepsilon} \cap\left\{r>r_{0}\right\}} g_{\varepsilon} \varphi d \sigma_{x}\right) d t .
\end{aligned}
$$

Remark 4.3 Hereafter $\langle\cdot, \cdot\rangle_{H}$ is the duality pairing of a dual space $H^{*}$ with $H$.
Remark 4.4 There are different definitions of a weak solution to problem (4.1) (e.g., [131, Sect. 3.4]). We will use several of them depending on our needs.

Similarly as, for instance, in $[92,131]$ we can prove that for every fixed $\varepsilon>0$ there exists a unique weak solution to problem (4.1).

### 4.1.2 Auxiliary Statements

From (4.5), we deduce the inequalities

$$
\begin{gather*}
C_{2} s^{2}+k_{0}(0) s \leq k_{0}(s) s \leq C_{3} s^{2}+k_{0}(0) s,  \tag{4.8}\\
\left|k_{0}(s)\right| \leq C_{4}|s|+\left|k_{0}(0)\right| \quad \forall s \in \mathbb{R} . \tag{4.9}
\end{gather*}
$$

Clearly, the same inequalities hold for the functions $\kappa_{1}$ and $\kappa_{2}$.

Lemma 4.1 There exist positive constants $C_{5}$ and $\varepsilon_{0}$ such that for every $\varepsilon \in\left(0, \varepsilon_{0}\right)$ the following estimate for the weak solution $u_{\varepsilon}$ to problem (4.1) holds:

$$
\begin{equation*}
\max _{0 \leq t \leq T}\left\|u_{\varepsilon}(t, \cdot)\right\|_{L^{2}\left(\Omega_{\varepsilon}\right)}+\left\|u_{\varepsilon}\right\|_{L^{2}\left(0, T ; H^{1}\left(\Omega_{\varepsilon}\right)\right)} \leq C_{5} \tag{4.10}
\end{equation*}
$$

Proof In the identity (4.7), we can take any $\tau \in(0, T]$ instead of $T$. Then, putting $\varphi=u_{\varepsilon}$ in (4.7), we get

$$
\begin{gathered}
\frac{1}{2}\left\|u_{\varepsilon}(\tau, \cdot)\right\|_{L^{2}\left(\Omega_{\varepsilon}\right)}^{2}+\int_{0}^{\tau}\left(\int_{\Omega_{\varepsilon}}\left(\left|\nabla_{x} u_{\varepsilon}\right|^{2}+k_{0}\left(u_{\varepsilon}\right) u_{\varepsilon}\right) d x\right. \\
\left.+\varepsilon^{\alpha} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}} \kappa_{1}\left(u_{\varepsilon}\right) u_{\varepsilon} d \sigma_{x}+\varepsilon \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}} \kappa_{2}\left(u_{\varepsilon}\right) u_{\varepsilon} d \sigma_{x}\right) d t \\
=\int_{0}^{\tau}\left(\int_{\Omega_{\varepsilon}} f_{\varepsilon} u_{\varepsilon} d x+\int_{\partial \Omega_{0} \cap\left\{r<r_{0}\right\}} q_{\varepsilon} u_{\varepsilon} d \tilde{x}+\varepsilon^{\beta} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\} \cup \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}} g_{\varepsilon} u_{\varepsilon} d \sigma_{x}\right) d t
\end{gathered}
$$

whence using (4.8) we get

$$
\begin{align*}
& \frac{1}{2}\left\|u_{\varepsilon}(\tau, \cdot)\right\|_{L^{2}\left(\Omega_{\varepsilon}\right)}^{2} \\
& +c_{0} \int_{0}^{\tau}\left(\int_{\Omega_{\varepsilon}}\left(\left|\nabla_{x} u_{\varepsilon}\right|^{2}+u_{\varepsilon}^{2}\right) d x+\varepsilon^{\alpha} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}} u_{\varepsilon}^{2} d \sigma_{x}+\varepsilon \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}} u_{\varepsilon}^{2} d \sigma_{x}\right) d t \\
& \leq \int_{0}^{\tau}\left(-k_{0}(0) \int_{\Omega_{\varepsilon}} u_{\varepsilon} d x-\kappa_{1}(0) \varepsilon^{\alpha} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}} u_{\varepsilon} d \sigma_{x}-\kappa_{2}(0) \varepsilon \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}} u_{\varepsilon} d \sigma_{x}\right. \\
& \left.+\int_{\Omega_{\varepsilon}} f_{\varepsilon} u_{\varepsilon} d x+\underset{\partial \Omega_{0} \cap\left\{r<r_{0}\right\}}{ } q_{\varepsilon} u_{\varepsilon} d \tilde{x}++\varepsilon^{\beta} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\} \cup \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}} g_{\varepsilon} u_{\varepsilon} d \sigma_{x}\right) d t . \tag{4.11}
\end{align*}
$$

If $\alpha \geq 1$, then with the help of Cauchy-Schwarz-Bunyakovsky inequality, (2.10) and (2.13) we derive from (4.11)

$$
\begin{aligned}
& \frac{1}{2}\left\|u_{\varepsilon}(\tau, \cdot)\right\|_{L^{2}\left(\Omega_{\varepsilon}\right)}^{2}+c_{1}\left\|u_{\varepsilon}\right\|_{L^{2}\left(0, \tau ; H^{1}\left(\Omega_{\varepsilon}\right)\right)}^{2} \leq c_{1}\left(1+\varepsilon^{\alpha-1}+\left\|f_{\varepsilon}\right\|_{L^{2}\left((0, \tau) \times \Omega_{\varepsilon}\right)}+\right. \\
& \left.\quad+\varepsilon^{\beta-1}\left\|g_{\varepsilon}\right\|_{L^{2}\left(0, \tau ; H^{1}\left(\Omega^{(2)}\right)\right)}+\left\|q_{\varepsilon}\right\|_{L^{2}\left((0, \tau) \times \partial \Omega_{0} \cap\left\{r<r_{0}\right\}\right)}\right)\left\|u_{\varepsilon}\right\|_{L^{2}\left(0, \tau ; H^{1}\left(\Omega_{\varepsilon}\right)\right)}
\end{aligned}
$$

whence

$$
\begin{aligned}
\left\|u_{\varepsilon}\right\|_{L^{2}\left(0, \tau ; H^{1}\left(\Omega_{\varepsilon}\right)\right)} \leq c_{2} & \left(1+\varepsilon^{\alpha-1}+\left\|f_{\varepsilon}\right\|_{L^{2}\left((0, \tau) \times \Omega_{\varepsilon}\right)}\right. \\
& \left.+\varepsilon^{\beta-1}\left\|g_{\varepsilon}\right\|_{L^{2}\left(0, \tau ; H^{1}\left(\Omega^{(2)}\right)\right)}+\left\|q_{\varepsilon}\right\|_{L^{2}\left((0, \tau) \times \partial \Omega_{0} \cap\left\{r<r_{0}\right\}\right)}\right)
\end{aligned}
$$

and

$$
\begin{aligned}
\max _{0 \leq t \leq \tau}\left\|u_{\varepsilon}(t, \cdot)\right\|_{L^{2}\left(\Omega_{\varepsilon}\right)} \leq & c_{3}\left(1+\varepsilon^{\alpha-1}+\left\|f_{\varepsilon}\right\|_{L^{2}\left((0, \tau) \times \Omega_{\varepsilon}\right)}\right. \\
& \left.+\varepsilon^{\beta-1}\left\|g_{\varepsilon}\right\|_{L^{2}\left(0, \tau ; H^{1}\left(\Omega^{(2)}\right)\right)}+\left\|q_{\varepsilon}\right\|_{L^{2}\left((0, \tau) \times \partial \Omega_{0} \cap\left\{r<r_{0}\right\}\right)}\right) .
\end{aligned}
$$

Putting $\tau=T$ in those inequalities and considering (4.2)-(4.4), we get (4.10). In the case $\alpha<1$ with the help of (4.6), we deduce from (4.11) that

$$
\begin{aligned}
& \frac{1}{2}\left\|u_{\varepsilon}(\tau, \cdot)\right\|_{L^{2}\left(\Omega_{\varepsilon}\right)}^{2}+c_{4}\left\|u_{\varepsilon}\right\|_{L^{2}\left(0, \tau ; H^{1}\left(\Omega_{\varepsilon}\right)\right)}^{2} \leq c_{5}\left(1+\left\|f_{\varepsilon}\right\|_{L^{2}\left((0, \tau) \times \Omega_{\varepsilon}\right)}\right. \\
& \left.\quad+\varepsilon^{\beta-1}\left\|g_{\varepsilon}\right\|_{L^{2}\left(0, \tau ; H^{1}\left(\Omega^{(2)}\right)\right)}+\left\|q_{\varepsilon}\right\|_{L^{2}\left((0, \tau) \times \partial \Omega_{0} \cap\left\{r<r_{0}\right\}\right)}\right)\left\|u_{\varepsilon}\right\|_{L^{2}\left(0, \tau ; H^{1}\left(\Omega_{\varepsilon}\right)\right)}
\end{aligned}
$$

whence by the same way as previously we obtain (4.10).
Next we introduce the following zero-extensions

$$
\widetilde{\varphi}^{(i)}(t, x)=\left\{\begin{array}{ll}
\varphi(t, x), & (t, x) \in(0, T) \times \Omega_{\varepsilon}^{(i)}, \\
0, & (t, x) \in(0, T) \times\left(\Omega^{(i)} \backslash \Omega_{\varepsilon}^{(i)}\right),
\end{array} \quad i=1,2,\right.
$$

where $\varphi:(0, T) \times \Omega_{\varepsilon} \mapsto \mathbb{R}$.
With the help of identity (2.9) similarly as in [90], we can prove the Lemma.
Lemma 4.2 Let a sequence $\left\{v_{\varepsilon}\right\}_{\varepsilon>0} \subset L^{2}\left(0, T ; H^{1}\left(\Omega_{\varepsilon}\right)\right)$ be uniformly bounded with respect to $\varepsilon$. Then

$$
{\widetilde{\kappa_{i}\left(v_{\varepsilon}\right)}}^{(i)} \xrightarrow{w} \widetilde{\kappa}_{i} \text { weakly in } L^{2}\left((0, T) \times \Omega^{(i)}\right) \text { as } \varepsilon \rightarrow 0 \quad(i=1,2)
$$

and for arbitrary function $\varphi \in L^{2}\left(0, T ; H^{1}\left(\Omega^{(i)}\right)\right)$

$$
\varepsilon \int_{0}^{T} \int_{\partial \Omega_{\varepsilon}^{(i)} \cap\left\{r_{0}<r<r_{i}\right\}} \kappa_{i}\left(v_{\varepsilon}\right) \varphi d \sigma_{x} d t \longrightarrow 2 \int_{0}^{T} \int_{\Omega^{(i)}} h_{i}^{-1}(r) \widetilde{\kappa}_{i} \varphi d x d t \text { as } \varepsilon \rightarrow 0,
$$

### 4.1.3 Convergence Theorems

Consider time-dependent multivalued functions

$$
\mathbf{p}(t, x)=\left(p_{0}, p_{1}, p_{2}\right)= \begin{cases}p_{0}(t, x), & (t, x) \in(0, T) \times \Omega_{0}, \\ p_{1}(t, x), & (t, x) \in(0, T) \times \Omega^{(1)} \\ p_{2}(t, x), & (t, x) \in(0, T) \times \Omega^{(2)}\end{cases}
$$

and the space $\mathbf{L}_{T}:=L^{2}(0, T ; \mathbf{L})$ with the scalar product

$$
(\mathbf{p}, \mathbf{q})_{\mathbf{L}_{T}}=\int_{0}^{T}(\mathbf{p}, \mathbf{q})_{\mathbf{L}} d t
$$

(the space $\mathbf{L}$ is defined in Sect. 2.3.1). Also, we define the space

$$
\begin{aligned}
\widetilde{\mathbf{W}}_{T}:= & \left\{\mathbf{p}=\left(p_{0}, p_{1}, p_{2}\right): p_{0} \in L^{2}\left(0, T ; H^{1}\left(\Omega_{0}\right)\right), \partial_{t} p_{0} \in L^{2}\left(0, T ;\left(H^{1}\left(\Omega_{0}\right)\right)^{*}\right),\right. \\
& p_{i} \in L^{2}\left(0, T ; \widetilde{H}^{1}\left(\Omega^{(i)}\right)\right), \partial_{t} p_{i} \in L^{2}\left(0, T ;\left(\widetilde{H}^{1}\left(\Omega^{(i)}\right)\right)^{*}\right), i=1,2, \\
& \left.\left.p_{0}\right|_{\Omega^{\prime}}=\left.p_{1}\right|_{\Omega^{\prime}}=\left.p_{2}\right|_{\Omega^{\prime}} \text { for a.e. } t \in(0, T)\right\}
\end{aligned}
$$

with the norm

$$
\begin{aligned}
\|\mathbf{p}\|_{\widetilde{\mathbf{W}}_{T}}^{2}= & \left\|p_{0}\right\|_{L^{2}\left(0, T ; H^{1}\left(\Omega_{0}\right)\right)}^{2}+\left\|p_{0}^{\prime}\right\|_{L^{2}\left(0, T ;\left(H^{1}\left(\Omega_{0}\right)\right)^{*}\right)}^{2} \\
& +\sum_{i=1}^{2}\left(\left\|p_{i}\right\|_{L^{2}\left(0, T ; \widetilde{H}^{1}\left(\Omega^{(i)}\right)\right)}^{2}+\left\|p_{i}^{\prime}\right\|_{L^{2}\left(0, T ;\left(\widetilde{H}^{1}\left(\Omega^{(i)}\right)\right)^{*}\right)}^{2}\right)
\end{aligned}
$$

where $p^{\prime}:=\partial_{t} p, \widetilde{H}^{1}\left(\Omega^{(i)}\right)$ is defined in Sect. 2.3.1. Obviously, the embedding $\widetilde{\mathbf{W}}_{T} \subset$ $\mathbf{L}_{T}$ is continuous. Besides, $\widetilde{\mathbf{W}}_{T} \subset C([0, T] ; \mathbf{L})$ (see [42, Theorem 1.17]).

Theorem 4.1 If $\alpha \geq 1$, then for the weak solution $u_{\varepsilon}$ to problem (4.1) we have

$$
\left.\begin{array}{rl}
u_{\varepsilon} \xrightarrow{w} u_{0} & \text { weakly in } L^{2}\left(0, T ; H^{1}\left(\Omega_{0}\right)\right),  \tag{4.12}\\
\tilde{u}_{\varepsilon}^{(1)} & \xrightarrow{w} h_{1} u_{1} \\
\text { weakly in } L^{2}\left((0, T) \times \Omega^{(1)}\right), \\
\tilde{u}_{\varepsilon}^{(2)} \xrightarrow{w} h_{2} u_{2} & \text { weakly in } L^{2}\left((0, T) \times \Omega^{(2)}\right)
\end{array}\right\} \quad \text { as } \varepsilon \rightarrow 0,
$$

where $\mathbf{u}:=\left(u_{0}, u_{1}, u_{2}\right) \in \widetilde{\mathbf{W}}_{T}$ and it is a weak solution to the problem

$$
\begin{cases}\partial_{t} u_{0}-\Delta_{x} u_{0}+k_{0}\left(u_{0}\right)=f_{0}, & (t, x) \in(0, T) \times \Omega_{0},  \tag{4.13}\\ \partial_{\nu} u_{0}=q_{0}, & (t, x) \in(0, T) \times \partial \Omega_{0} \cap\left\{r<r_{0}\right\}, \\ h_{1}(r) \partial_{t} u_{1}-\operatorname{div}_{\tilde{x}}\left(h_{1}(r) \nabla_{\tilde{x}} u_{1}\right)+h_{1}(r) k_{0}\left(u_{1}\right) & \\ +2 \delta_{\alpha, 1} \kappa_{1}\left(u_{1}\right)=h_{1}(r) f_{0}+2 \delta_{\beta, 1} g_{0}, & (t, x) \in(0, T) \times \Omega^{(1)}, \\ \partial_{\nu} u_{1}=0, & (t, x) \in(0, T) \times \partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}, \\ h_{2}(r) \partial_{t} u_{2}-\operatorname{div}_{\tilde{x}}\left(h_{2}(r) \nabla_{\tilde{x}} u_{2}\right)+h_{2}(r) k_{0}\left(u_{2}\right) & \\ +2 \kappa_{2}\left(u_{2}\right)=h_{2}(r) f_{0}+2 \delta_{\beta, 1} g_{0}, & (t, x) \in(0, T) \times \Omega^{(2)}, \\ \partial_{\nu} u_{2}=0, & (t, x) \in(0, T) \times \partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}, \\ u_{0}=u_{1}=u_{2}, & (t, x) \in(0, T) \times \Omega^{\prime}, \\ \partial_{r} u_{0}=\sum_{i=1}^{2} h_{i}\left(r_{0}\right) \partial_{r} u_{i}, & \\ \mathbf{u}(0, x)=\mathbf{0}:=(0,0,0) . & \end{cases}
$$

Definition 4.2 A function $\mathbf{u}=\left(u_{0}, u_{1}, u_{2}\right) \in \widetilde{\mathbf{W}}_{T}$ is called a weak solution of problem (4.13) if $\mathbf{u}(0, x)=\mathbf{0}$ and the following integral identity takes place:
$\mathrm{B}_{0}\left(\mathbf{u}, \mathbf{p} ; k_{0}\left(u_{0}\right), h_{1} k_{0}\left(u_{1}\right), h_{2} k_{0}\left(u_{2}\right), h_{1} \kappa_{1}\left(u_{1}\right), h_{2} \kappa_{2}\left(u_{2}\right)\right)=\mathrm{L}_{0}(\mathbf{p}) \quad \forall \mathbf{p} \in \widetilde{\mathbf{W}}_{T}$, where
$\left.\mathrm{B}_{0}\left(\mathbf{u}, \mathbf{p} ; \omega_{0}, \widetilde{\omega}_{1}, \widetilde{\omega}_{2}, \widetilde{\kappa}_{1}, \widetilde{\kappa}_{2}\right)\right)=\left.\int_{\Omega_{0}}\left(u_{0} p_{0}\right)\right|_{t=T} d x+\left.\sum_{i=1}^{2} \int_{\Omega^{(i)}} h_{i}(r)\left(u_{i} p_{i}\right)\right|_{t=T} d x$

$$
\begin{gathered}
+\int_{0}^{T}\left(-\left\langle\partial_{t} p_{0}, u_{0}\right\rangle_{H^{1}\left(\Omega_{0}\right)}-\sum_{i=1}^{2}\left\langle h_{i}(r) \partial_{t} p_{i}, u_{i}\right\rangle_{\tilde{H}^{1}\left(\Omega^{(i)}\right)}\right. \\
+\int_{\Omega_{0}}\left(\nabla_{x} u_{0} \cdot \nabla_{x} p_{0}+\omega_{0} p_{0}\right) d x+\sum_{i=1}^{2} \int_{\Omega^{(i)}}\left(h_{i}(r) \nabla_{\tilde{x}} u_{i} \cdot \nabla_{\tilde{x}} p_{i}+\widetilde{\omega}_{i} p_{i}\right) d x \\
\left.\quad+2 \delta_{\alpha, 1} \int_{\Omega^{(1)}} h_{1}^{-1}(r) \widetilde{\kappa}_{1} p_{1} d x+2 \int_{\Omega^{(2)}} h_{2}^{-1}(r) \widetilde{\kappa}_{2} p_{2} d x\right) d t \\
\mathrm{~L}_{0}(\mathbf{p})=\int_{0}^{T}\left(\int_{\Omega_{0}} f_{0} p_{0} d x+\int_{\partial \Omega_{0} \cap\left\{r<r_{0}\right\}} q_{0} p_{0} d \tilde{x}+\sum_{i=1}^{2} \int_{\Omega^{(i)}}\left(h_{i}(r) f_{0}+2 \delta_{\beta, 1} g_{0}\right) p_{i} d x\right) d t
\end{gathered}
$$

Problem (4.13) is called a homogenized problem for problem (4.1). The existence and uniqueness of a weak solution to problem (4.13) can be proved as, e.g., in [131] using (4.5).

Proof 1. From (4.10) and (4.9), it follows that there exists a subsequence $\left\{\varepsilon^{\prime}\right\} \subset\{\varepsilon\}$ (again denoted by $\{\varepsilon\}$ ) such that for $i \in\{1,2\}$ and $k \in\{1,2,3\}$

$$
\begin{aligned}
& u_{\varepsilon} \xrightarrow{w} u_{0} \quad \text { weakly in } L^{2}\left(0, T ; H^{1}\left(\Omega_{0}\right)\right) \text {, }
\end{aligned}
$$

$$
\begin{align*}
& \text { as } \varepsilon \rightarrow 0 \tag{4.14}
\end{align*}
$$

The estimate (4.10) also implies that for every $t \in[0, T]$ there exists a subsequence $\left\{\varepsilon_{t}\right\} \subset\{\varepsilon\}$ such that

$$
\begin{gather*}
u_{\varepsilon_{t}}(t, \cdot) \xrightarrow{w} \dot{u}_{0}(t, \cdot) \quad \text { weakly in } L^{2}\left(\Omega_{0}\right)  \tag{4.15}\\
\widetilde{u}_{\varepsilon_{t}}^{(i)}(t, \cdot) \xrightarrow{w} \dot{u}_{i}(t, \cdot) \quad \text { weakly in } L^{2}\left(\Omega^{(i)}\right), i=1,2 . \tag{4.16}
\end{gather*}
$$

The Fubini's Theorem implies that $u_{0}(t, \cdot) \in L^{2}\left(\Omega_{0}\right)$ and $u_{i}(t, \cdot) \in L^{2}\left(\Omega^{(i)}\right)$ for a.e. $t \in(0, T)(i=1,2)$. Then, thanks to (4.38) and (4.16)

$$
\begin{gathered}
\dot{u}_{0}(t, x)=u_{0}(t, x) \quad \text { a.e. in }(0, T) \times \Omega_{0} \\
\dot{u}_{i}(t, x)=h_{i} u_{i}(t, x) \quad \text { a.e. in }(0, T) \times \Omega^{(i)}, i=1,2 .
\end{gathered}
$$

Here unknown functions in the right-hand sides will be defined later.
2. Definition 4.1 is equivalent to the following one (cf. e.g. [131, Sect.3.4]): a function $u_{\varepsilon} \in W_{T}\left(\Omega_{\varepsilon}\right)$ is called a weak solution to problem (4.1) if $u_{\varepsilon}(0, x)=0$ and for all $\varphi \in H^{1}\left(\Omega_{\varepsilon}\right)$ and a.e. $t \in(0, T)$ the following integral identity holds:

$$
\begin{align*}
& \left\langle\partial_{t} u_{\varepsilon}, \varphi\right\rangle_{H^{1}\left(\Omega_{\varepsilon}\right)}+\int_{\Omega_{\varepsilon}}\left(\nabla_{x} u_{\varepsilon} \cdot \nabla_{x} \varphi+k_{0}\left(u_{\varepsilon}\right) \varphi\right) d x \\
& +\varepsilon^{\alpha} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}} \kappa_{1}\left(u_{\varepsilon}\right) \varphi d \sigma_{x}+\varepsilon \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}} \kappa_{2}\left(u_{\varepsilon}\right) \varphi d \sigma_{x} \\
& \quad=\int_{\Omega_{\varepsilon}} f_{\varepsilon} \varphi d x+\int_{\partial \Omega_{0} \cap\left\{r<r_{0}\right\}} q_{\varepsilon} \varphi d \tilde{x}+\varepsilon^{\beta} \int_{\partial \Omega_{\varepsilon} \cap\left\{r>r_{0}\right\}} g_{\varepsilon} \varphi d \sigma_{x} . \tag{4.17}
\end{align*}
$$

Let us take a test function in (4.7) in the form $\varphi(t, x)=\Phi_{1}(x) \eta(t)$, where $\Phi_{1}$ is defined in the second part of the proof of Theorem 2.2 and $\eta \in C^{1}([0, T])$. We get

$$
\left|\int_{0}^{T} \int_{\Omega_{\varepsilon}^{(1)}} \partial_{x_{2}} u_{\varepsilon} \varphi_{1} \eta d x d t\right|=\mathscr{O}(\varepsilon), \quad \varepsilon \rightarrow 0
$$

whence

$$
\int_{0}^{T} \int_{\Omega^{(1)}} u_{1,2} \varphi_{1} \eta d x d t=0 \quad \forall \varphi_{1} \in C_{0}^{\infty}\left(\Omega^{(1)}\right), \forall \eta \in C^{1}([0, T])
$$

Thus, $u_{1,2}=0$ a.e. in $(0, T) \times \Omega^{(1)}$. Similarly, we show that $u_{2,2}=0$ in $(0, T) \times$ $\Omega^{(2)}$.

Now let us find $u_{i, 1}$ and $u_{i, 3}, i=1$, 2. Identity (2.27) gives

$$
\begin{align*}
& \int_{0}^{T} \int_{\Omega^{(1)}}{\widetilde{\partial_{x_{m}}} u_{\varepsilon}^{(1)} \psi \eta d x d t}=\int_{0}^{T}\left(-\int_{\Omega^{(1)}} \widetilde{u}_{\varepsilon}^{(1)}\left(\partial_{x_{m}} \psi+\partial_{x_{m}} \ln h_{1}(r) \psi\right) d x\right. \\
&\left.+\varepsilon \int_{\Omega_{\varepsilon}^{(1)}} Y_{1}\left(\frac{x_{2}}{\varepsilon}\right) \partial_{x_{m}} \ln h_{1}(r) \partial_{x_{2}}\left(u_{\varepsilon} \psi\right) d x\right) \eta d t \tag{4.18}
\end{align*}
$$

for all $\psi \in C_{0}^{\infty}\left(\Omega^{(1)}\right)$ and $\eta \in C^{1}([0, T]) ; m=1$, 3. In the limit, (4.18) gives

$$
\int_{0}^{T} \int_{\Omega^{(1)}} u_{1, m} h_{1}(r) \psi \eta d x d t=-\int_{0}^{T} \int_{\Omega^{(1)}} u_{1} \partial_{x_{m}}\left(h_{1}(r) \psi\right) \eta d x d t
$$

whence we conclude the existence of the weak derivative $\partial_{x_{m}} u_{1}$ and $u_{1, m}=\partial_{x_{m}} u_{1}$ a.e. in $(0, T) \times \Omega^{(1)}, m=1$, 3. Similarly, we show the existence of the weak derivative $\partial_{x_{m}} u_{2}$ and $u_{2, m}=\partial_{x_{m}} u_{2}$ a.e. in $(0, T) \times \Omega^{(2)}, m=1,3$.

The obtained relations provide embedding $u_{i} \in L^{2}\left(0, T ; \widetilde{H}^{1}\left(\Omega^{(i)}\right)\right), i=1,2$.
3. Now we find conjugation conditions on the joint zone. The properties of a trace operator and (4.14) imply that for a.e. $t \in(0, T)$ the following convergence holds:

$$
\begin{equation*}
\left.\left.u_{\varepsilon}(t, \cdot)\right|_{\Omega^{\prime}} \longrightarrow u_{0}(t, \cdot)\right|_{\Omega^{\prime}} \text { strongly in } L^{2}\left(\Omega^{\prime}\right) \text { as } \varepsilon \rightarrow 0 . \tag{4.19}
\end{equation*}
$$

Identity (2.31) provides

$$
\begin{gather*}
-r_{0}^{-1} \int_{0}^{T} \int_{\Omega^{\prime}} \chi_{\Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{0}\right\}} u_{\varepsilon} \psi \eta d \sigma_{x} d t \\
=\int_{0}^{T}\left(\int_{\Omega^{(1)}} r^{-1}\left(\widetilde{\partial_{r}} u_{\varepsilon}^{(1)} \psi+\widetilde{u}_{\varepsilon}^{(1)} \partial_{r} \psi+\left(\ln h_{1}(r)\right)^{\prime} \widetilde{u}_{\varepsilon}^{(1)} \psi\right) d x\right. \\
\left.-\varepsilon \int_{\Omega_{\varepsilon}^{(1)}} Y_{1}\left(\frac{x_{2}}{\varepsilon}\right) r^{-1}\left(\ln h_{1}(r)\right)^{\prime} \partial_{x_{2}}\left(u_{\varepsilon} \psi\right) d \sigma_{x}\right) \eta d t \tag{4.20}
\end{gather*}
$$

for all $\eta \in C^{1}([0, T])$ and $\psi \in C^{\infty}\left(\overline{\Omega^{(1)}}\right)$ such that $\left.\psi\right|_{\partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}}=0$. Passing to the limit in (4.20) as $\varepsilon \rightarrow 0$, taking into account (2.16), (4.19), and (4.14), and integrating by parts, we obtain the identity

$$
\int_{0}^{T} \int_{\Omega^{\prime}} u_{0} \psi \eta d \sigma_{x} d t=\int_{0}^{T} \int_{\Omega^{\prime}} u_{1} \psi \eta d \sigma_{x} d t
$$

that means $\left.u_{0}\right|_{\Omega^{\prime}}=\left.u_{1}\right|_{\Omega^{\prime}}$ for a.e. $t \in(0, T)$. Repeating the same assertions for the thin discs from the second level, we obtain

$$
\begin{equation*}
\left.u_{0}\right|_{\Omega^{\prime}}=\left.u_{1}\right|_{\Omega^{\prime}}=\left.u_{2}\right|_{\Omega^{\prime}} \quad \text { for a.e. } t \in(0, T) \tag{4.21}
\end{equation*}
$$

4. Consider the multivalued function $\mathbf{u}=\left(u_{0}, u_{1}, u_{2}\right)$. On the basis of (4.14), (4.21) and the relations obtained in the item $\mathbf{2}$, we conclude that $\mathbf{u} \in \widetilde{\mathbf{W}}_{T}$.

Let $\eta \in C^{1}([0, T]), \varphi_{0} \in C^{\infty}\left(\overline{\Omega_{0}}\right), \varphi_{i} \in C^{\infty}\left(\overline{\Omega^{(i)}}\right), i=1$, 2 , be arbitrary functions such that $\left.\varphi_{0}\right|_{\Omega^{\prime}}=\left.\varphi_{1}\right|_{\Omega^{\prime}}=\left.\varphi_{2}\right|_{\Omega^{\prime}}, \eta(T)=0$. With the help of them we define

$$
\Phi(t, x)= \begin{cases}\varphi_{0}(x) \eta(t), & (t, x) \in(0, T) \times \Omega_{0}, \\ \varphi_{1}(x) \eta(t), & (t, x) \in(0, T) \times \Omega_{\varepsilon}^{(1)}, \\ \varphi_{2}(x) \eta(t), & (t, x) \in(0, T) \times \Omega_{\varepsilon}^{(2)}\end{cases}
$$

Clearly, $\Phi \in W_{T}\left(\Omega_{\varepsilon}\right)$. We substitute $\Phi$ as a test function into (4.7) and utilize zeroextension operators. Then passing to the limit as $\varepsilon \rightarrow 0$ (if necessary we choose an appropriate subsequence) and bearing in mind (4.2), (4.3), (4.4), (4.9), (4.10), (2.13), (2.16), Lemmas 2.2 and 4.2, and the relations obtained above in the proof, we get

$$
\begin{equation*}
\mathrm{B}_{0}\left(\mathbf{u}, \mathbf{p}, \omega_{0}, \widetilde{\omega}_{1}, \widetilde{\omega}_{2}, \widetilde{\kappa}_{1}, \widetilde{\kappa}_{2}\right)=\mathrm{L}_{0}(\mathbf{p}), \tag{4.22}
\end{equation*}
$$

where $\mathbf{p}=\left(\varphi_{0} \eta, \varphi_{1} \eta, \varphi_{2} \eta\right)$.
The set of multivalued functions

$$
\begin{array}{r}
\left\{\left(\varphi_{0} \eta, \varphi_{1} \eta, \varphi_{2} \eta\right): \varphi_{0} \in C^{\infty}\left(\overline{\Omega_{0}}\right), \varphi_{1} \in C^{\infty}\left(\overline{\Omega^{(1)}}\right), \varphi_{2} \in C^{\infty}\left(\overline{\Omega^{(2)}}\right)\right. \\
\left.\left.\varphi_{0}\right|_{\Omega^{\prime}}=\left.\varphi_{1}\right|_{\Omega^{\prime}}=\left.\varphi_{2}\right|_{\Omega^{\prime}}, \eta \in C^{1}([0, T]), \eta(T)=0\right\}
\end{array}
$$

is dense in the space $\widetilde{\mathbf{W}}_{T}$ of functions $\mathbf{p}$ such that $\left.\mathbf{p}\right|_{t=T}=\mathbf{0}$ (see [42, Lemma 1.12]). This means that the multivalued function $\mathbf{u}=\left(u_{0}, u_{1}, u_{2}\right)$ is a solution of identity (4.22) with till now unknown functions $\omega_{0}, \widetilde{\omega}_{1}, \widetilde{\omega}_{2}, \widetilde{\kappa}_{1}$, and $\widetilde{\kappa}_{2}$.
5. In order to find them, we use Minty-Browder method. Consider the integral identity (4.7) with the test function $\varphi=u_{\varepsilon}$ :

$$
\mathrm{B}_{1, \varepsilon}\left(u_{\varepsilon}, u_{\varepsilon}\right)=\mathrm{L}_{1, \varepsilon}\left(u_{\varepsilon}\right)
$$

Conditions (4.2), (4.3), (4.4), and relations (4.14), (2.13) and (2.16) imply that the limit of the right-hand side as $\varepsilon \rightarrow 0$ is equal to $L_{0}(\mathbf{u})$, whence on the grounds of identity (4.22) with the test function $\mathbf{p}=\mathbf{u}$ we find that

$$
\begin{equation*}
\mathrm{B}_{1, \varepsilon}\left(u_{\varepsilon}, u_{\varepsilon}\right) \longrightarrow \mathrm{B}_{0}\left(\mathbf{u}, \mathbf{u}, \omega_{0}, \widetilde{\omega}_{1}, \widetilde{\omega}_{2}, \widetilde{\kappa}_{1}, \widetilde{\kappa}_{2}\right) \text { as } \varepsilon \rightarrow 0 \tag{4.23}
\end{equation*}
$$

Consider a monotonicity inequality

$$
\begin{gathered}
\frac{1}{2} \int_{\Omega_{0}}\left(u_{\varepsilon}(T, x)-p_{0}(T, x)\right)^{2} d x+\frac{1}{2} \sum_{i=1}^{2} \int_{\Omega_{\varepsilon}^{(i)}}\left(u_{\varepsilon}(T, x)-p_{i}(T, x)\right)^{2} d x \\
+\int_{0}^{T}\left(\int_{\Omega_{0}}\left|\nabla_{x} u_{\varepsilon}-\nabla_{x} p_{0}\right|^{2} d x+\sum_{i=1}^{2} \int_{\Omega_{\varepsilon}^{(i)}}\left(\left|\nabla_{\tilde{x}} u_{\varepsilon}-\nabla_{\tilde{x}} p_{i}\right|^{2}+\left(\partial_{x_{2}} u_{\varepsilon}\right)^{2}\right) d x\right. \\
+\int_{\Omega_{0}}\left(k_{0}\left(u_{\varepsilon}\right)-k_{0}\left(p_{0}\right)\right)\left(u_{\varepsilon}-p_{0}\right) d x+\sum_{i=1}^{2} \int_{\Omega_{\varepsilon}^{(i)}}\left(k_{0}\left(u_{\varepsilon}\right)-k_{0}\left(p_{i}\right)\right)\left(u_{\varepsilon}-p_{i}\right) d x \\
\quad+\varepsilon^{\alpha} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}}\left(\kappa_{1}\left(u_{\varepsilon}\right)-\kappa_{1}\left(p_{1}\right)\right)\left(u_{\varepsilon}-p_{1}\right) d \sigma_{x} \\
\left.+\varepsilon \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}}\left(\kappa_{2}\left(u_{\varepsilon}\right)-\kappa_{2}\left(p_{2}\right)\right)\left(u_{\varepsilon}-p_{2}\right) d \sigma_{x}\right) d t \geq 0,
\end{gathered}
$$

where $\mathbf{p}=\left(p_{0}, p_{1}, p_{2}\right) \in \widetilde{\mathbf{W}}_{T}$ is arbitrary. Use zero-extensions and passing to the limit in the obtained inequality as $\varepsilon \rightarrow 0$ and utilizing (4.23), (2.16), (4.14), (2.9), and Lemma 4.2, we get

$$
\begin{aligned}
& \frac{1}{2} \int_{\Omega_{0}}\left(u_{0}(T, x)-p_{0}(T, x)\right)^{2} d x+\frac{1}{2} \sum_{i=1}^{2} \int_{\Omega^{(i)}} h_{i}(r)\left(u_{i}(T, x)-p_{i}(T, x)\right)^{2} d x \\
& \quad+\int_{0}^{T}\left(\int_{\Omega_{0}}\left|\nabla_{x} u_{0}-\nabla_{x} p_{0}\right|^{2} d x+\sum_{i=1}^{2} \int_{\Omega^{(i)}} h_{i}(r)\left|\nabla_{\tilde{x}} u_{i}-\nabla_{\tilde{x}} p_{i}\right|^{2} d x\right. \\
& +\int_{\Omega_{0}}\left(\omega_{0}-k_{0}\left(p_{0}\right)\right)\left(u_{0}-p_{0}\right) d x+\sum_{i=1}^{2} \int_{\Omega^{(i)}}\left(\widetilde{\omega}_{i}-h_{i}(r) k_{0}\left(p_{i}\right)\right)\left(u_{i}-p_{i}\right) d x \\
& \quad+2 \delta_{\alpha, 1} \int_{\Omega^{(1)}}\left(h_{1}^{-1}(r) \widetilde{\kappa}_{1}-\kappa_{1}\left(p_{1}\right)\right)\left(u_{1}-p_{1}\right) d x \\
& \left.\quad+2 \int_{\Omega^{(2)}}\left(h_{2}^{-1}(r) \widetilde{\kappa}_{2}-\kappa_{2}\left(p_{2}\right)\right)\left(u_{2}-p_{2}\right) d x\right) d t \geq 0 .
\end{aligned}
$$

Setting $p_{m}(t, x)=u_{m}(t, x)-\lambda q_{m}(t, x), m=0,1,2$, in the last inequality, where $\lambda>0$ and $\mathbf{q}=\left(q_{0}, q_{1}, q_{2}\right) \in \widetilde{\mathbf{W}}_{T}$, we obtain

$$
\begin{aligned}
& \lambda\left\{\frac{1}{2} \int_{\Omega_{0}} q_{0}^{2} d x+\frac{1}{2} \sum_{i=1}^{2} \int_{\Omega^{(i)}} h_{i}(r) q_{i}^{2} d x+\int_{0}^{T}\left(\int_{\Omega_{0}}\left|\nabla_{x} q_{0}\right|^{2} d x+\sum_{i=1}^{2} \int_{\Omega^{(i)}} h_{i}(r)\left|\nabla_{\tilde{x}} q_{i}\right|^{2} d x\right) d t\right\} \\
& +\int_{0}^{T}\left(\int_{\Omega_{0}}\left(\omega_{0}-k_{0}\left(u_{0}-\lambda q_{0}\right)\right) q_{0} d x+\sum_{i=1}^{2} \int_{\Omega^{(i)}}\left(\widetilde{\omega}_{i}-h_{i}(r) k_{0}\left(u_{i}-\lambda q_{i}\right)\right) q_{i} d x\right. \\
& +2 \delta_{\alpha, 1} \int_{\Omega^{(1)}}\left(h_{1}^{-1}(r) \widetilde{\kappa}_{1}-\kappa_{1}\left(u_{1}-\lambda q_{1}\right)\right) q_{1} d x \\
& + \\
& \left.+2 \int_{\Omega^{(2)}}\left(h_{2}^{-1}(r) \widetilde{\kappa}_{2}-\kappa_{2}\left(u_{2}-\lambda q_{2}\right)\right) q_{2} d x\right) d t \geq 0 .
\end{aligned}
$$

Sending $\lambda$ to zero and taking into account continuity of $k_{0}, \kappa_{1}$, and $\kappa_{2}$, we get

$$
\begin{aligned}
& \int_{0}^{T}\left(\int_{\Omega_{0}}\left(\omega_{0}-k_{0}\left(u_{0}\right)\right) q_{0} d x+\sum_{i=1}^{2} \int_{\Omega^{(i)}}\left(\widetilde{\omega}_{i}-h_{i}(r) k_{0}\left(u_{i}\right)\right) q_{i} d x\right. \\
+ & \left.2 \delta_{\alpha, 1} \int_{\Omega^{(1)}}\left(h_{1}^{-1}(r) \widetilde{\kappa}_{1}-\kappa_{1}\left(u_{1}\right)\right) q_{1} d x+2 \int_{\Omega^{(2)}}\left(h_{2}^{-1}(r) \widetilde{\kappa}_{2}-\kappa_{2}\left(u_{2}\right)\right) q_{2} d x\right) d t \geq 0 .
\end{aligned}
$$

Setting $q_{m}:=-q_{m}(m=0,1,2)$, we see that in fact the equality holds. Since $\mathbf{q}=$ ( $q_{0}, q_{1}, q_{2}$ ) is arbitrary multifunction, we deduce that

$$
\begin{aligned}
\omega_{0} & =k_{0}\left(u_{0}\right) & & \text { a.e. in }(0, T) \times \Omega_{0}, \\
\widetilde{\omega}_{1}+2 \delta_{\alpha, 1} h_{1}^{-1}(r) \widetilde{\kappa}_{1} & =h_{1}(r) k_{0}\left(u_{1}\right)+2 \delta_{\alpha, 1} \kappa_{1}\left(u_{1}\right) & & \text { a.e. in }(0, T) \times \Omega^{(1)}, \\
\widetilde{\omega}_{2}+2 h_{2}^{-1}(r) \widetilde{\kappa}_{2} & =h_{2}(r) k_{0}\left(u_{2}\right)+2 \kappa_{2}\left(u_{2}\right) & & \text { a.e. in }(0, T) \times \Omega^{(2)} .
\end{aligned}
$$

Now it follows from (4.22) that $\mathbf{u}$ is the weak solution to problem (4.13).
6. Since all of the above assertions remain valid for arbitrary subsequence $\left\{\varepsilon^{\prime}\right\}$ chosen at the beginning of the proof, the uniqueness of the weak solution to the homogenized problem (4.13) implies the limits (4.12). The theorem is proved.

Now consider the case $\alpha<1$. Then assumption (4.6) is additionally satisfied in this case. For our investigations, we introduce the spaces

$$
W_{T}\left(\Omega_{0}, \Omega^{\prime}\right)=\left\{\varphi \in L^{2}\left(0, T ; H^{1}\left(\Omega_{0}, \Omega^{\prime}\right)\right): \partial_{t} \varphi \in L^{2}\left(0, T ;\left(H^{1}\left(\Omega_{0}, \Omega^{\prime}\right)\right)^{*}\right)\right\}
$$

and

$$
\widetilde{W}_{T}\left(\Omega^{(i)}, \Omega^{\prime}\right)=\left\{\varphi \in L^{2}\left(0, T ; \widetilde{H}^{1}\left(\Omega^{(i)}, \Omega^{\prime}\right)\right): \partial_{t} \varphi \in L^{2}\left(0, T ;\left(\widetilde{H}^{1}\left(\Omega^{(i)}, \Omega^{\prime}\right)\right)^{*}\right)\right\},
$$

where the spaces $H^{1}\left(\Omega_{0}, \Omega^{\prime}\right)$ and $\widetilde{H}^{1}\left(\Omega^{(i)}, \Omega^{\prime}\right)$ are defined in Sect. 2.3.2, $i=1,2$.
Theorem 4.2 If $\alpha<1$, then for the weak solution $u_{\varepsilon}$ to problem (4.1) we have

$$
\left.\begin{array}{rl}
u_{\varepsilon} & \xrightarrow{w} u_{0} \\
\widetilde{u}_{\varepsilon}^{(1)} \longrightarrow 0 & \text { weakly in } L^{2}\left(0, T ; H^{1}\left(\Omega_{0}\right)\right),  \tag{4.24}\\
\widetilde{u}_{\varepsilon}^{(2)} \xrightarrow{w} h_{2} u_{2} & \text { weakly in } L^{2}\left((0, T) \times \Omega^{(2)}\right)
\end{array}\right\} \quad \text { as } \varepsilon \rightarrow 0,
$$

where the function $u_{0} \in W_{T}\left(\Omega_{0}, \Omega^{\prime}\right)$ and it is a weak solution to the problem

$$
\begin{cases}\partial_{t} u_{0}-\Delta_{x} u_{0}+k_{0}\left(u_{0}\right)=f_{0}, & (t, x) \in(0, T) \times \Omega_{0},  \tag{4.25}\\ \partial_{\nu} u_{0}=q_{0}, & (t, x) \in(0, T) \times \partial \Omega_{0} \cap\left\{r<r_{0}\right\}, \\ u_{0}=0, & (t, x) \in(0, T) \times \Omega^{\prime}, \\ u_{0}(0, x)=0, & x \in \Omega_{0},\end{cases}
$$

the function $u_{2} \in \widetilde{W}_{T}\left(\Omega^{(2)}, \Omega^{\prime}\right)$ and it is a weak solution to the problem

$$
\begin{cases}h_{2}(r) \partial_{t} u_{2}-\operatorname{div}_{\tilde{x}}\left(h_{2}(r) \nabla_{\tilde{x}} u_{2}\right)+h_{2}(r) k_{0}\left(u_{2}\right) &  \tag{4.26}\\ +2 \kappa_{2}\left(u_{2}\right)=h_{2}(r) f_{0}+2 \delta_{\beta, 1} g_{0}, & (t, x) \in(0, T) \times \Omega^{(2)}, \\ \partial_{\nu} u_{2}=0, & (t, x) \in(0, T) \times \partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}, \\ u_{2}=0, & x \in \Omega^{(2)} . \\ u_{2}(0, x)=0, & (0, T) \times \Omega^{\prime}, \\ \hline\end{cases}
$$

Problems (4.25) and (4.26) form the homogenized problem for problem (4.1).
Definition 4.3 A function $u \in L^{2}\left(0, T ; H^{1}\left(\Omega_{0}, \Omega^{\prime}\right)\right)$ is called a weak solution to problem (4.25) if $u(0, x)=0$ and

$$
\mathrm{B}_{1,0}\left(u, \varphi, k_{0}(u)\right)=\mathrm{L}_{1,0}(\varphi) \quad \forall \varphi \in W_{T}\left(\Omega_{0}, \Omega^{\prime}\right),
$$

where

$$
\begin{gathered}
\mathrm{B}_{1,0}\left(u, \varphi, \omega_{0}\right)=\left.\int_{\Omega_{0}}(u \varphi)\right|_{t=T} d x \\
+\int_{0}^{T}\left(-\left\langle\partial_{t} \varphi, u\right\rangle_{H^{1}\left(\Omega_{0}, \Omega^{\prime}\right)}+\int_{\Omega_{0}}\left(\nabla_{x} u \cdot \nabla_{x} \varphi+\omega_{0} \varphi\right) d x\right) d t \\
\mathrm{~L}_{1,0}(\varphi, t)=\int_{0}^{T}\left(\int_{\Omega_{0}} f_{0} \varphi d x+\int_{\partial \Omega_{0} \cap\left\{r<r_{0}\right\}} q_{0} \varphi d \tilde{x}\right) d t
\end{gathered}
$$

Definition 4.4 A function $u \in L^{2}\left(0, T ; \widetilde{H}^{1}\left(\Omega^{(2)}, \Omega^{\prime}\right)\right)$ is called a weak solution to problem (4.26) if $u(0, x)=0$ and

$$
\mathrm{B}_{1,2}\left(u, \varphi, h_{2} k_{0}(u), h_{2} \kappa_{2}(u)\right)=\mathrm{L}_{1,2}(\varphi) \quad \forall \varphi \in \widetilde{W}_{T}\left(\Omega^{(2)}, \Omega^{\prime}\right),
$$

where

$$
\begin{gathered}
\mathrm{B}_{1,2}\left(u, \varphi, \widetilde{\omega}_{2}, \widetilde{\kappa}_{2}\right)=\left.\int_{\Omega^{(2)}} h_{2}(r)(u \varphi)\right|_{t=T} d x+\int_{0}^{T}\left(-\left\langle h_{2}(r) \partial_{t} \varphi, u\right\rangle_{\tilde{H}^{1}\left(\Omega^{(2)}, \Omega^{\prime}\right)}\right. \\
\left.+\int_{\Omega^{(2)}}\left(h_{2}(r) \nabla_{\tilde{x}} u \cdot \nabla_{\tilde{x}} \varphi+\widetilde{\omega}_{2} \varphi+2 h_{2}^{-1}(r) \widetilde{\kappa}_{2} \varphi\right) d x\right) d t \\
\mathrm{~L}_{1,2}(\varphi)=\int_{0}^{T} \int_{\Omega^{(2)}}\left(h_{2}(r) f_{0}+2 \delta_{\beta, 1} g_{0}\right) \varphi d x d t
\end{gathered}
$$

Using (4.5), we prove the existence and uniqueness of weak solutions to problems (4.25) and (4.26) as e.g. in [131].

Proof 1. Without any changes we repeat the first item of the proof of Theorem 4.1.
2. With the help of (4.6) and (4.8), we deduce from (4.11)

$$
\begin{aligned}
& \frac{1}{2}\left\|u_{\varepsilon}(T, \cdot)\right\|_{L^{2}\left(\Omega_{\varepsilon}\right)}^{2} \\
& +c_{0} \int_{0}^{T}\left(\int_{\Omega_{\varepsilon}}\left(\left|\nabla_{x} u_{\varepsilon}\right|^{2}+u_{\varepsilon}^{2}\right) d x+\varepsilon^{\alpha} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}} u_{\varepsilon}^{2} d \sigma_{x}+\varepsilon \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}} u_{\varepsilon}^{2} d \sigma_{x}\right) d t \\
& \quad \leq \int_{0}^{T}\left(-\omega(0) \int_{\Omega_{\varepsilon}} u_{\varepsilon} d x-\kappa_{2}(0) \varepsilon \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}} u_{\varepsilon} d \sigma_{x}\right. \\
& \left.+\int_{\Omega_{\varepsilon}} f_{\varepsilon} u_{\varepsilon} d x+\int_{\partial \Omega_{0} \cap\left\{r<r_{0}\right\}} q_{\varepsilon} u_{\varepsilon} d \tilde{x}+\varepsilon^{\beta} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\} \cup \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}} g_{\varepsilon} u_{\varepsilon} d \sigma_{x}\right) d t
\end{aligned}
$$

from where, using (4.2), (4.3), (4.4), and Lemma 4.1, it follows

$$
\begin{equation*}
\varepsilon \int_{0}^{T} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}} u_{\varepsilon}^{2} d \sigma_{x} d t \leq c_{1} \varepsilon^{1-\alpha} . \tag{4.27}
\end{equation*}
$$

Then thanks to (4.27) and Lemma 4.1 we deduce from (2.11) the estimate

$$
\int_{0}^{T} \int_{\Omega_{\varepsilon}^{(1)}} u_{\varepsilon}^{2} d x d t \leq c_{2} \varepsilon^{\min \{2,1-\alpha\}}
$$

which implies that

$$
\begin{equation*}
\tilde{u}_{\varepsilon}^{(1)} \longrightarrow 0 \text { strongly in } L^{2}\left((0, T) \times \Omega^{(1)}\right) \text { as } \varepsilon \rightarrow 0 . \tag{4.28}
\end{equation*}
$$

3. Similarly as in the second part of the proof of Theorem 4.1 we can show that $u_{2} \in L^{2}\left(0, T ; \widetilde{H}^{1}\left(\Omega^{(2)}\right)\right)$ and

$$
u_{2,2}=0, \quad u_{2, k}=\partial_{x_{k}} u_{2} \quad \text { a.e. in }(0, T) \times \Omega^{(2)}, \quad k=1,3 .
$$

Repeating the assertions of the third part of the proof of Theorem 4.1 and taking into account (4.28), we get

$$
\left.u_{0}\right|_{\Omega^{\prime}}=\left.u_{2}\right|_{\Omega^{\prime}}=0 \quad \text { a.e. in }(0, T) \times \Omega^{\prime} .
$$

4. Consider the following sets of functions:

$$
\begin{aligned}
& \mathrm{S}_{0}=\left\{\varphi_{0} \eta: \quad \varphi_{0} \in C^{\infty}\left(\overline{\Omega_{0}}\right),\left.\varphi_{0}\right|_{\Omega^{\prime}}=0, \quad \eta \in C^{1}([0, T]), \eta(T)=0\right\}, \\
& \mathrm{S}_{2}=\left\{\varphi_{2} \eta: \quad \varphi_{2} \in C^{\infty}\left(\overline{\Omega^{(2)}}\right),\left.\varphi_{2}\right|_{\Omega^{\prime}}=0, \quad \eta \in C^{1}([0, T]), \eta(T)=0\right\} .
\end{aligned}
$$

With the help of them, we define a function

$$
\Phi(t, x)= \begin{cases}\varphi_{0}(x) \eta(t), & (t, x) \in(0, T) \times \Omega_{0} \\ 0, & (t, x) \in(0, T) \times \Omega_{\varepsilon}^{(1)} \\ \varphi_{2}(x) \eta(t), & (t, x) \in(0, T) \times \Omega_{\varepsilon}^{(2)}\end{cases}
$$

Clearly, $\Phi \in W_{T}\left(\Omega_{\varepsilon}\right)$. We substitute $\Phi$ as a test function into (4.7) and utilize zeroextension operators. Then passing to the limit as $\varepsilon \rightarrow 0$ (if necessary we choose an appropriate subsequence) and taking into account (2.13), (4.9), (4.2), (4.3), (4.4), (2.16), Lemma 4.2, (4.28) and relations obtained in the items $\mathbf{1}$ and $\mathbf{3}$, we obtain

$$
\mathrm{B}_{1,0}\left(u_{0}, \varphi_{0} \eta, \omega_{0}\right)+\mathrm{B}_{1,2}\left(u_{2}, \varphi_{2} \eta, \widetilde{\omega}_{2}, \widetilde{\kappa}_{2}\right)=\mathrm{L}_{1,0}\left(\varphi_{0} \eta\right)+\mathrm{L}_{1,2}\left(\varphi_{2} \eta\right) .
$$

Obviously, the last identity is equivalent to the following two identities:

$$
\begin{align*}
& \mathrm{B}_{1,0}\left(u_{0}, \varphi_{0} \eta, \omega_{0}\right)=\mathrm{L}_{1,0}\left(\varphi_{0} \eta\right) \quad \forall \varphi_{0} \eta \in \mathrm{~S}_{0},  \tag{4.29}\\
& \mathrm{~B}_{1,2}\left(u_{2}, \varphi_{2}, \widetilde{\omega}_{2}, \widetilde{\kappa}_{2}\right)=\mathrm{L}_{1,2}\left(\varphi_{2}\right) \quad \forall \varphi_{2} \eta \in \mathrm{~S}_{2} . \tag{4.30}
\end{align*}
$$

The set $\mathrm{S}_{0}$ is dense in the space $W_{T}\left(\Omega_{0}, \Omega^{\prime}\right)$ of functions $\varphi$ such that $\left.\varphi\right|_{t=T}=0$, and the set $\mathrm{S}_{2}$ is dense in the space $\widetilde{W}_{T}\left(\Omega^{(2)}, \Omega^{\prime}\right)$ of functions $\varphi$ such that $\left.\varphi\right|_{t=T}=0$ (see [42, Lemma 1.12]). Those facts imply that $u_{0}$ is a weak solution to problem (4.25) and $u_{2}$ is a weak solution to problem (4.26) (see [131]) with still unknown functions $\omega_{0}, \widetilde{\omega}_{2}, \widetilde{\kappa}_{2}$.
5. In order to find them, we again use Minty-Browder method. Similarly as in the item 5 of the proof of Theorem 4.1 we find that

$$
\begin{equation*}
\mathrm{B}_{1, \varepsilon}\left(u_{\varepsilon}, u_{\varepsilon}\right) \longrightarrow \mathrm{B}_{1,0}\left(u_{0}, u_{0}, \omega_{0}\right)+\mathrm{B}_{1,2}\left(u_{2}, u_{2}, \widetilde{\omega}_{2}, \widetilde{\kappa}_{2}\right) \text { as } \varepsilon \rightarrow 0 \tag{4.31}
\end{equation*}
$$

Consider arbitrary $\varphi_{0} \in W_{T}\left(\Omega_{0}, \Omega^{\prime}\right), \varphi_{2} \in \widetilde{W}_{T}\left(\Omega^{(2)}, \Omega^{\prime}\right)$, and the inequality

$$
\begin{gathered}
\frac{1}{2} \int_{\Omega_{0}}\left(u_{\varepsilon}(T, x)-\varphi_{0}(T, x)\right)^{2} d x+\frac{1}{2} \int_{\Omega_{\varepsilon}^{(2)}}\left(u_{\varepsilon}(T, x)-\varphi_{2}(T, x)\right)^{2} d x \\
+\frac{1}{2} \int_{\Omega_{\varepsilon}^{(1)}} u_{\varepsilon}^{2}(T, x) d x+\int_{0}^{T}\left(\int_{\Omega_{\varepsilon}^{(1)}}\left|\nabla_{x} u_{\varepsilon}\right|^{2} d x+\int_{\Omega_{\varepsilon}^{(1)}}\left(k_{0}\left(u_{\varepsilon}\right)-k_{0}(0)\right) u_{\varepsilon} d x\right) d t \\
+\int_{0}^{T}\left(\int_{\Omega_{0}}\left|\nabla_{x} u_{\varepsilon}-\nabla_{x} \varphi_{0}\right|^{2} d x+\int_{\Omega_{\varepsilon}^{(2)}}\left(\left|\nabla_{\tilde{x}} u_{\varepsilon}-\nabla_{\tilde{x}} \varphi_{2}\right|^{2}+\left(\partial_{x_{2}} u_{\varepsilon}\right)^{2}\right) d x\right. \\
+\int_{\Omega_{0}}\left(k_{0}\left(u_{\varepsilon}\right)-k_{0}\left(\varphi_{0}\right)\right)\left(u_{\varepsilon}-\varphi_{0}\right) d x+\int_{\Omega_{\varepsilon}^{(2)}}\left(k_{0}\left(u_{\varepsilon}\right)-k_{0}\left(\varphi_{2}\right)\right)\left(u_{\varepsilon}-\varphi_{2}\right) d x \\
+\varepsilon^{\alpha} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}} \kappa_{1}\left(u_{\varepsilon}\right) u_{\varepsilon} d \sigma_{x} \\
\left.\quad+\varepsilon \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}}\left(\kappa_{2}\left(u_{\varepsilon}\right)-\kappa_{2}\left(\varphi_{2}\right)\right)\left(u_{\varepsilon}-\varphi_{2}\right) d \sigma_{x}\right) d t \geq 0 .
\end{gathered}
$$

Taking (4.31), (2.16), (4.14), (2.9), and Lemma 4.2 into account, we pass to the limit in the last inequality as $\varepsilon \rightarrow 0$. As a result, we get the inequality

$$
\begin{aligned}
& \frac{1}{2} \int_{\Omega_{0}}\left(u_{0}(T, x)-\varphi_{0}(T, x)\right)^{2} d x+\frac{1}{2} \int_{\Omega^{(2)}} h_{2}(r)\left(u_{2}(T, x)-\varphi_{2}(T, x)\right)^{2} d x \\
& \quad+\int_{0}^{T}\left(\int_{\Omega_{0}}\left|\nabla_{x} u_{0}-\nabla_{x} \varphi_{0}\right|^{2} d x+\int_{\Omega^{(2)}} h_{2}(r)\left|\nabla_{\tilde{x}} u_{2}-\nabla_{\tilde{x}} \varphi_{2}\right|^{2} d x\right. \\
& +\int_{\Omega_{0}}\left(\omega_{0}-k_{0}\left(\varphi_{0}\right)\right)\left(u_{0}-\varphi_{0}\right) d x+\int_{\Omega^{(2)}}\left(\widetilde{\omega}_{2}-h_{2}(r) k_{0}\left(\varphi_{2}\right)\right)\left(u_{2}-\varphi_{2}\right) d x \\
& \left.\quad+2 \int_{\Omega^{(2)}}\left(h_{2}^{-1}(r) \widetilde{\kappa}_{2}-\kappa_{2}\left(\varphi_{2}\right)\right)\left(u_{2}-\varphi_{2}\right) d x\right) d t \geq 0
\end{aligned}
$$

We set $\varphi_{0}=u_{0}-\lambda \psi_{0}, \varphi_{2}=u_{2}-\lambda \psi_{2}$ in this inequality, where $\lambda>0, \psi_{0}, \psi_{2}$ are arbitrary functions from $W_{T}\left(\Omega_{0}, \Omega^{\prime}\right)$ and $\widetilde{W}_{T}\left(\Omega^{(2)}, \Omega^{\prime}\right)$, respectively. This leads us to the inequality

$$
\begin{aligned}
& \lambda\left\{\frac{1}{2} \int_{\Omega_{0}} \psi_{0}^{2}(T, x) d x\right.+\frac{1}{2} \int_{\Omega^{(2)}} h_{2}(r) \psi_{2}^{2}(T, x) d x+\int_{0}^{T}\left(\int_{\Omega_{0}}\left|\nabla_{x} \psi_{0}\right|^{2} d x\right. \\
&+\left.\left.\int_{\Omega^{(2)}} h_{2}(r)\left|\nabla_{\tilde{x}} \psi_{2}\right|^{2} d x\right) d t\right\} \\
&+\int_{0}^{T}\left(\int_{\Omega_{0}}\left(\omega_{0}-k_{0}\left(u_{0}-\lambda \psi_{0}\right)\right) \psi_{0} d x+\int_{\Omega^{(2)}}\left(\widetilde{\omega}_{2}-h_{2}(r) k_{0}\left(u_{2}-\lambda \psi_{2}\right)\right) \psi_{2} d x\right. \\
&\left.+2 \int_{\Omega^{(2)}}\left(h_{2}^{-1}(r) \widetilde{\kappa}_{2}-\kappa_{2}\left(u_{2}-\lambda \psi_{2}\right)\right) \psi_{2} d x\right) d t \geq 0 .
\end{aligned}
$$

Now we pass to the limit as $\lambda \rightarrow 0$ taking into account continuity of $k_{0}$ and $\kappa_{2}$ :

$$
\begin{aligned}
\int_{0}^{T}\left(\int_{\Omega_{0}}\left(\omega_{0}-k_{0}\left(u_{0}\right)\right) \psi_{0} d x+\right. & \int_{\Omega^{(2)}}\left(\widetilde{\omega}_{2}-h_{2}(r) k_{0}\left(u_{2}\right)\right) \psi_{2} d x \\
& \left.+2 \int_{\Omega^{(2)}}\left(h_{2}^{-1}(r) \widetilde{\kappa}_{2}-\kappa_{2}\left(u_{2}\right)\right) \psi_{2} d x\right) d t \geq 0
\end{aligned}
$$

Substituting $\psi_{0}:=-\psi_{0}, \psi_{2}:=-\psi_{2}$, we see that in fact the equality holds. Since $\psi_{0} \in W_{T}\left(\Omega_{0}, \Omega^{\prime}\right)$ and $\psi_{2} \in \widetilde{W}_{T}\left(\Omega^{(2)}, \Omega^{\prime}\right)$ are arbitrary functions, we get

$$
\begin{align*}
& \omega_{0}=k_{0}\left(u_{0}\right) \quad \text { a.e. in }(0, T) \times \Omega_{0}, \\
& \widetilde{\omega}_{2}+2 h_{2}^{-1}(r) \widetilde{\kappa}_{2}=h_{2}(r) k_{0}\left(u_{2}\right)+2 \kappa_{2}\left(u_{2}\right) \text { a.e. in }(0, T) \times \Omega^{(2)} \text {. } \tag{4.32}
\end{align*}
$$

Thus, the first relation in (4.32) and identity (4.29) imply that the function $u_{0}$ is the weak solution to problem (4.25), and the second relation in (4.32) and identity (4.30) imply that $u_{2}$ is the weak solution of problem (4.26).
6. Since all of the above assertions remain valid for arbitrary subsequence $\left\{\varepsilon^{\prime}\right\}$ chosen at the beginning of the proof, the uniqueness of weak solutions to problems (4.25) and (4.26) implies that relations (4.24) hold. The theorem is proved.

### 4.2 Problem with Alternating Robin and Dirichlet Boundary Conditions

### 4.2.1 Statement of the Problem

Consider the following semilinear parabolic problem:

$$
\begin{cases}\partial_{t} v_{\varepsilon}(t, x)-\Delta_{x} v_{\varepsilon}(t, x)+k_{0}\left(v_{\varepsilon}\right)=f_{\varepsilon}, & (t, x) \in(0, T) \times \Omega_{\varepsilon},  \tag{4.33}\\ \partial_{\nu} v_{\varepsilon}(t, x)+\varepsilon^{\alpha} \kappa_{1}\left(v_{\varepsilon}\right)=\varepsilon^{\beta} g_{\varepsilon}(t, x), & (t, x) \in(0, T) \times \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}, \\ v_{\varepsilon}(t, x)=0, & (t, x) \in(0, T) \times \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}, \\ \partial_{\nu} v_{\varepsilon}(t, x)=0, & (t, x) \in(0, T) \times \partial \Omega_{\varepsilon} \cap\left\{r=r_{0}\right\}, \\ \partial_{\nu} v_{\varepsilon}(t, x)=q_{\varepsilon}(t, x), & (t, x) \in(0, T) \times \partial \Omega_{0} \cap\left\{r<r_{0}\right\}, \\ v_{\varepsilon}(0, x)=0, & x \in \Omega_{\varepsilon} .\end{cases}
$$

Here the functions $f_{\varepsilon}, g_{\varepsilon}, q_{\varepsilon}, k_{0}, \kappa_{1}$ satisfy the same conditions as in Sect. 4.1.1.
We introduce the space

$$
\begin{aligned}
W_{T}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}\right):= & \left\{\varphi \in L^{2}\left(0, T ; H^{1}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}\right)\right):\right. \\
& \left.\partial_{t} \varphi \in L^{2}\left(0, T ;\left(H^{1}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}\right)\right)^{*}\right)\right\}
\end{aligned}
$$

where the space $H^{1}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}\right)$ is defined in Sect. 2.1. It is known (see e.g., [42, Theorem 1.17]) that $W_{T}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}\right) \subset C\left([0, T] ; L^{2}\left(\Omega_{\varepsilon}\right)\right)$.

Definition 4.5 A function $v_{\varepsilon} \in W_{T}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}\right)$ is called a weak solution to problem (4.33) if $v_{\varepsilon}(0, x)=0$ and the integral identity

$$
\begin{equation*}
\mathrm{B}_{2, \varepsilon}\left(v_{\varepsilon}, \varphi\right)=\mathrm{L}_{2, \varepsilon}(\varphi) \tag{4.34}
\end{equation*}
$$

holds for any function $\varphi \in W_{T}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}\right)$, where

$$
\begin{aligned}
\mathrm{B}_{2, \varepsilon}\left(v_{\varepsilon}, \varphi\right) & =\left.\int_{\Omega_{\varepsilon}}\left(v_{\varepsilon} \varphi\right)\right|_{t=T} d x+\int_{0}^{T}\left(-\left\langle\partial_{t} \varphi, v_{\varepsilon}\right\rangle_{H^{1}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}\right)}\right. \\
& \left.+\int_{\Omega_{\varepsilon}}\left(\nabla_{x} v_{\varepsilon} \cdot \nabla_{x} \varphi+\omega\left(v_{\varepsilon}\right) \varphi\right) d x+\varepsilon^{\alpha} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}} \kappa_{1}\left(v_{\varepsilon}\right) \varphi d \sigma_{x}\right) d t \\
\mathrm{~L}_{2, \varepsilon}(\varphi)= & \int_{0}^{T}\left(\int_{\Omega_{\varepsilon}} f_{\varepsilon} \varphi d x+\int_{\partial \Omega_{0} \cap\left\{r<r_{0}\right\}} q_{\varepsilon} \varphi d \tilde{x}+\varepsilon^{\beta} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}} g_{\varepsilon} \varphi d \sigma_{x}\right) d t .
\end{aligned}
$$

Using (4.5), we prove the existence and uniqueness of the weak solution to problem (4.33) for each fixed $\varepsilon>0$ (see e.g. [131]).

### 4.2.2 Convergence Theorems

With the help of (4.8) similarly as in Sect.4.1.2, we prove a priory estimate.
Lemma 4.3 There exist positive constants $C_{0}$ and $\varepsilon_{0}$ such that for every $\varepsilon \in\left(0, \varepsilon_{0}\right)$ the following estimate for the weak solution $v_{\varepsilon}$ to problem (4.33) holds:

$$
\max _{0 \leq t \leq T}\left\|v_{\varepsilon}(t, \cdot)\right\|_{L^{2}\left(\Omega_{\varepsilon}\right)}+\left\|v_{\varepsilon}\right\|_{L^{2}\left(0, T ; H^{1}\left(\Omega_{\varepsilon}\right)\right)} \leq C_{0}
$$

Theorem 4.3 If $\alpha \geq 1$, then the solution $v_{\varepsilon}$ to problem (4.33) satisfies the relations

$$
\left.\begin{array}{rl}
v_{\varepsilon} & \xrightarrow{w} v_{0} \quad \text { weakly in } L^{2}\left(0, T ; H^{1}\left(\Omega_{0}\right)\right),  \tag{4.35}\\
\widetilde{v}_{\varepsilon}^{(1)} & \xrightarrow{w} h_{1} v_{1} \text { weakly in } L^{2}\left((0, T) \times \Omega^{(1)}\right), \\
\tilde{v}_{\varepsilon}^{(2)} \xrightarrow{w} 0 & \text { weakly in } L^{2}\left(0, T ; H^{1}\left(\Omega^{(2)}\right)\right)
\end{array}\right\} \quad \text { as } \varepsilon \rightarrow 0,
$$

where $v_{0} \in W_{T}\left(\Omega_{0}, \Omega^{\prime}\right)$ and it is a weak solution to problem (4.25), $v_{1} \in \widetilde{W}_{T}\left(\Omega^{(1)}\right.$, $\Omega^{\prime}$ ) and it is a weak solution to the problem

$$
\begin{cases}h_{1}(r) \partial_{t} v_{1}-\operatorname{div}_{\tilde{x}}\left(h_{1}(r) \nabla_{\tilde{x}} v_{1}\right)+h_{1}(r) k_{0}\left(v_{1}\right) &  \tag{4.36}\\ +2 \delta_{\alpha, 1} \kappa_{1}\left(v_{1}\right)=h_{1}(r) f_{0}+2 \delta_{\beta, 1} g_{0}, & (t, x) \in(0, T) \times \Omega^{(1)}, \\ \partial_{\nu} v_{1}=0, & (t, x) \in(0, T) \times \partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}, \\ v_{1}=0, & (t, x) \in(0, T) \times \Omega^{\prime}, \\ v_{1}(0, x)=0, & x \in \Omega^{(1)} .\end{cases}
$$

Definition 4.6 A function $v \in \widetilde{W}_{T}\left(\Omega^{(1)}, \Omega^{\prime}\right)$ is called a weak solution to problem (4.36) if it satisfies the initial condition $v(0, x)=0$ and the integral identity

$$
\mathrm{B}_{2,1}\left(v, \varphi, h_{1} k_{0}(v), h_{1} \kappa_{1}(v)\right)=\mathrm{L}_{2,1}(\varphi) \quad \forall \varphi \in \widetilde{W}_{T}\left(\Omega^{(1)}, \Omega^{\prime}\right),
$$

where

$$
\begin{aligned}
& \mathrm{B}_{2,1}\left(v, \varphi, \widetilde{\omega}_{1}, \widetilde{\kappa}_{1}\right)=\left.\int_{\Omega^{(1)}} h_{1}(r)(v \varphi)\right|_{t=T} d x+\int_{0}^{T}\left(-\left\langle\partial_{t} \varphi, h_{1}(r) v\right\rangle_{\tilde{H}^{1}\left(\Omega^{(1)}, \Omega^{\prime}\right)}\right. \\
&\left.+\int_{\Omega^{(1)}}\left(h_{1}(r) \nabla_{\tilde{x}} v \cdot \nabla_{\tilde{x} \varphi} \varphi+\widetilde{\omega}_{1} \varphi+2 \delta_{\alpha, 1} h_{1}^{-1}(r) \widetilde{\kappa}_{1} \varphi\right) d x\right) d t \\
& \mathrm{~L}_{2,1}(\varphi)=\int_{0}^{T} \int_{\Omega^{(1)}}\left(h_{1}(r) f_{0}+2 \delta_{\beta, 1} g_{0}\right) \varphi d x d t
\end{aligned}
$$

Due to the assumptions for the functions $f_{0}, g_{0}, k_{0}$, and $\kappa_{1}$, there exists a unique weak solution to problem (4.36) (see e.g., [131]).

Proof 1. Note that for any function $\varphi \in L^{2}\left(0, T ; H^{1}\left(\Omega_{\varepsilon}^{(2)}, \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}\right)\right)$ its zero-extension $\widetilde{\varphi}^{(2)}$ belongs to the space $L^{2}\left(0, T ; H^{1}\left(\Omega^{(2)}\right)\right)$. Inequality (2.12) and Lemma 4.3 imply that

$$
\left\|\widetilde{v}_{\varepsilon}^{(2)}\right\|_{L^{2}\left((0, T) \times \Omega^{(2)}\right)} \leq c_{0} \varepsilon\left\|\nabla_{x} v_{\varepsilon}\right\|_{L^{2}\left((0, T) \times \Omega_{\varepsilon}^{(2)}\right)} \leq c_{1} \varepsilon .
$$

Therefore, the last limit in (4.35) holds.
2. Lemma 4.3 and inequality (4.9) imply that there exists a subsequence $\left\{\varepsilon^{\prime}\right\} \subset\{\varepsilon\}$ (again denoted by $\{\varepsilon\}$ ) such that the following convergence holds:
as $\varepsilon \rightarrow 0(k=1,2,3)$.
Similar as in the proof of Theorem 4.1 we show that for every $t \in[0, T]$, there exists a subsequence $\left\{\varepsilon_{t}\right\} \subset\{\varepsilon\}$ such that

$$
\begin{gather*}
\left.\begin{array}{c}
v_{\varepsilon_{t}}(t, \cdot) \xrightarrow{w} v_{0}(t, \cdot) \\
\tilde{v}_{\varepsilon_{t}}^{(i)}(t, \cdot) \xrightarrow{w} h_{1} v_{1}(t, \cdot) \\
\text { weakly in } L^{2}\left(\Omega_{0}\right), \\
\text { weakly in } L^{2}\left(\Omega^{(1)}\right),
\end{array}\right\} \quad \text { as } \varepsilon \rightarrow 0, ~ \tag{4.38}
\end{gather*}
$$

and

- $v_{1,2}=0$ a.e. in $(0, T) \times \Omega^{(1)}$;
- there exist weak derivatives $\partial_{x_{k}} v_{1}=v_{1, k}$ a.e. in $(0, T) \times \Omega^{(1)}, k=1,3$;
- $\left.v_{0}\right|_{\Omega^{\prime}}=\left.v_{1}\right|_{\Omega^{\prime}}=0$ for a.e. $(t, x) \in(0, T) \times \Omega^{\prime}$.

3. Let us define a function

$$
\Phi(t, x)= \begin{cases}\varphi_{0}(x) \eta(t), & (t, x) \in(0, T) \times \Omega_{0} \\ \varphi_{1}(x) \eta(t), & (t, x) \in(0, T) \times \Omega_{\varepsilon}^{(1)}, \\ 0, & (t, x) \in(0, T) \times \Omega_{\varepsilon}^{(2)}\end{cases}
$$

where $\varphi_{0} \eta \in \mathrm{~S}_{0}$ (it is defined in the item $\mathbf{4}$ of the proof of Theorem 4.1) and $\varphi_{1} \eta$ belongs to the function set

$$
\mathrm{S}_{1}=\left\{\varphi_{1} \eta: \varphi_{1} \in C^{\infty}\left(\overline{\Omega^{(1)}}\right),\left.\varphi_{1}\right|_{\Omega^{\prime}}=0, \quad \eta \in C^{1}([0, T]), \eta(T)=0\right\} .
$$

Clearly, $\Phi \in W_{T}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}\right)$. Next we substitute $\Phi$ as a test function into (4.34) and utilize the zero-extension operators. Bearing in mind (2.13), (4.9), (4.2), (4.3), (4.4), (2.16), Lemma 4.2, and the relations, obtained in the previous parts of the proof, we pass to the limit as $\varepsilon \rightarrow 0$. As a result, we obtain

$$
\mathrm{B}_{1,0}\left(v_{0}, \varphi_{0} \eta, \omega_{0}\right)+\mathrm{B}_{2,1}\left(v_{1}, \varphi_{1} \eta, \widetilde{\omega}_{1}, \widetilde{\kappa}_{1}\right)=\mathrm{L}_{1,0}\left(\varphi_{0} \eta\right)+\mathrm{L}_{2,1}\left(\varphi_{1} \eta\right)
$$

Obviously, the last identity is equivalent to the following ones:

$$
\begin{gather*}
\mathrm{B}_{1,0}\left(v_{0}, \varphi_{0} \eta, \omega_{0}\right)=\mathrm{L}_{1,0}\left(\varphi_{0} \eta\right) \quad \forall \varphi_{0} \eta \in \mathrm{~S}_{0},  \tag{4.39}\\
\mathrm{~B}_{2,1}\left(v_{1}, \varphi_{1} \eta, \widetilde{\omega}_{1}, \widetilde{\kappa}_{1}\right)=\mathrm{L}_{2,1}\left(\varphi_{1} \eta\right) \quad \forall \varphi_{1} \eta \in \mathrm{~S}_{1} . \tag{4.40}
\end{gather*}
$$

The set $\mathrm{S}_{0}$ is dense in a set of functions $\varphi \in W_{T}\left(\Omega_{0}, \Omega^{\prime}\right)$ such that $\left.\varphi\right|_{t=T}=0$, and the set $\mathrm{S}_{1}$ is dense in a set of functions $\varphi \in \widetilde{W}_{T}\left(\Omega^{(1)}, \Omega^{\prime}\right)$ such that $\left.\varphi\right|_{t=T}=0$ (see [42, Lemma 1.12]). Thus, identity (4.39) implies that $v_{0} \in W_{T}\left(\Omega_{0}, \Omega^{\prime}\right)$ is a weak solution to problem (4.25) with still unknown function $\omega_{0}$, and identity (4.40) provides that $v_{1} \in \widetilde{W}_{T}\left(\Omega^{(1)}, \Omega^{\prime}\right)$ is a weak solution to problem (4.36) with unknown functions $\widetilde{\omega}_{1}$ and $\widetilde{\kappa}_{1}$.
4. Similarly as in the item $\mathbf{5}$ of the proof of Theorem 4.1 with the help of the inequality

$$
\begin{gathered}
\frac{1}{2} \int_{\Omega_{0}}\left(v_{\varepsilon}(T, x)-\varphi_{0}(T, x)\right)^{2} d x+\frac{1}{2} \int_{\Omega_{\varepsilon}^{(1)}}\left(v_{\varepsilon}(T, x)-\varphi_{1}(T, x)\right)^{2} d x \\
+\frac{1}{2} \int_{\Omega_{\varepsilon}^{(2)}}\left(v_{\varepsilon}(T, x)\right)^{2} d x+\int_{\Omega_{\varepsilon}^{(2)}}\left|\nabla_{x} v_{\varepsilon}\right|^{2} d x \\
+\int_{0}^{T}\left(\int_{\Omega_{0}}\left|\nabla_{x} v_{\varepsilon}-\nabla_{x} \varphi_{0}\right|^{2} d x+\int_{\Omega_{\varepsilon}^{(1)}}\left(\left|\nabla_{\tilde{x}} v_{\varepsilon}-\nabla_{\tilde{x}} \varphi_{1}\right|^{2}+\left(\partial_{x_{2}} v_{\varepsilon}\right)^{2}\right) d x\right. \\
+\int_{\Omega_{0}}\left(k_{0}\left(v_{\varepsilon}\right)-k_{0}\left(\varphi_{0}\right)\right)\left(v_{\varepsilon}-\varphi_{0}\right) d x+\int_{\Omega_{\varepsilon}^{(1)}}\left(k_{0}\left(v_{\varepsilon}\right)-k_{0}\left(\varphi_{1}\right)\right)\left(v_{\varepsilon}-\varphi_{1}\right) d x \\
\left.+\int_{\Omega_{\varepsilon}^{(2)}}\left(k_{0}\left(v_{\varepsilon}\right)-k_{0}(0)\right) v_{\varepsilon} d x+\varepsilon^{\alpha} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}}\left(\kappa_{1}\left(v_{\varepsilon}\right)-\kappa_{1}\left(\varphi_{1}\right)\right)\left(v_{\varepsilon}-\varphi_{1}\right) d \sigma_{x}\right) d t \geq 0
\end{gathered}
$$

(here $\varphi_{0}$ and $\varphi_{1}$ are arbitrary functions from the spaces $W_{T}\left(\Omega_{0}, \Omega^{\prime}\right)$ and $\widetilde{W}_{T}\left(\Omega^{(1)}\right.$, $\Omega^{\prime}$ ), respectively) we show that

$$
\begin{gathered}
\omega_{0}=k_{0}\left(v_{0}\right) \quad \text { a.e. in }(0, T) \times \Omega_{0} \\
\widetilde{\omega}_{1}+2 \delta_{\alpha, 1} h_{1}^{-1}(r) \widetilde{\kappa}_{1}=h_{1}(r) k_{0}\left(v_{1}\right)+2 \delta_{\alpha, 1} \kappa_{1}\left(v_{1}\right) \quad \text { a.e. in }(0, T) \times \Omega^{(1)} .
\end{gathered}
$$

Thus, $v_{0}$ and $v_{1}$ are weak solutions to problems (4.25) and (4.36), respectively. 5. Since all of the above assertions remain valid for arbitrary subsequence $\left\{\varepsilon^{\prime}\right\}$ chosen at the beginning of the proof, the uniqueness of weak solutions to problems (4.25) and (4.36) implies that relations (4.35) hold. The theorem is proved.

Now consider the case $\alpha<1$. Then assumption (4.6) is satisfied in this case.
Theorem 4.4 If $\alpha<1$, then for the solution $v_{\varepsilon}$ to problem (4.33) we have

$$
\left.\begin{array}{r}
v_{\varepsilon} \xrightarrow{w} v_{0} \text { weakly in } L^{2}\left(0, T ; H^{1}\left(\Omega_{0}\right)\right),  \tag{4.41}\\
\widetilde{v}_{\varepsilon}^{(1)} \longrightarrow 0 \text { strongly in } L^{2}\left((0, T) \times \Omega^{(1)}\right), \\
\tilde{v}_{\varepsilon}^{(2)} \xrightarrow{w} 0 \text { weakly in } L^{2}\left(0, T ; H^{1}\left(\Omega^{(2)}\right)\right)
\end{array}\right\} \text { as } \varepsilon \rightarrow 0,
$$

where $v_{0} \in L^{2}\left(0, T ; H^{1}\left(\Omega_{0}, \Omega^{\prime}\right)\right)$ and it is a weak solution to problem (4.25).
Proof We repeat the items $\mathbf{1}$ and $\mathbf{2}$ of the proof of Theorem 4.3. Also repeating assertions of the item $\mathbf{2}$ of the proof of Theorem 4.2, we can prove that

$$
\widetilde{\nu}_{\varepsilon}^{(1)} \longrightarrow 0 \text { strongly in } L^{2}\left((0, T) \times \Omega^{(1)}\right) \text { as } \varepsilon \rightarrow 0
$$

The first limit in (4.37) and compactness of the embedding $L^{2}\left(0, T ; H^{1}\left(\Omega_{0}\right)\right) \subset$ $L^{2}\left((0, T) \times \Omega_{0}\right)$ imply existence of a subsequence $\left\{\varepsilon^{\prime}\right\} \subset\{\varepsilon\}$ (again denoted by $\{\varepsilon\})$ such that

$$
v_{\varepsilon} \rightarrow v_{0} \quad \text { strongly in } L^{2}\left((0, T) \times \Omega_{0}\right) \text { and a.e. in }(0, T) \times \Omega_{0} .
$$

By virtue of the continuity of $k_{0}$, we have that

$$
k_{0}\left(v_{\varepsilon}\right) \longrightarrow k_{0}\left(v_{0}\right) \quad \text { a.e. in }(0, T) \times \Omega_{0} \text { as } \varepsilon \rightarrow 0
$$

Using [70, Lemma 1.3] and Lemma 4.3, we get $\omega_{0}=k_{0}\left(v_{0}\right)$ a.e. in $(0, T) \times \Omega_{0}$.
Let us define a function

$$
\Phi(t, x):= \begin{cases}\varphi_{0}(x) \eta(t), & (t, x) \in(0, T) \times \Omega_{0}, \\ 0, & (t, x) \in(0, T) \times \Omega_{\varepsilon}^{(1)} \cup \Omega_{\varepsilon}^{(2)},\end{cases}
$$

where $\varphi_{0} \eta \in \mathrm{~S}_{0}$ (it is defined in the item $\mathbf{4}$ of the proof of Theorem 4.1). Clearly, $\Phi \in W_{T}\left(\Omega_{\varepsilon}, \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}\right)$. We substitute $\Phi$ into integral identity (4.34) as a test function. Passing to the limit and taking into account the obtained relations, we
get the integral identity (4.39) for the function $v_{0}$. Since $\mathrm{S}_{0}$ is dense in a set of functions $\varphi \in W_{T}\left(\Omega_{0}, \Omega^{\prime}\right)$ such that $\left.\varphi\right|_{t=T}=0, v_{0}$ is a weak solution to problem (4.25) (see Definition 4.3).

The standard remark on the uniqueness of the weak solution to problem (4.25) completes the proof of the theorem.

### 4.3 Conclusions to this Chapter

The results obtained in this chapter show that the influence of the geometric structure of the thick junction $\Omega_{\varepsilon}$ and boundary conditions on the asymptotic behavior of the solutions to the semilinear parabolic problems remains the same as for the elliptic problems considered in Chap. 2 in the case if the parameter $\alpha \geq 1$ (see the conclusions to Chap. 2).

Indeed, in the case $\alpha \geq 1$, the homogenized problem for problem (4.1) is a nonstandard problem in the anisotropic Sobolev space $\widetilde{\mathbf{W}}_{T}$ of multivalued functions, and the nonlinear Robin boundary conditions are transformed (as $\varepsilon \rightarrow 0$ ) by the same way into two summands of the corresponding differential equations in the domains $\Omega^{(i)}, i=1,2$.

The case $\alpha<1$, which is not considered in Chap. 2, is qualitatively quite different. The initial problem (4.1) is divided (as $\varepsilon \rightarrow 0$ ) into two independent problems in the domains $\Omega_{0}$ and $\Omega^{(2)}$.

If we interpret problem (4.1) as a mathematical model of the heat radiation, then conditions $\alpha<1$ and $\kappa_{1}(0)=0$ mean that there is an intensive heat exchange on the surfaces of the thin discs from the first level with cold environment. As a result, the thin discs from the first level are quickly cooled down, cooling at the same time the junction's body (as a result, we have the homogeneous Dirichlet condition on $\Omega^{\prime}$ in problems (4.25) and (4.26)).

Similar conclusions are valid for problem (4.33). In the case $\alpha \geq 1$, the initial problem is divided (as $\varepsilon \rightarrow 0$ ) into two independent problems thanks to the homogeneous Dirichlet boundary conditions on the surfaces of the thin discs from the second level. If $\alpha<1$, the solution to problem (4.33) tends to zero in the thin discs from both levels.

# Chapter 5 <br> Asymptotic Approximations for Solutions to Semilinear Elliptic and Parabolic Problems 

Here another approach to study the asymptotic behavior of solutions to BVPs in thick two-level junctions of the type 3:2:2 is demonstrated. We consider two semilinear problems (elliptic and parabolic) in the thick junction $\Omega_{\varepsilon}$ described in Sect. 2.1. Nonlinear perturbed Robin boundary conditions are imposed on the surfaces of the thin discs from both levels in each of the problems. Approximations for the solutions to those problems are constructed and asymptotic estimates in Sobolev spaces are proved. Two-scale asymptotic expansion method and the method of matching asymptotic expansions are used.

### 5.1 Semilinear Elliptic Problem

### 5.1.1 Statement of the Problem

In $\Omega_{\varepsilon}$, we consider the semilinear boundary-value problem

$$
\begin{cases}-\Delta_{x} u_{\varepsilon}(x)+k_{0}\left(u_{\varepsilon}(x)\right)=f_{\varepsilon}(x), & x \in \Omega_{\varepsilon},  \tag{5.1}\\ \partial_{\nu} u_{\varepsilon}(x)+\varepsilon^{\alpha} \kappa_{1}\left(u_{\varepsilon}(x)\right)=\varepsilon^{\beta} g_{\varepsilon}(x), & x \in \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}, \\ \partial_{\nu} u_{\varepsilon}(x)+\varepsilon \kappa_{2}\left(u_{\varepsilon}(x)\right)=\varepsilon^{\beta} g_{\varepsilon}(x), & x \in \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}, \\ \partial_{\nu} u_{\varepsilon}(x)+\kappa_{2}\left(u_{\varepsilon}(x)\right)=0, & x \in \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}, \\ \partial_{\nu} u_{\varepsilon}(x)=0, & x \in \partial \Omega_{\varepsilon} \cap\left\{r=r_{0}\right\}, \\ \partial_{x_{2}}^{p} u_{\varepsilon}\left(x_{1}, 0, x_{3}\right)=\partial_{x_{2}}^{p} u_{\varepsilon}\left(x_{1}, l, x_{3}\right), & p=0,1, x \in \partial \Omega_{0} \cap\left\{r<r_{0}\right\} .\end{cases}
$$

Here $\alpha \geq 1, \beta \geq 1$ are parameters; the functions $k_{0}, \kappa_{1}$ and $\kappa_{2}$ satisfy assumptions (4.5); $f_{\varepsilon} \in L^{2}\left(\Omega_{\varepsilon}\right), g_{\varepsilon} \in H^{1}\left(\Omega^{(2)}\right)$, and

$$
\begin{equation*}
\left\|g_{\varepsilon}\right\|_{L^{2}\left(\Omega^{(2)}\right)}+\left\|\partial_{x_{2}} g_{\varepsilon}\right\|_{L^{2}\left(\Omega^{(2)}\right)} \leq C_{0} . \tag{5.2}
\end{equation*}
$$

The thick junction $\Omega_{\varepsilon}$ is described in Sect. 2.1. In this chapter, we additionally assume that the functions $h_{1}, h_{2}$ describing the geometric structure of the thin discs are constant in a neighborhood of $r_{0}$, i.e., there exists a constant $\delta_{0}>0$ such that $h_{i}(r)=h_{i}\left(r_{0}\right)$ for all $r \in\left[r_{0}, r_{0}+\delta_{0}\right], i=1,2$.

Definition 5.1 A function

$$
u_{\varepsilon} \in H_{\mathrm{per}}^{1}\left(\Omega_{\varepsilon}\right):=\left\{\varphi \in H^{1}\left(\Omega_{\varepsilon}\right): \varphi\left(x_{1}, 0, x_{3}\right)=\varphi\left(x_{1}, l, x_{3}\right), r<r_{0}\right\}
$$

is called a weak solution to problem (5.1) if for all $\varphi \in H_{\text {per }}^{1}\left(\Omega_{\varepsilon}\right)$ the identity

$$
\begin{align*}
& \int_{\Omega_{\varepsilon}}\left(\nabla_{x} u_{\varepsilon} \cdot \nabla_{x} \varphi+k_{0}\left(u_{\varepsilon}\right) \varphi\right) d x+\varepsilon^{\alpha} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}} \kappa_{1}\left(u_{\varepsilon}\right) \varphi d \sigma_{x} \\
& \quad+\varepsilon \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}} \kappa_{2}\left(u_{\varepsilon}\right) \varphi d \sigma_{x}+\int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}} \kappa_{2}\left(u_{\varepsilon}\right) \varphi d \sigma_{x}=\mathrm{L}_{\varepsilon}(\varphi) \tag{5.3}
\end{align*}
$$

holds. Here

$$
\begin{equation*}
\mathrm{L}_{\varepsilon}(\varphi):=\int_{\Omega_{\varepsilon}} f_{\varepsilon} \varphi d x+\varepsilon^{\beta} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\} \cup \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}} g_{\varepsilon} \varphi d \sigma_{x} \tag{5.4}
\end{equation*}
$$

Similarly as in [90], we can prove that for every fixed $\varepsilon>0$ there exists a unique weak solution to problem (5.1).

### 5.1.2 Formal Asymptotic Expansions

Only in this section, we assume that the functions $f_{\varepsilon}, g_{\varepsilon}$ are independent of $\varepsilon$, i.e., $f_{\varepsilon}=f_{0}$ in $\Omega_{0} \cup \Omega^{(2)}$ and $g_{\varepsilon}=g_{0}$ in $\Omega^{(2)}$, and they are smooth enough.

## Outer Expansions

We propose the following asymptotic ansatzes for the solution $u_{\varepsilon}$ :

$$
\begin{equation*}
u_{\varepsilon}(x) \approx u_{0}^{+}(x)+\varepsilon u_{1}^{+}(x)+\ldots, \quad \text { in } \Omega_{0} \tag{5.5}
\end{equation*}
$$

and

$$
\begin{equation*}
u_{\varepsilon}(x) \approx u_{0}^{i,-}(x)+\varepsilon u_{1}^{i,-}\left(x, \frac{x_{2}}{\varepsilon}-j\right)+\varepsilon^{2} u_{2}^{i,-}\left(x, \frac{x_{2}}{\varepsilon}-j\right)+\ldots, \quad \text { in } \Omega_{\varepsilon}^{(i)}(j) \tag{5.6}
\end{equation*}
$$

where $j \in\{0,1, \ldots, N-1\}, i=1$, 2. Expansions (5.5) and (5.6) are usually called the outer expansions.

Using Taylor's formula, we get

$$
\begin{equation*}
k_{0}\left(u_{\varepsilon}(x)\right)=k_{0}\left(u_{0}^{+}(x)\right)+\mathscr{O}(\varepsilon), \quad \varepsilon \rightarrow 0 \quad\left(x \in \Omega_{0}\right) . \tag{5.7}
\end{equation*}
$$

Substituting (5.5) into the first equation to problem (5.1) and into the boundary conditions on $\partial \Omega_{0} \cap\left\{r<r_{0}\right\}$, utilizing (5.7), and collecting coefficients at the same powers of $\varepsilon$, we obtain the following relations for the function $u_{0}^{+}$:

$$
\begin{cases}-\Delta_{x} u_{0}^{+}+k_{0}\left(u_{0}^{+}\right)=f_{0}, & x \in \Omega_{0}, \\ \partial_{x_{2}}^{p} u_{0}^{+}\left(x_{1}, 0, x_{3}\right)=\partial_{x_{2}}^{p} u_{0}^{+}\left(x_{1}, l, x_{3}\right), & x \in \partial \Omega_{0} \cap\left\{r<r_{0}\right\}, \quad p=0,1 .\end{cases}
$$

Now let us find relations for the main terms of the outer expansions in the domains $\Omega_{\varepsilon}^{(i)}, i=1,2$. Considering the functions $u_{k}^{i,-}\left(x, \xi_{2}-j\right)$ to be smooth, we write down their Taylor series with respect to the "slow" variable $x_{2}$ in a neighborhood of $x_{2}=\varepsilon\left(j+l_{i}\right)$ for fixed $j \in\{0,1, \ldots, N-1\}$ and $i=1,2$. Then (5.6) reads
$u_{\varepsilon}(x) \approx u_{0}^{i,-}\left(x_{1}, \varepsilon\left(j+l_{i}\right), x_{3}\right)+\sum_{k=1}^{\infty} \varepsilon^{k} U_{k}^{i,-}\left(x_{1}, \varepsilon\left(j+l_{i}\right), x_{3}, \frac{x_{2}}{\varepsilon}-j\right), \quad x \in \Omega_{\varepsilon}^{(i)}(j)$,
where

$$
\begin{align*}
U_{k}^{i,-}\left(x_{1}, \varepsilon\left(j+l_{i}\right), x_{3}, \xi_{2}-j\right) & =\sum_{m=0}^{k-1} \frac{\left(\xi_{2}-j-l_{i}\right)^{m}}{m!} \frac{\partial^{m} u_{k-m}^{i,-}}{\partial x_{2}^{m}}\left(x_{1}, \varepsilon\left(j+l_{i}\right), x_{3}, \xi_{2}-j\right) \\
& +\frac{\left(\xi_{2}-j-l_{i}\right)^{k}}{k!} \frac{\partial^{k} u_{0}^{i,-}}{\partial x_{2}^{k}}\left(x_{1}, \varepsilon\left(j+l_{i}\right), x_{3}, \xi_{2}-j\right) \tag{5.9}
\end{align*}
$$

and $\xi_{2}=x_{2} / \varepsilon$ is a "fast" variable.
Again exploiting Taylor's formula, we get

$$
\begin{equation*}
k_{0}\left(u_{\varepsilon}(x)\right)=k_{0}\left(u_{0}^{i,-}\left(x_{1}, \varepsilon\left(j+l_{i}\right), x_{3}\right)\right)+\mathscr{O}(\varepsilon), \quad \varepsilon \rightarrow 0\left(x \in \Omega_{\varepsilon}^{(i)}(j)\right) \tag{5.10}
\end{equation*}
$$

Substituting (5.8) into (5.1) instead of $u_{\varepsilon}$, taking into account (2.8), (2.17), (5.7), and the fact that the Laplace operator for the variables $\left(\tilde{x}, \xi_{2}\right)$ reads $\Delta_{x}=\Delta_{\tilde{x}}+$ $\varepsilon^{-2} \frac{\partial^{2}}{\partial \xi_{2}^{2}}$, and then collecting coefficients at the same powers of $\varepsilon$, we obtain BVPs with respect to $\xi_{2}$ for the functions $U_{k}^{i,-}$.

The function $U_{1}^{i,-}$ should be a solution to the problem

$$
\begin{cases}\partial_{\xi_{2} \xi_{2}}^{2} U_{1}^{i,-}=0, & \xi_{2} \in \varepsilon^{-1} I_{\varepsilon}^{(i)}\left(j, h_{i}(r)\right)  \tag{5.11}\\ \partial_{\xi_{2}} U_{1}^{i,-}=0, & \xi_{2} \in \varepsilon^{-1} \partial I_{\varepsilon}^{(i)}\left(j, h_{i}(r)\right)\end{cases}
$$

where the variables $\tilde{x}$ are involved here as parameters; the interval $I_{\varepsilon}^{(i)}\left(j, h_{i}(r)\right)$ is defined in Sect. 2.1; $r \in\left(r_{0}, r_{i}\right)$. Problem (5.11) implies that $U_{1}^{i,-}$ is independent of $\xi_{2}$. Thus $U_{1}^{i,-}$ is equal to some function $\varphi_{1}^{(i)}\left(x_{1}, \varepsilon\left(j+l_{i}\right), x_{3}\right), r \in\left(r_{0}, r_{i}\right)$, which will be defined later. Then according to (5.9), we have

$$
\begin{align*}
u_{1}^{i,-}\left(x_{1}, \varepsilon\left(j+l_{i}\right), x_{3}, \frac{x_{2}}{\varepsilon}-j\right)= & \varphi_{1}^{(i)}\left(x_{1}, \varepsilon\left(j+l_{i}\right), x_{3}\right) \\
& -\left(\frac{x_{2}}{\varepsilon}-j-l_{i}\right) \partial_{x_{2}} u_{0}^{i,-}\left(x_{1}, \varepsilon\left(j+l_{i}\right), x_{3}\right) \tag{5.12}
\end{align*}
$$

Boundary-value problems for $U_{2}^{1,-}$ and $U_{2}^{2,-}$ look as follows:

$$
\begin{aligned}
& -\partial_{\xi_{2} \xi_{2}}^{2} U_{2}^{1,--}=\left.\left(\Delta_{\tilde{x}} u_{0}^{1,-}-k_{0}\left(u_{0}^{1,-}\right)+f_{0}\right)\right|_{x_{2}=\varepsilon\left(j+l_{1}\right)}, \quad \xi_{2} \in \varepsilon^{-1} I_{\varepsilon}^{(1)}\left(j, h_{1}(r)\right), \\
& \pm\left.\partial_{\xi_{2}} U_{2}^{1,-}\right|_{\xi_{2}=j+l_{1} \pm \frac{h_{1}(r)}{2}}=\left.\left(2^{-1} \nabla_{\tilde{x}} h_{1} \cdot \nabla_{\tilde{x}} u_{0}^{1,-}-\delta_{\alpha, 1} \kappa_{1}\left(u_{0}^{1,-}\right)+\delta_{\beta, 1} g_{0}\right)\right|_{x_{2}=\varepsilon\left(j+l_{1}\right)},
\end{aligned}
$$

and

$$
\begin{aligned}
& -\partial_{\xi_{2} \xi_{2}}^{2} U_{2}^{2,-}=\left.\left(\Delta_{\tilde{x}} u_{0}^{2,-}-\omega\left(u_{0}^{2,-}\right)+f_{0}\right)\right|_{x_{2}=\varepsilon\left(j+l_{2}\right)}, \quad \xi_{2} \in \varepsilon^{-1} I_{\varepsilon}^{(2)}\left(j, h_{2}(r)\right), \\
& \pm\left.\partial_{\xi_{2}} U_{2}^{2,-}\right|_{\xi_{2}=j+l_{2} \pm \frac{h_{2}(r)}{2}}=\left.\left(2^{-1} \nabla_{\tilde{x}} h_{2} \cdot \nabla_{\tilde{x}} u_{0}^{2,-}-\kappa_{2}\left(u_{0}^{2,-}\right)+\delta_{\beta, 1} g_{0}\right)\right|_{x_{2}=\varepsilon\left(j+l_{2}\right)} .
\end{aligned}
$$

Here the variables $\tilde{x}$ are parameters. Solvability conditions for these problems read

$$
\begin{equation*}
-\operatorname{div}_{\tilde{x}}\left(h_{1}(r) \nabla_{\tilde{x}} u_{0}^{1,-}\right)+h_{1}(r) k_{0}\left(u_{0}^{1,-}\right)+2 \delta_{\alpha, 1} \kappa_{1}\left(u_{0}^{1,-}\right)=h_{1}(r) f_{0}+2 \delta_{\beta, 1} g_{0} \tag{5.13}
\end{equation*}
$$

where $r \in\left(r_{0}, r_{1}\right), x_{2}=\varepsilon\left(j+l_{1}\right)$, and

$$
\begin{equation*}
-\operatorname{div}_{\tilde{x}}\left(h_{2}(r) \nabla_{\tilde{x}} u_{0}^{2,-}\right)+h_{2}(r) k_{0}\left(u_{0}^{2,-}\right)+2 \kappa_{2}\left(u_{0}^{2,-}\right)=h_{2}(r) f_{0}+2 \delta_{\beta, 1} g_{0} \tag{5.14}
\end{equation*}
$$

where $r \in\left(r_{0}, r_{2}\right), x_{2}=\varepsilon\left(j+l_{2}\right)$, respectively.
Substituting (5.8) into the Robin boundary conditions on $\partial \Omega_{\varepsilon}^{(i)} \cap\left\{r=r_{i}\right\}$ and utilizing (5.10), we obtain the relations

$$
\begin{align*}
\partial_{r} u_{0}^{1,-}=0, & r=r_{1}, x_{2}=\varepsilon\left(j+l_{1}\right), \\
\partial_{r} u_{0}^{2,-}+\kappa_{2}\left(u_{0}^{2,-}\right)=0, & r=r_{2}, x_{2}=\varepsilon\left(j+l_{2}\right) . \tag{5.15}
\end{align*}
$$

In order to find relations on the joint zone $\Omega^{\prime}$, we will use the method of matched asymptotic expansions for the outer expansions (5.5), (5.6), and an inner expansion which is constructed in the next section.

## Inner Expansion

If we pass to the "fast" variables $\xi=\left(\xi_{1}, \xi_{2}\right)=\left(-\frac{r-r_{0}}{\varepsilon}, \frac{x_{2}}{\varepsilon}\right)$ in $\delta_{0}$-neighborhood of the joint zone $\Omega^{\prime}$ and send $\varepsilon$ to zero, then due to the additional assumption made in this chapter the cross section of the periodicity cell is transformed into a domain $\Pi=\Pi^{+} \cup \Pi_{1}^{-} \cup \Pi_{2}^{-}$(see Fig. 5.1), which is a union of semiinfinite strips


Fig. 5.1 The domain $\Pi$ and the thick junction $\Omega_{\varepsilon}$

$$
\begin{gathered}
\Pi^{+}=\left\{\xi \in \mathbb{R}^{2}: \xi_{1}>0, \xi_{2} \in(0,1)\right\} \\
\Pi_{i}^{-}=\left\{\xi \in \mathbb{R}^{2}: \xi_{1} \leq 0, \xi_{2} \in I_{i}\left(r_{0}\right)\right\}, \quad i=1,2
\end{gathered}
$$

The interval $I_{i}(s)$ is defined in Sect. 2.1.
The Laplace operator for the variables $(\xi, \theta)$ reads

$$
\begin{equation*}
\Delta=\varepsilon^{-2}\left(\frac{\partial^{2}}{\partial \xi_{1}^{2}}+\frac{\partial^{2}}{\partial \xi_{2}^{2}}\right)-\varepsilon^{-1} \frac{1}{r_{0}-\varepsilon \xi_{1}} \frac{\partial}{\partial \xi_{1}}+\frac{1}{\left(r_{0}-\varepsilon \xi_{1}\right)^{2}} \frac{\partial^{2}}{\partial \theta^{2}} \tag{5.16}
\end{equation*}
$$

We propose the following ansatz for the solution $u_{\varepsilon}$ in a neighborhood of $\Omega^{\prime}$ :

$$
\begin{array}{r}
\left.u_{\varepsilon}(x) \approx u_{0}^{+}\right|_{\Omega^{\prime}}(x)+\varepsilon\left(-\left.\left\{\eta\left(x_{2}, \theta\right) Z_{1}(\xi)+\left(1-\eta\left(x_{2}, \theta\right)\right) Z_{2}(\xi)\right\} \partial_{r} u_{0}^{+}\right|_{\Omega^{\prime}}(x)\right. \\
\left.+\left.Z_{3}(\xi) \partial_{x_{2}} u_{0}^{+}\right|_{\Omega^{\prime}}(x)\right)\left.\right|_{\xi_{1}=-\frac{r-r_{0}}{\varepsilon}, \xi_{2}=\frac{x_{2}}{\varepsilon}}+\ldots, \tag{5.17}
\end{array}
$$

where $Z_{1}, Z_{2}, Z_{3}$ are 1-periodic with respect to $\xi_{2}$ functions in $\Pi$, and $\eta$ is some function. Those functions are unknown and will be defined later. The expansion (5.17) is called an inner expansion for the solution $u_{\varepsilon}$.

Remark 5.1 One of the main difficulties in the construction of asymptotic approximations for solutions of BVPs in thick junctions is to guess an ansatz for the inner expansion. In our case, the summands $\left.\eta Z_{1} \partial_{r} u_{0}^{+}\right|_{\Omega^{\prime}}$ and $\left.(1-\eta) Z_{2} \partial_{r} u_{0}^{+}\right|_{\Omega^{\prime}}$ are to eliminate discrepancies on $\partial \Omega_{\varepsilon} \cap\left\{r=r_{0}\right\}$. We need two of them due to the fact that we have a thick two-level junction. The multipliers $\eta$ and $1-\eta$ are to satisfy the matching condition. The summand $\left.Z_{3} \partial_{x_{2}} u_{0}^{+}\right|_{\Omega^{\prime}}$ is to eliminate discrepancies on $\partial \Omega_{\varepsilon}^{(i)} \cap\left\{r_{0}<r<r_{i}\right\}$ (in a neighborhood of the joint zone).

Substituting (5.17) into the differential equation of problem (5.1) and into the proper boundary conditions, taking into account (5.16), and collecting coefficients
of the same powers of $\varepsilon$, we obtain junction-layer problems for the functions $\left\{Z_{i}\right\}$. So, the functions $Z_{1}$ and $Z_{2}$ are solutions to the problem

$$
\begin{cases}-\Delta_{\xi} Z(\xi)=0, & \xi \in \Pi,  \tag{5.18}\\ \partial_{\xi_{2}} Z(\xi)=0, & \xi \in\left(\partial \Pi_{1}^{-} \cup \partial \Pi_{2}^{-}\right) \cap\left\{\xi \in \mathbb{R}^{2}: \xi_{1}<0\right\} \\ \partial_{\xi_{1}} Z(\xi)=0, & \xi \in \partial \Pi \cap\left\{\xi \in \mathbb{R}^{2}: \xi_{1}=0\right\}, \\ \partial_{\xi_{2}}^{p} Z\left(\xi_{1}, 0\right)=\partial_{\xi_{2}}^{p} Z\left(\xi_{1}, 1\right), & p=0,1, \xi_{1}>0,\end{cases}
$$

and $Z_{3}$ is a solution to the problem

$$
\begin{cases}-\Delta_{\xi} Z_{3}(\xi)=0, & \xi \in \Pi,  \tag{5.19}\\ \partial_{\xi_{2}} Z_{3}(\xi)=-1, & \xi \in\left(\partial \Pi_{1}^{-} \cup \partial \Pi_{2}^{-}\right) \cap\left\{\xi \in \mathbb{R}^{2}: \xi_{1}<0\right\} \\ \partial_{\xi_{1}} Z_{3}(\xi)=0, & \xi \in \partial \Pi \cap\left\{\xi \in \mathbb{R}^{2}: \xi_{1}=0\right\}, \\ \partial_{\xi_{2}}^{p} Z_{3}\left(\xi_{1}, 0\right)=\partial_{\xi_{2}}^{p} Z\left(\xi_{1}, 1\right), & p=0,1, \xi_{1}>0\end{cases}
$$

The main asymptotic relations for solutions to those problems can be obtained from general results on asymptotic behavior of solutions to elliptic BVPs in unbounded domains (see e.g., [63, 66, 122]). However, we can obtain more precise relations for the asymptotics of $Z_{1}, Z_{2}, Z_{3}$ similarly as was done in [79, 108].

Consider a Sobolev space
$H_{\mathrm{loc}}^{1}(\Pi)=\left\{\varphi: \Pi \mapsto \mathbb{R}: \forall R>0 \varphi \in H^{1}\left(\Pi_{R}\right), \varphi\left(\xi_{1}, 0\right)=\varphi\left(\xi_{1}, 1\right) \forall \xi_{1}>0\right\}$,
where $\Pi_{R}=\left\{\xi \in \Pi:-R<\xi_{1}<R\right\}$.
Statement 1. There exist two solutions $Z_{1}, Z_{2} \in H_{\mathrm{loc}}^{1}(\Pi)$ to problem (5.18) with the differentiable asymptotics

$$
\begin{align*}
& Z_{1}(\xi)= \begin{cases}\xi_{1}+\mathscr{O}\left(e^{-2 \pi \xi_{1}}\right), & \xi_{1} \rightarrow+\infty, \xi_{2} \in(0,1) \\
h_{1}^{-1}\left(r_{0}\right) \xi_{1}+c_{1}^{(1)}+\mathscr{O}\left(e^{\pi h_{1}^{-1}\left(r_{0}\right) \xi_{1}}\right), & \xi_{1} \rightarrow-\infty, \xi_{2} \in I_{1}\left(r_{0}\right) \\
c_{1}^{(2)}+\mathscr{O}\left(e^{\pi h_{2}^{-1}\left(r_{0}\right) \xi_{1}}\right), & \xi_{1} \rightarrow-\infty, \xi_{2} \in I_{2}\left(r_{0}\right)\end{cases}  \tag{5.20}\\
& Z_{2}(\xi)= \begin{cases}\xi_{1}+\mathscr{O}\left(e^{-2 \pi \xi_{1}},\right. & \xi_{1} \rightarrow+\infty, \xi_{2} \in(0,1) \\
c_{2}^{(1)}+\mathscr{O}\left(e^{\pi h_{1}^{-1}\left(r_{0}\right) \xi_{1}}\right), & \xi_{1} \rightarrow-\infty, \xi_{2} \in I_{1}\left(r_{0}\right) \\
h_{2}^{-1}\left(r_{0}\right) \xi_{1}+c_{2}^{(2)}+\mathscr{O}\left(e^{\pi h_{2}^{-1}\left(r_{0}\right) \xi_{1}}\right), & \xi_{1} \rightarrow-\infty, \xi_{2} \in I_{2}\left(r_{0}\right)\end{cases} \tag{5.21}
\end{align*}
$$

where $c_{1}^{(i)}, c_{2}^{(i)}, i=1,2$, are some constants.
Another solution to problem (5.18) with polynomial growth at infinity can be represented as a linear combination $c_{0}+c_{1} Z_{1}+c_{2} Z_{2}$.

Statement 2. There exists a unique solution $Z_{3} \in H_{\mathrm{loc}}^{1}(\Pi)$ to problem (5.19) with the differentiable asymptotics

$$
Z_{3}(\xi)= \begin{cases}\mathscr{O}\left(e^{-2 \pi \xi_{1}}\right), & \xi_{1} \rightarrow+\infty, \xi_{2} \in(0,1)  \tag{5.22}\\ -\xi_{2}+l_{1}+c_{3}^{(1)}+\mathscr{O}\left(e^{\pi h_{1}^{-1}\left(r_{0}\right) \xi_{1}}\right), & \xi_{1} \rightarrow-\infty, \xi_{2} \in I_{1}\left(r_{0}\right) \\ -\xi_{2}+l_{2}+c_{3}^{(2)}+\mathscr{O}\left(e^{\pi h_{2}^{-1}\left(r_{0}\right) \xi_{1}}\right), & \xi_{1} \rightarrow-\infty, \xi_{2} \in I_{2}\left(r_{0}\right)\end{cases}
$$

where $c_{3}^{(1)}, c_{3}^{(2)}$ are some constants.
Another solution to problem (5.19) with polynomial growth at infinity can be represented as $c_{0}+Z_{3}$.

Now let us check the matching conditions for outer expansions (5.5), (5.6), and inner expansion (5.17), namely (see [54,55]), the main terms of the asymptotics of the outer expansions as $r \rightarrow r_{0} \mp$ have to coincide with the main terms of the asymptotics of the inner expansion as $\xi_{1} \rightarrow \pm \infty$.

The asymptotics of $u_{0}^{+}$in a neighborhood of $\left(r_{0}, \varepsilon\left(j+l_{i}\right), \theta\right) \in \Omega^{\prime}$ as $r \rightarrow r_{0}-$, $x_{2} \rightarrow \varepsilon\left(j+l_{i}\right)(i=1,2)$ are

$$
u_{0}^{+}+\varepsilon\left(\left(\xi_{2}-j-l_{i}\right) \partial_{x_{2}} u_{0}^{+}-\xi_{1} \partial_{r} u_{0}^{+}\right), \quad r=r_{0}, \quad x_{2}=\varepsilon\left(j+l_{i}\right)
$$

Taking into account the asymptotics of $Z_{1}, Z_{2}, Z_{3}$ as $\xi_{1} \rightarrow+\infty$ (see (5.20), (5.21), (5.22)), we see that the matching conditions for expansions (5.5) and (5.17) holds.

The first terms of the asymptotics for the outer expansions (5.6) as $r \rightarrow r_{0}+$, $x_{2} \rightarrow \varepsilon\left(j+l_{i}\right)(i=1,2)$ are

$$
\begin{equation*}
u_{0}^{i,-}+\varepsilon\left(\varphi_{1}^{(i)}-\xi_{1} \partial_{r} u_{0}^{i,-}\right), \quad r=r_{0}, \quad x_{2}=\varepsilon\left(j+l_{i}\right) \tag{5.23}
\end{equation*}
$$

In accordance with (5.20), (5.21), and (5.22) the first terms of the asymptotics of the inner expansion (5.17) as $\xi_{1} \rightarrow-\infty, \xi_{2} \rightarrow j+l_{1}$ are

$$
\begin{equation*}
u_{0}^{+}+\varepsilon\left(-\left\{\left(h_{1}^{-1}\left(r_{0}\right) \xi_{1}+c_{1}^{(1)}\right) \eta+c_{2}^{(1)}(1-\eta)\right\} \partial_{r} u_{0}^{+}+c_{3}^{(1)} \partial_{x_{2}} u_{0}^{+}\right) \tag{5.24}
\end{equation*}
$$

and as $\xi_{1} \rightarrow-\infty, \xi_{2} \rightarrow j+l_{2}$ are

$$
\begin{equation*}
\left.u_{0}^{+}+\varepsilon\left(-\left\{c_{1}^{(2)} \eta+\left(h_{2}^{-1}\left(r_{0}\right) \xi_{1}+c_{2}^{(2)}\right)(1-\eta)\right\} \partial_{r} u_{0}^{+}\right)+c_{3}^{(2)} \partial_{x_{2}} u_{0}^{+}\right) . \tag{5.25}
\end{equation*}
$$

Comparing the first terms in (5.23), (5.24), and (5.25), we obtain the equalities

$$
\begin{equation*}
u_{0}^{+}=u_{0}^{i,-}, \quad r=r_{0}, \quad x_{2}=\varepsilon\left(j+l_{i}\right), \quad i=1,2, \quad j=\overline{0, N-1} \tag{5.26}
\end{equation*}
$$

the comparing the second ones gives

$$
\begin{equation*}
\varphi_{1}^{(i)}=c_{3}^{(i)} \partial_{x_{2}} u_{0}^{+}, \quad r=r_{0}, \quad x_{2}=\varepsilon\left(j+l_{i}\right), i=1,2, j=\overline{0, N-1}, \tag{5.27}
\end{equation*}
$$

and

$$
\begin{array}{rlll}
h_{1}^{-1}\left(r_{0}\right) \eta \partial_{r} u_{0}^{+}=\partial_{r} u_{0}^{1,-}, & r=r_{0}, & x_{2}=\varepsilon\left(j+l_{1}\right), & j=\overline{0, N-1}, \\
h_{2}^{-1}\left(r_{0}\right)(1-\eta) \partial_{r} u_{0}^{+}=\partial_{r} u_{0}^{2,-}, & r=r_{0}, & x_{2}=\varepsilon\left(j+l_{2}\right), & j=\overline{0, N-1} . \tag{5.28}
\end{array}
$$

Since the points $\left\{\varepsilon\left(j+l_{i}\right): j=\overline{0, N-1}\right\}, i=1,2$, form the $\varepsilon$-net in the interval $(0, l)$, we can spread Eqs. (5.12), (5.13), (5.14) into $\Omega^{(i)}, i=1,2$, respectively; relations (5.15) over $\partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}$ and $\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}$ respectively; and Eqs. (5.26), (5.27), and (5.28) over $\Omega^{\prime}$. As a result, we deduce

$$
\begin{equation*}
\eta\left(x_{2}, \theta\right)=\frac{h_{1}\left(r_{0}\right) \partial_{r} u_{0}^{1,-}}{\partial_{r} u_{0}^{+}}, \quad x \in \Omega^{\prime} \tag{5.29}
\end{equation*}
$$

(for points where $\left.\partial_{r} u_{0}^{+}\right|_{\Omega^{\prime}}=0$ we set $\eta\left(x_{2}, \theta\right)=1$ );

$$
\begin{equation*}
u_{0}^{+}=u_{0}^{i,-}, \quad \partial_{r} u_{0}^{+}=h_{1}\left(r_{0}\right) \partial_{r} u_{0}^{1,-}+h_{2}\left(r_{0}\right) \partial_{r} u_{0}^{2,-}, \quad x \in \Omega^{\prime} \tag{5.30}
\end{equation*}
$$

and

$$
\begin{equation*}
\varphi_{1}^{(i)}(x)=c_{3}^{(i)} \partial_{x_{2}} u_{0}^{i,-}(x), \quad x \in \Omega^{(i)}, i=1,2 . \tag{5.31}
\end{equation*}
$$

### 5.1.3 The Homogenized Problem

With the help of the first terms $u_{0}^{+}, u_{0}^{1,-}$, and $u_{0}^{2,-}$ of the ansatzes (5.5) and (5.6) we define a multivalued function $\mathbf{u}_{0}=\left(u_{0}^{+}, u_{0}^{1,-}, u_{0}^{2,-}\right)$. Thanks to relations obtained above, we conclude that $\mathbf{u}_{0}$ should be a solution to the homogenized problem

$$
\begin{cases}-\Delta_{x} u_{0}^{+}+k_{0}\left(u_{0}^{+}\right)=f_{0}, & \text { in } \Omega_{0},  \tag{5.32}\\ \partial_{x_{2}}^{p} u_{0}^{+}\left(x_{1}, 0, x_{3}\right)=\partial_{x_{2}}^{p} u_{0}^{+}\left(x_{1}, l, x_{3}\right), & \text { on } \partial \Omega_{0} \cap\left\{r<r_{0}\right\}, p=0,1, \\ -\operatorname{div}_{\tilde{x}}\left(h_{1} \nabla_{\tilde{x}} u_{0}^{1,-}\right)+h_{1} k_{0}\left(u_{0}^{1,-}\right) & \\ +2 \delta_{\alpha, 1} \kappa_{1}\left(u_{0}^{1,-}\right)=h_{1} f_{0}+2 \delta_{\beta, 1} g_{0}, & \text { in } \Omega^{(1)}, \\ \partial_{\nu} u_{0}^{1,-}=0, & \text { on } \partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}, \\ -\operatorname{div}_{\tilde{x}}\left(h_{2} \nabla_{\tilde{x}} u_{0}^{2,-}\right)+h_{2} k_{0}\left(u_{0}^{2,-}\right) & \\ +2 \kappa_{2}\left(u_{0}^{2,-}\right)=h_{2} f_{0}+2 \delta_{\beta, 1} g_{0}, & \text { in } \Omega^{(2)}, \\ \partial_{\nu} u_{0}^{2,-}+\kappa_{2}\left(u_{0}^{2,-}\right)=0, & \text { on } \partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}, \\ u_{0}^{+}=u_{0}^{1,-}=u_{0}^{2,-}, & \text { on } \Omega^{\prime}, \\ \partial_{r} u_{0}^{+}=\sum_{i=1}^{2} h_{i}\left(r_{0}\right) \partial_{r} u_{0}^{i,-}, & \text { on } \Omega^{\prime} .\end{cases}
$$

Definition 5.2 A function $\mathbf{u}=\left(u_{0}, u_{1}, u_{2}\right) \in \widetilde{\mathbf{H}}_{\text {per }}$ is called a weak solution to problem (5.32) if the integral identity

$$
\begin{gathered}
\int_{\Omega_{0}}\left(\nabla_{x} u_{0} \cdot \nabla_{x} p_{0}+k_{0}\left(u_{0}\right) p_{0}\right) d x+\sum_{i=1}^{2} \int_{\Omega^{(i)}} h_{i}\left(\nabla_{\tilde{x}} u_{i} \cdot \nabla_{\tilde{x}} p_{i}+k_{0}\left(u_{i}\right) p_{i}\right) d x \\
+2 \delta_{\alpha, 1} \int_{\Omega^{(1)}} \kappa_{1}\left(u_{1}\right) p_{1} d x+2 \int_{\Omega^{(2)}} \kappa_{2}\left(u_{2}\right) p_{2} d x+h_{2}\left(r_{2}\right) \int_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}} \kappa_{2}\left(u_{2}\right) p_{2} d \sigma_{x} \\
=\int_{\Omega_{0}} f_{0} p_{0} d x+\sum_{i=1}^{2} \int_{\Omega^{(i)}}\left(h_{i} f_{0}+2 \delta_{\beta, 1} g_{0}\right) p_{i} d x
\end{gathered}
$$

holds for all functions $\mathbf{p}=\left(p_{0}, p_{1}, p_{2}\right) \in \widetilde{\mathbf{H}}_{\text {per }}$ (the space $\widetilde{\mathbf{H}}_{\text {per }}$ is defined in Sect. 3.4.1).
From the theory of monotone operators (see e.g. [90, 131]) and assumptions (4.5), it follows that there exists a unique weak solution to problem (5.32).

### 5.1.4 Asymptotic Approximation and Estimates

Consider a smooth cut-off function $\chi_{0}(r)$, which is equal to 1 if $\left|r-r_{0}\right|<\delta / 2$ and to 0 if $\left|r-r_{0}\right|>\delta$, where $\delta \in\left(0, \delta_{0}\right)$ is some fixed number.

With the help of $\mathbf{u}_{0}$ and the solutions $Z_{1}, Z_{2}, Z_{3}$ to problems (5.18) and (5.19), respectively, we construct the following approximation function $R_{\varepsilon}$ :

$$
\begin{equation*}
R_{\varepsilon}(x)=R_{\varepsilon}^{+}(x)=u_{0}^{+}(x)+\varepsilon \chi_{0}(r) \mathscr{Z}^{+}\left(-\frac{r-r_{0}}{\varepsilon}, \frac{x_{2}}{\varepsilon}, x_{2}, \theta\right), \quad x \in \Omega_{0}, \tag{5.33}
\end{equation*}
$$

where

$$
\mathscr{Z}^{+}\left(\xi, x_{2}, \theta\right)=-\left.\sum_{i=1}^{2} h_{i}\left(r_{0}\right) Z_{i}(\xi) \partial_{r} u_{0}^{i,-}\right|_{\Omega^{\prime}}+\left.Z_{3}(\xi) \partial_{x_{2}} u_{0}^{+}\right|_{\Omega^{\prime}}+\left.\xi_{1} \partial_{r} u_{0}^{+}\right|_{\Omega^{\prime}}
$$

and

$$
\begin{align*}
& R_{\varepsilon}(x)=R_{\varepsilon}^{i,-}(x)=u_{0}^{i,-}(x)+\varepsilon\left(\left(Y_{i}\left(\frac{x_{2}}{\varepsilon}\right)+c_{3}^{(i)}\right) \partial_{x_{2}} u_{0}^{i,-}(x)\right. \\
&\left.+\chi_{0}(r) \mathscr{Z}^{i,-}\left(-\frac{r-r_{0}}{\varepsilon}, \frac{x_{2}}{\varepsilon}, x_{2}, \theta\right)\right), x \in \Omega_{\varepsilon}^{(i)}(j), \tag{5.34}
\end{align*}
$$

where

$$
\begin{aligned}
& \mathscr{Z}^{i,-}\left(\xi, x_{2}, \theta\right)=-\left.\sum_{i=1}^{2} h_{i}\left(r_{0}\right) Z_{i}(\xi) \partial_{r} u_{0}^{i,-}\right|_{\Omega^{\prime}} \\
& \quad+\left.\left(Z_{3}(\xi)-Y_{i}\left(\xi_{2}\right)-c_{3}^{(i)}\right) \partial_{x_{2}} u_{0}^{+}\right|_{\Omega^{\prime}}+\left.\xi_{1} \partial_{r} u_{0}^{i,-}\right|_{\Omega^{\prime}}, \quad i=1,2 ; \quad j=\overline{0, N-1}
\end{aligned}
$$

In fact we sum the outer expansions with the inner expansion subtracting the common part of their asymptotics, because it is summed twice. Due to (5.29)-(5.31), the approximation function $R_{\varepsilon} \in H^{1}\left(\Omega_{\varepsilon}\right)$.

Theorem 5.1 Suppose that in addition to the assumptions made in Sect. 5.1.1, the following conditions hold: $f_{0} \in H^{3}\left(\Omega_{0} \cup \Omega^{(2)}\right) ; \partial_{x_{2}}^{p} f_{0}\left(x_{1}, 0, x_{3}\right)=\partial_{x_{2}}^{p} f_{0}\left(x_{1}, l, x_{3}\right)$ for $x \in \partial \Omega_{0} \cap\left\{r<r_{0}\right\}$ and $p=0,1 ; g_{0} \in H^{1}\left(\Omega^{(2)}\right)$ and it vanishes at a neighborhood of the joint zone $\Omega^{\prime}$.

Thenfor any $\mu>0$ there exist positive constants $\varepsilon_{0}, C_{1}$ such thatfor all values $\varepsilon \in$ $\left(0, \varepsilon_{0}\right)$ the difference between the solution $u_{\varepsilon}$ to problem (5.1) and the approximating function $R_{\varepsilon}$ defined by (5.33) and (5.34) satisfies the following estimate:

$$
\begin{align*}
\left\|u_{\varepsilon}-R_{\varepsilon}\right\|_{H^{1}\left(\Omega_{\varepsilon}\right)} \leq C_{1}\left(\left\|f_{0}-f_{\varepsilon}\right\|_{L^{2}\left(\Omega_{\varepsilon}\right)}\right. & +\delta_{\beta, 1}\left\|g_{0}-g_{\varepsilon}\right\|_{L^{2}\left(\Omega^{(2)}\right)} \\
& \left.+\varepsilon^{1-\mu}+\varepsilon^{\alpha-1+\delta_{\alpha, 1}}+\left(1-\delta_{\beta, 1}\right) \varepsilon^{\beta-1}\right) \tag{5.35}
\end{align*}
$$

Proof 1. First we find discrepancies in $\Omega_{0}$. The first relation in (5.32) implies that

$$
\partial_{x_{2} x_{2}}^{2} u_{0}^{+}(x)=-\Delta_{\tilde{x}} u_{0}^{+}(x)+k_{0}\left(u_{0}^{+}(x)\right)-f_{0}(x), \quad x \in \Omega_{0},
$$

whence due to the second relation in (5.32) we conclude that

$$
\partial_{x_{2} x_{2}}^{2} u_{0}^{+}\left(x_{1}, 0, x_{3}\right)=\partial_{x_{2} x_{2}}^{2} u_{0}^{+}\left(x_{1}, l, x_{3}\right), \quad x \in \partial \Omega_{0} \cap\left\{r<r_{0}\right\} .
$$

Consequently, according to the properties of the solutions $Z_{1}, Z_{2}, Z_{3}$, the function $R_{\varepsilon}^{+}$satisfies the boundary conditions of problem (5.1) on $\partial \Omega_{\varepsilon} \cap \partial \Omega_{0}$.

It is easy to verify that

$$
\begin{equation*}
\Delta_{x}\left(\chi_{0}(r) \varphi(x)\right)=\operatorname{div}_{\tilde{x}}\left(\varphi(x) \nabla_{\tilde{x}} \chi_{0}(r)\right)+\nabla_{\tilde{x}} \chi_{0}(r) \cdot \nabla_{\tilde{x}} \varphi(x)+\chi_{0}(r) \Delta_{x} \varphi(x) . \tag{5.36}
\end{equation*}
$$

Utilizing (5.16), (5.32), and (5.36), we obtain the equality

$$
\begin{align*}
&-\Delta_{x} R_{\varepsilon}^{+}(x)+k_{0}\left(R_{\varepsilon}^{+}\right)-f_{\varepsilon}(x)=f_{0}(x)-f_{\varepsilon}(x)+k_{0}\left(R_{\varepsilon}^{+}\right)-k_{0}\left(u_{0}^{+}(x)\right) \\
&+\chi_{0}(r)\left(r^{-1} \partial_{\xi_{1}} \mathscr{Z}^{+}\left(\xi, x_{2}, \theta\right)-2 \partial_{\xi_{2} x_{2}}^{2} \mathscr{Z}^{+}\left(\xi, x_{2}, \theta\right)\right) \\
&-\varepsilon \operatorname{div}_{\tilde{x}}\left(\left.\mathscr{Z}^{+}\right|_{\xi_{1}=-\left(r-r_{0}\right) / \varepsilon} \nabla_{\tilde{x}} \chi_{0}(r)\right)+\chi_{0}^{\prime}(r) \partial_{\xi_{1}} \mathscr{Z}{ }^{+}\left(\xi, x_{2}, \theta\right)  \tag{5.37}\\
&-\varepsilon \chi_{0}(r) \partial_{x_{2} x_{2}}^{2} \mathscr{Z}^{+}\left(\xi, x_{2}, \theta\right)-\varepsilon r^{-2} \chi_{0}(r) \partial_{\theta \theta}^{2} \mathscr{Z}^{+}\left(\xi, x_{2}, \theta\right) \quad x \in \Omega_{0},
\end{align*}
$$

where $\xi=\left(\xi_{1}, \xi_{2}\right), \xi_{1}=-\frac{r-r_{0}}{\varepsilon}, \xi_{2}=\frac{x_{2}}{\varepsilon}$.

Multiplying this equality by a test function $\psi \in H_{\text {per }}^{1}\left(\Omega_{\varepsilon}\right)$ and then integrating it over $\Omega_{0}$, we get

$$
\begin{gathered}
\int_{\Omega_{0}}\left(\nabla_{x} R_{\varepsilon}^{+} \cdot \nabla_{x} \psi+k_{0}\left(R_{\varepsilon}^{+}\right) \psi\right) d x-\int_{\Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{0}\right\} \cup \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{0}\right\}} \partial_{r} R_{\varepsilon}^{+} \psi d \sigma_{x}-\int_{\Omega_{0}} f_{\varepsilon} \psi d x \\
=I_{0}^{+}(\varepsilon, \psi)+\ldots+I_{3}^{+}(\varepsilon, \psi)+I_{7}^{+}(\varepsilon, \psi),
\end{gathered}
$$

where

$$
\begin{aligned}
& I_{0}^{+}(\varepsilon, \psi)=\int_{\Omega_{0}}\left(f_{0}-f_{\varepsilon}\right) \psi d x, \\
& I_{1}^{+}(\varepsilon, \psi)=\int_{\Omega_{0}} \chi_{0}\left(r^{-1} \partial_{\xi_{1}} \mathscr{Z}^{+}-\partial_{x_{2} \xi_{2}}^{2} \mathscr{Z}^{+}\right) \psi d x, \\
& I_{2}^{+}(\varepsilon, \psi)=\varepsilon \int_{\Omega_{0}} \mathscr{Z}^{+} \nabla_{\tilde{x}} \chi_{0} \cdot \nabla_{\tilde{x}} \psi d x+\int_{\Omega_{0}} \chi_{0}^{\prime} \partial_{\xi_{1}} \mathscr{Z}+\psi d x, \\
& I_{3}^{+}(\varepsilon, \psi)=\varepsilon \int_{\Omega_{0}} \chi_{0} \partial_{x_{2}} \mathscr{Z}^{+} \partial_{x_{2}} \psi d x+\varepsilon \int_{\Omega_{0}} r^{-2} \chi_{0} \partial_{\theta} \mathscr{Z}^{+} \partial_{\theta} \psi d x, \\
& I_{7}^{+}(\varepsilon, \psi)=\int_{\Omega_{0}}\left(k_{0}\left(R_{\varepsilon}^{+}\right)-k_{0}\left(u_{0}^{+}\right)\right) \psi d x .
\end{aligned}
$$

2. Now let us find discrepancies in the thin discs. Direct calculations show that

$$
\begin{array}{lr}
\partial_{r} R_{\varepsilon}^{1,-}=0 & \text { on } \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{1}\right\}, \\
\partial_{r} R_{\varepsilon}^{2,-}=-\kappa_{2}\left(u_{0}^{2,--}\right)-\varepsilon\left(Y_{2}\left(\frac{x_{2}}{\varepsilon}\right)+c_{3}^{(2)}\right) \partial_{x_{2}} \kappa_{2}\left(u_{0}^{2,-}\right) & \text { on } \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}, \tag{5.38}
\end{array}
$$

and

$$
\begin{equation*}
\partial_{r} R_{\varepsilon}^{i,-}=\varepsilon\left(Y_{i}\left(\frac{x_{2}}{\varepsilon}\right)+z_{3}^{(i)}\right) \partial_{r x_{2}}^{2} u_{0}^{i,-}+\partial_{r} R_{\varepsilon}^{+}, \quad x \in \Omega_{\varepsilon}^{(i)} \cap\left\{r=r_{0}\right\}, i=1,2 . \tag{5.39}
\end{equation*}
$$

Bearing in mind (2.8) and the fact that the functions $h_{i}$ are constant in the neighborhood of $\Omega_{0}$, we deduce that

$$
\begin{align*}
\partial_{\nu} R_{\varepsilon}^{i,-}=\varepsilon\left(N_{\varepsilon}^{(i)}(r)\right)^{-1}( & \pm\left(Y_{i}\left(\frac{x_{2}}{\varepsilon}\right)+c_{3}^{(i)}\right) \partial_{x_{2} x_{2}}^{2} u_{0}^{i,-} \pm \chi_{0} \partial_{x_{2}}\left(\left.\mathscr{Z}^{i,-}\right|_{\xi_{2}=x_{2} / \varepsilon}\right) \\
& \left.-\frac{1}{2} \nabla_{\tilde{x}} h_{i} \cdot \nabla_{\tilde{x}}\left(u_{0}^{i,-}+\varepsilon\left(Y_{i}\left(\frac{x_{2}}{\varepsilon}\right)+c_{3}^{(i)}\right) \partial_{x_{2}} u_{0}^{i,-}\right)\right) \tag{5.40}
\end{align*}
$$

for a.e. $x \in \partial \Omega_{\varepsilon}^{(i)}(j) \cap\left\{r_{0}<r<r_{i}\right\}, i=1,2$, where " + " ("-") in " $\pm$ " indicates the right (left) part of the lateral surface of $j$ th thin disc.

With the help of (5.16) and (5.32), we get

$$
\begin{aligned}
& -\Delta_{x} R_{\varepsilon}^{i,-}(x)+k_{0}\left(R_{\varepsilon}^{i,-}\right)-f_{\varepsilon}(x)=f_{0}(x)-f_{\varepsilon}(x)+k_{0}\left(R_{\varepsilon}^{i,-}\right)-k_{0}\left(u_{0}^{i,-}(x)\right) \\
+ & \nabla_{\tilde{x}}\left(\ln h_{i}(r)\right) \cdot \nabla_{\tilde{x}} u_{0}^{i,-}(x)-2\left(\delta_{i, 1} \delta_{\alpha, 1}+\delta_{i, 2}\right) h_{i}^{-1}(r) \kappa_{i}\left(u_{0}^{i,-}(x)\right)+2 \delta_{\beta, 1} h_{i}^{-1}(r) g_{0}(x)
\end{aligned}
$$

$$
\begin{aligned}
& -\varepsilon \operatorname{div}_{x}\left(\left(Y_{i}\left(\frac{x_{2}}{\varepsilon}\right)+z_{3}^{(i)}\right) \nabla_{x}\left(\partial_{x_{2}} u_{0}^{i,-}(x)\right)\right) \\
- & \varepsilon \Delta_{x}\left(\chi_{0}(r) \mathscr{Z}^{i,-}\left(-\frac{r-r_{0}}{\varepsilon}, \frac{x_{2}}{\varepsilon}, x_{2}, \theta\right)\right), \quad x \in \Omega_{\varepsilon}^{(i)}, i=1,2 .
\end{aligned}
$$

Using (5.36), we rewrite the last summand similarly as in (5.37). Then multiplying those equalities with a test function $\psi \in H_{\text {per }}^{1}\left(\Omega_{\varepsilon}\right)$, integrating it over $\Omega_{\varepsilon}^{(i)}$, and taking into account (2.9), (5.39), (5.40), (5.38), we obtain the identities

$$
\begin{aligned}
\int_{\Omega_{\varepsilon}^{(1)}}\left(\nabla_{x} R_{\varepsilon}^{1,-} \cdot \nabla_{x} \psi+k_{0}\left(R_{\varepsilon}^{1,-}\right) \psi\right) d x+\varepsilon^{\alpha} & \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}} \kappa_{1}\left(R_{\varepsilon}^{1,-}\right) \psi d \sigma_{x} \\
+\int_{\Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{0}\right\}} \partial_{r} R_{\varepsilon}^{+} \psi d \sigma_{x}-\int_{\Omega_{\varepsilon}^{(1)}} f_{\varepsilon} \psi d x & -\varepsilon^{\beta} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}} g_{\varepsilon} \psi d \sigma_{x} \\
= & I_{0}^{1,-}(\varepsilon, \psi)+\ldots+I_{7}^{1,-}(\varepsilon, \psi)
\end{aligned}
$$

and

$$
\begin{aligned}
\int_{\Omega_{\varepsilon}^{(2)}}\left(\nabla_{x} R_{\varepsilon}^{2,-} \cdot \nabla_{x} \psi\right. & \left.+k_{0}\left(R_{\varepsilon}^{2,-}\right) \psi\right) d x+\varepsilon \int_{\partial \Omega_{\varepsilon}^{(2) \cap\left\{r_{0}<r<r_{2}\right\}}} \kappa_{2}\left(R_{\varepsilon}^{2,-}\right) \psi d \sigma_{x} \\
+ & \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}} \kappa_{2}\left(R_{\varepsilon}^{2,-}\right) \psi d \sigma_{x}+\int_{\Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{0}\right\}} \partial_{r} R_{\varepsilon}^{+} \psi d \sigma_{x}-\int_{\Omega_{\varepsilon}^{(2)}} f_{\varepsilon} \psi d x \\
& -\varepsilon^{\beta} \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r>r_{0}\right\}} g_{\varepsilon} \psi d \sigma_{x}=I_{0}^{2,-}(\varepsilon, \psi)+\ldots+I_{7}^{2,-}(\varepsilon, \psi)
\end{aligned}
$$

for all $\psi \in H_{\text {per }}^{1}\left(\Omega_{\varepsilon}\right)$, where
$I_{0}^{i,-}(\varepsilon, \psi)=\int_{\Omega_{\varepsilon}^{(i)}}\left(f_{0}-f_{\varepsilon}\right) \psi d x$,
$I_{1}^{i,-}(\varepsilon, \psi)=\int_{\Omega_{\varepsilon}^{(i)}} \chi_{o}\left(r^{-1} \partial_{\xi_{1}} \mathscr{Z}^{i,-}-\partial_{x_{2} \xi_{2}}^{2} \mathscr{Z}^{i,-}\right) \psi d x$,
$I_{2}^{i,-}(\varepsilon, \psi)=\varepsilon \int_{\Omega_{\varepsilon}^{(i)}} \mathscr{Z}^{i,-} \nabla_{\tilde{x}} \chi_{0} \cdot \nabla_{\tilde{x}} \psi d x+\int_{\Omega_{\varepsilon}^{(i)}} \chi_{0}^{\prime} \partial_{\xi_{1}} \mathscr{Z}^{i,-} \psi d x$,
$I_{3}^{i,-}(\varepsilon, \psi)=\varepsilon \int_{\Omega_{\varepsilon}^{(i)}} \chi_{0} \partial_{x_{2}} \mathscr{Z}^{i,-} \partial_{x_{2}} \psi d x+\varepsilon \int_{\Omega_{\varepsilon}^{(i)}} r^{-2} \chi_{0} \partial_{\theta} \mathscr{Z}^{i,-} \partial_{\theta} \psi d x$,
$I_{4}^{i,-}(\varepsilon, \psi)=\varepsilon \int_{\Omega_{\varepsilon}^{(i)}} Y_{i}\left(\frac{x_{2}}{\varepsilon}\right) \partial_{x_{2}}\left(\psi \nabla_{\tilde{x}} u_{0}^{i,-} \cdot \nabla_{\tilde{x}} \ln h_{i}\right) d x+$
$\varepsilon \int_{\Omega_{\varepsilon}^{(i)}}\left(Y_{i}\left(\frac{x_{2}}{\varepsilon}\right)+z_{3}^{(i)}\right) \nabla_{x}\left(\partial_{x_{2}} u_{0}^{i,-}\right) \cdot \nabla_{x} \psi d x, \quad i=1,2$,
$I_{5}^{1,-}(\varepsilon, \psi)=2 \delta_{\beta, 1} \int_{\Omega_{\varepsilon}^{(1)}} h_{1}^{-1} g_{0} \psi d x-\varepsilon^{\beta} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}} g_{\varepsilon} \psi d \sigma_{x}$,
$I_{5}^{2,-}(\varepsilon, \psi)=2 \delta_{\beta, 1} \int_{\Omega_{\varepsilon}^{(2)}} h_{2}^{-1} g_{0} \psi d x-\varepsilon^{\beta} \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}} g_{\varepsilon} \psi d \sigma_{x}$,
$I_{6}^{1,-}(\varepsilon, \psi)=-2 \delta_{\alpha, 1} \int_{\Omega_{\varepsilon}^{(1)}} h_{1}^{-1} \kappa_{1}\left(u_{0}^{1,-}\right) \psi d x+\varepsilon^{\alpha} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}} \kappa_{1}\left(R_{\varepsilon}^{1,-}\right) \psi d \sigma_{x}$,

$$
\begin{aligned}
& I_{6}^{2,-}(\varepsilon, \psi)=-2 \int_{\Omega_{\varepsilon}^{(2)}} h_{2}^{-1} \kappa_{2}\left(u_{0}^{2,-}\right) \psi d x+\varepsilon \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}} \kappa_{2}\left(R_{\varepsilon}^{2,-}\right) \psi d \sigma_{x} \\
& \quad+\int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}}\left(\kappa_{2}\left(R_{\varepsilon}^{2,-}\right)-\kappa_{2}\left(u_{0}^{2,-}\right)-\varepsilon\left(Y_{2}\left(\frac{x_{2}}{\varepsilon}\right)+c_{3}^{(2)}\right) \partial_{x_{2}} \kappa_{2}\left(u_{0}^{2,-}\right)\right) \psi d \sigma_{x}, \\
& I_{7}^{i,-}(\varepsilon, \psi)=\int_{\Omega_{\varepsilon}^{(i)}}\left(k_{0}\left(R_{\varepsilon}^{i,-}\right)-k_{0}\left(u_{0}^{i,-}\right)\right) \psi d x, \quad i=1,2 .
\end{aligned}
$$

3. Now we prove the main asymptotic estimate. Summing the integral identities obtained in the previous parts of the proof, we see that the function $R_{\varepsilon}$ satisfies the integral identity

$$
\begin{gathered}
\int_{\Omega_{\varepsilon}}\left(\nabla_{x} R_{\varepsilon} \cdot \nabla_{x} \psi+k_{0}\left(R_{\varepsilon}\right) \psi\right) d x+\varepsilon^{\alpha} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}} \kappa_{1}\left(R_{\varepsilon}\right) \psi d \sigma_{x} \\
+\varepsilon \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}} \kappa_{2}\left(R_{\varepsilon}\right) \psi d \sigma_{x}+\int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}} \kappa_{2}\left(R_{\varepsilon}\right) \psi d \sigma_{x}-\mathrm{L}_{\varepsilon}(\psi)=F_{\varepsilon}(\psi)
\end{gathered}
$$

for every $\psi \in H_{\text {per }}^{1}\left(\Omega_{\varepsilon}\right)$, where $\mathrm{L}_{\varepsilon}(\psi)$ is defined in (5.4), $F_{\varepsilon}(\psi)=I_{0}+\ldots+$ $I_{4}+I_{5}^{-}+I_{6}^{-}+I_{7}, I_{m}=I_{m}^{+}+I_{m}^{-}, m \in\{0, \ldots, 4\}, I_{7}=I_{7}^{+}+I_{7}^{-}, I_{k}^{-}=I_{k}^{1,-}+$ $I_{k}^{2,-}, k \in\{0, \ldots, 7\}$.

Subtracting (5.3) from the integral identity above, we get

$$
\begin{align*}
& \int_{\Omega_{\varepsilon}}\left(\nabla_{x}\left(R_{\varepsilon}-u_{\varepsilon}\right) \cdot \nabla_{x} \psi+\left(k_{0}\left(R_{\varepsilon}\right)-k_{0}\left(u_{\varepsilon}\right)\right) \psi\right) d x \\
& +\varepsilon^{\alpha} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}}\left(\kappa_{1}\left(R_{\varepsilon}\right)-\kappa_{1}\left(u_{\varepsilon}\right)\right) \psi d \sigma_{x}+\varepsilon \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}}\left(\kappa_{2}\left(R_{\varepsilon}\right)-\kappa_{2}\left(u_{\varepsilon}\right)\right) \psi d \sigma_{x} \\
& \quad+\int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}}\left(\kappa_{2}\left(R_{\varepsilon}\right)-\kappa_{2}\left(u_{\varepsilon}\right)\right) \psi d \sigma_{x}=F_{\varepsilon}(\psi) \quad \forall \psi \in H_{\mathrm{per}}^{1}\left(\Omega_{\varepsilon}\right) . \tag{5.41}
\end{align*}
$$

Let us estimate $F_{\varepsilon}(\psi)$. Using Cauchy-Bunyakovsky inequality, we get

$$
\left|I_{0}(\varepsilon, \psi)\right| \leq\left\|f_{0}-f_{\varepsilon}\right\|_{L^{2}\left(\Omega_{\varepsilon}\right)}\|\psi\|_{L^{2}\left(\Omega_{\varepsilon}\right)}
$$

Since $\partial_{\xi_{1}} \mathscr{Z}^{+}, \partial_{x_{2} \xi_{2}}^{2} \mathscr{Z}^{+}, \partial_{\xi_{1}} \mathscr{Z}^{i,-}, \partial_{x_{2} \xi_{2}}^{2} \mathscr{Z}^{i,-}$ exponentially decrease as $\left|\xi_{1}\right| \rightarrow \infty$ (see (5.20), (5.21), (5.22)), on the grounds of [30, Lemma 3.1] we deduce that

$$
\forall \mu>0 \quad \exists C_{2}>0 \quad \exists \varepsilon_{0}>0 \quad \forall \varepsilon \in\left(0, \varepsilon_{0}\right): \quad\left|I_{1}(\varepsilon, \psi)\right| \leq C_{2} \varepsilon^{1-\mu}\|\psi\|_{H^{1}\left(\Omega_{\varepsilon}\right)}
$$

Integrals in $I_{2}(\varepsilon, \psi)$ are over the set $\left\{x \in \Omega_{\varepsilon}: \delta / 2<\left|r-r_{0}\right|<\delta\right\}$, where according to (5.20), (5.21), and (5.22) the functions $\mathscr{Z}^{+}, \partial_{\xi_{1}} \mathscr{Z}^{+}, \partial_{\xi_{1}} \mathscr{Z}^{i,-}$ are exponentially small. The functions $\mathscr{Z}^{i,-}$ can be estimated by some constant $c_{0}$. Thus,

$$
\left|I_{2}(\varepsilon, \psi)\right| \leq C_{3} \varepsilon\|\psi\|_{H^{1}\left(\Omega_{\varepsilon}\right)}
$$

Integrals in $I_{3}$ are over $\left\{x \in \Omega_{\varepsilon}:\left|r-r_{0}\right|<\delta\right\}$ and can be estimated extracting the exponentially decreasing part in the proper integrals and using the Cauchy-Schwartz-Bunyakovsky inequality. Consider, for instance, the integral

$$
\begin{aligned}
& \left|\int_{\Omega_{\varepsilon}^{(1)}} \chi_{0} \partial_{x_{2}} \not Z^{1,-} \partial_{x_{2}} \psi d x\right|=\mid \int_{\Omega_{\varepsilon}^{(1)}} \chi_{0}\left\{\partial _ { x _ { 2 } } \left(\left.\left(\xi_{1}-h_{1}\left(r_{0}\right)\left(Z_{1}(\xi)-c_{1}^{(1)}\right)\right) \partial_{r} u_{0}^{1,-}\right|_{\Omega^{\prime}}\right.\right. \\
& \quad-\left.h_{2}\left(r_{0}\right)\left(Z_{2}(\xi)-c_{2}^{(1)}\right) \partial_{r} u_{0}^{2,-}\right|_{\Omega^{\prime}}+\left.\left(Z_{3}(\xi)-Y_{1}\left(\xi_{2}\right)-c_{3}^{(1)}\right) \partial_{x_{2}} u_{0}^{+}\right|_{\Omega^{\prime}} \\
& \left.\left.-\left.c_{1}^{(1)} h_{1}\left(r_{0}\right) \partial_{r} u_{0}^{1,-}\right|_{\Omega^{\prime}}-\left.c_{2}^{(1)} h_{2}\left(r_{0}\right) \partial_{r} u_{0}^{2,-}\right|_{\Omega^{\prime}}\right)\right\}\left.\right|_{\xi_{1}=-\left(r-r_{0}\right) / \varepsilon, \xi_{2}=x_{2} / \varepsilon} \partial_{x_{2}} \psi d x \mid \\
& \leq c_{1}\|\psi\|_{H^{1}\left(\Omega_{\varepsilon}\right)}\left(\sqrt { \varepsilon } \left(\left\|\xi_{1}-h_{1}\left(r_{0}\right)\left(Z_{1}-c_{1}^{(1)}\right)\right\|_{L^{2}\left(\Pi_{1}^{-}\right)}+\left\|Z_{2}-c_{2}^{(1)}\right\|_{L^{2}\left(\Pi_{1}^{-}\right)}\right.\right. \\
& \left.\left.\quad+\left\|Z_{3}-Y_{1}-c_{3}^{(1)}\right\|_{\left.L^{2}\left(\Pi_{1}^{-}\right)\right)}\right)+\sqrt{\left|\Omega_{\varepsilon}^{(1)}\right|}\right)
\end{aligned}
$$

where $\left|\Omega_{\varepsilon}^{(1)}\right|$ is the Lebesgue measure of $\Omega_{\varepsilon}^{(1)}$. Thanks to (5.20), (5.21), and (5.22) we conclude that the norms in the right-hand sides of the last inequality are uniformly bounded with respect to $\varepsilon$. Analogously we can estimate the rest of the summands in $I_{3}(\varepsilon, \psi)$. As a result, we get the estimate

$$
\left|I_{3}(\varepsilon, \psi)\right| \leq C_{4} \varepsilon\|\psi\|_{H^{1}\left(\Omega_{\varepsilon}\right)}
$$

Remark 5.2 The constants $C_{3}$ and $C_{4}$ depend on

$$
\left.\left.\left.\sup _{x \in \Omega^{\prime}}\left|\partial_{x_{k}} u_{0}^{+}\right|_{\Omega^{\prime}}\left|, \sup _{x \in \Omega^{\prime}}\right| \partial_{x_{k} x_{m}}^{2} u_{0}^{+}\right|_{\Omega^{\prime}}\left|, \sup _{x \in \Omega^{\prime}}\right| \partial_{x_{k}} u_{0}^{i,-}\right|_{\Omega^{\prime}}\left|, \sup _{x \in \Omega^{\prime}}\right| \partial_{x_{k} x_{m}}^{2} u_{0}^{i,-}\right|_{\Omega^{\prime}} \mid,
$$

where $k, m \in\{1,2,3\}$. Extending problem (5.32) periodically with respect to $x_{2}$ through the planes $\left\{x: x_{2}=0\right\}$ and $\left\{x: x_{2}=l\right\}$ and taking (4.5) and assumptions for $f_{0}$ and $g_{0}$ into account, we conclude that these quantities are bounded thanks to results on the smoothness of solutions to semilinear BVPs (see e.g. [132, Sect. 14]).

Theorem's assumptions imply that $\partial_{x_{2}} u_{0}^{i,-} \in H^{1}\left(\Omega^{(i)}\right), i=1,2$. Therefore

$$
\left|I_{4}^{-}(\varepsilon, \psi)\right| \leq c_{2} \varepsilon \sum_{i=1}^{2}\left(\left\|u_{0}^{i,-}\right\|_{H^{1}\left(\Omega^{(i)}\right)}+\left\|\partial_{x_{2}} u_{0}^{i,-}\right\|_{H^{1}\left(\Omega^{(i)}\right)}\right)\|\psi\|_{H^{1}\left(\Omega_{\varepsilon}\right)} \leq C_{5} \varepsilon\|\psi\|_{H^{1}\left(\Omega_{\varepsilon}\right)}
$$

With the help of (2.9), (2.17), (2.13), (5.7), (5.42), and (4.9), we deduce

$$
\begin{gathered}
\left|I_{5}^{-}(\varepsilon, \psi)\right| \leq C_{6} \begin{cases}\left(\varepsilon+\left\|g_{0}-g_{\varepsilon}\right\|_{L^{2}\left(\Omega^{(2)}\right)}\right)\|\psi\|_{H^{1}\left(\Omega_{\varepsilon}\right)}, & \beta=1 \\
\varepsilon^{\beta-1}\|\psi\|_{H^{1}\left(\Omega_{\varepsilon}\right)}, & \beta>1\end{cases} \\
\left|I_{6}^{-}(\varepsilon, \psi)\right| \leq C_{7} \begin{cases}\varepsilon\|\psi\|_{H^{1}\left(\Omega_{\varepsilon}\right)}, & \alpha=1, \\
\left(\varepsilon^{\alpha-1}+\varepsilon\right)\|\psi\|_{H^{1}\left(\Omega_{\varepsilon}\right)}, & \alpha>1\end{cases}
\end{gathered}
$$

It follows from (4.5) that

$$
\begin{equation*}
\left|\kappa\left(s_{1}\right)-\kappa\left(s_{2}\right)\right| \leq c_{3}\left|s_{1}-s_{2}\right| \quad \forall s_{1}, s_{2} \in \mathbb{R} \tag{5.42}
\end{equation*}
$$

Using (5.42), we establish that

$$
\begin{aligned}
\left|I_{7}^{1,-}(\varepsilon, \psi)\right| \leq c_{4} \varepsilon \int_{\Omega_{\varepsilon}^{(1)}} \left\lvert\,\left(\left(Y_{1}\left(\frac{x_{2}}{\varepsilon}\right)\right.\right.\right. & \left.\left.+c_{3}^{(1)}\right) \partial_{x_{2}} u_{0}^{1,-}+\chi_{0} \mathscr{Z}^{1,-}\right) \psi \mid d x \\
& \leq c_{5} \varepsilon\left(\|\psi\|_{L^{2}\left(\Omega_{\varepsilon}^{(1)}\right)}+\int_{\Omega_{\varepsilon}^{(1)}} \chi_{0}\left|\mathscr{Z}^{1,-} \psi\right| d x\right)
\end{aligned}
$$

The last integral of the obtained inequality can be estimated by subtracting the exponentially decreasing part and exploiting [30, Lemma 3.1] (similarly as it was done for $\left.I_{3}\right)$. Thus, $\left|I_{7}^{1,-}(\varepsilon, \psi)\right| \leq c_{6} \varepsilon\|\psi\|_{H^{1}\left(\Omega_{\varepsilon}\right)}, \varepsilon \in\left(0, \varepsilon_{0}\right)$. By the same way, we estimate $I_{7}^{+}$and $I_{7}^{2,-}$. As a result, we get

$$
\left|I_{7}(\varepsilon, \psi)\right| \leq C_{8} \varepsilon\|\psi\|_{H^{1}\left(\Omega_{\varepsilon}\right)} \text { for all } \varepsilon \in\left(0, \varepsilon_{0}\right) \text { and } \psi \in H^{1}\left(\Omega_{\varepsilon}\right)
$$

Thus, for any $\mu>0$ and for all $\varepsilon \in\left(0, \varepsilon_{0}\right)$

$$
\begin{align*}
& \left|F_{\varepsilon}(\psi)\right| \leq C_{9}\left(\left\|f_{0}-f_{\varepsilon}\right\|_{L^{2}\left(\Omega_{\varepsilon}\right)}+\delta_{\beta, 1}\left\|g_{0}-g_{\varepsilon}\right\|_{L^{2}\left(\Omega^{(2)}\right)}+\right. \\
& \left.\quad \varepsilon^{1-\mu}+\varepsilon^{\alpha-1+\delta_{\alpha, 1}}+\left(1-\delta_{\beta, 1}\right) \varepsilon^{\beta-1}+\right)\|\psi\|_{H^{1}\left(\Omega_{\varepsilon}\right)} \tag{5.43}
\end{align*}
$$

Condition (4.5) provides the inequality:

$$
\begin{equation*}
\left(k_{0}\left(s_{1}\right)-k_{0}\left(s_{2}\right)\right)\left(s_{1}-s_{2}\right) \geq c_{7}\left(s_{1}-s_{2}\right)^{2} \quad \forall s_{1}, s_{2} \in \mathbb{R} \tag{5.44}
\end{equation*}
$$

Clearly, the same inequality holds for $\kappa_{1}$ and $\kappa_{2}$.
Setting $\psi:=R_{\varepsilon}-u_{\varepsilon}$ in (5.41) and using (5.43) and (5.44), we deduce (5.35).
Corollary 5.1 Let assumptions of Theorem 5.1 hold and let $\mathbf{u}=\left(u_{0}^{+}, u_{0}^{1,-}, u_{0}^{2,-}\right)$ be a weak solution to problem (5.32). Then estimate (5.35) implies that

$$
\begin{aligned}
\left\|u_{\varepsilon}-\left.\mathbf{u}\right|_{\Omega_{\varepsilon}}\right\|_{L^{2}\left(\Omega_{\varepsilon}\right)} \leq C_{10}\left(\left\|f_{0}-f_{\varepsilon}\right\|_{L^{2}\left(\Omega_{\varepsilon}\right)}\right. & +\delta_{\beta, 1}\left\|g_{0}-g_{\varepsilon}\right\|_{L^{2}\left(\Omega^{(2)}\right)} \\
& \left.+\varepsilon^{1-\mu}+\varepsilon^{\alpha-1+\delta_{\alpha, 1}}+\left(1-\delta_{\beta, 1}\right) \varepsilon^{\beta-1}\right)
\end{aligned}
$$

where

$$
\left.\mathbf{u}\right|_{\Omega_{\varepsilon}}(x)= \begin{cases}u_{0}^{+}(x), & x \in \Omega_{0} \\ u_{0}^{1,-}(x), & x \in \Omega_{\varepsilon}^{(1)} \\ u_{0}^{2,-}(x), & x \in \Omega_{\varepsilon}^{(2)}\end{cases}
$$

### 5.2 Semilinear Parabolic Problem

### 5.2.1 Statement of the Problem

For parabolic case, the right-hand sides $f_{\varepsilon}$ and $g_{\varepsilon}$ belong to $L^{2}\left((0, T) \times \Omega_{\varepsilon}\right)$ and $L^{2}\left((0, T) \times \Omega^{(2)}\right)$, respectively. In addition, there exists a weak derivative $\partial_{x_{2}} g_{\varepsilon} \in$ $L^{2}\left((0, T) \times \Omega^{(2)}\right)$, and

$$
\exists C_{0}>0 \quad \exists \varepsilon_{0}>0 \quad \forall \varepsilon \in\left(0, \varepsilon_{0}\right):\left\|g_{\varepsilon}\right\|_{L^{2}\left((0, T) \times \Omega^{(2)}\right)}+\left\|\partial_{x_{2}} g_{\varepsilon}\right\|_{L^{2}\left((0, T) \times \Omega^{(2)}\right)}<C_{0}
$$

The functions $k_{0}, \kappa_{1}$, and $\kappa_{2}$ satisfy conditions (4.5), and the parameters $\alpha, \beta \geq 1$.
Consider the following semilinear parabolic problem with Robin boundary conditions on the surfaces of the thin discs from both levels:

$$
\begin{cases}\partial_{t} u_{\varepsilon}(t, x)-\Delta_{x} u_{\varepsilon}+k_{0}\left(u_{\varepsilon}\right)=f_{\varepsilon}, & (t, x) \in(0, T) \times \Omega_{\varepsilon},  \tag{5.45}\\ \partial_{\nu} u_{\varepsilon}(t, x)+\varepsilon^{\alpha} \kappa_{1}\left(u_{\varepsilon}\right)=\varepsilon^{\beta} g_{\varepsilon}, & (t, x) \in(0, T) \times \partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}, \\ \partial_{\nu} u_{\varepsilon}(t, x)+\varepsilon \kappa_{2}\left(u_{\varepsilon}\right)=\varepsilon^{\beta} g_{\varepsilon}, & (t, x) \in(0, T) \times \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}, \\ \partial_{\nu} u_{\varepsilon}(t, x)+\kappa_{2}\left(u_{\varepsilon}(t, x)\right)=0, & (t, x) \in(0, T) \times \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}, \\ \partial_{\nu} u_{\varepsilon}(t, x)=0, & (t, x) \in(0, T) \times \partial \Omega_{\varepsilon} \cap\left\{r=r_{0}\right\}, \\ \partial_{x_{2}}^{p} u_{\varepsilon}\left(t, x_{1}, 0, x_{3}\right)=\partial_{x_{2}}^{p} u_{\varepsilon}\left(t, x_{1}, l, x_{3}\right), & (t, x) \in(0, T) \times \partial \Omega_{0} \cap\left\{r<r_{0}\right\}, p=0,1, \\ u(0, x)=0, & x \in \Omega_{\varepsilon} .\end{cases}
$$

We introduce the space $W_{T, \text { per }}\left(\Omega_{\varepsilon}\right)$ defined by

$$
W_{T, \operatorname{per}}\left(\Omega_{\varepsilon}\right):=\left\{\varphi \in L^{2}\left(0, T ; H_{\mathrm{per}}^{1}\left(\Omega_{\varepsilon}\right)\right): \partial_{t} \varphi:=\varphi^{\prime} \in L^{2}\left(0, T ;\left(H_{\mathrm{per}}^{1}\left(\Omega_{\varepsilon}\right)\right)^{*}\right)\right\} .
$$

It is known (see e.g. [42, Sect. 1, Chap. 4]) that $W_{T, \text { per }}\left(\Omega_{\varepsilon}\right) \subset C\left([0, T] ; L^{2}\left(\Omega_{\varepsilon}\right)\right)$.
Definition 5.3 A function $u_{\varepsilon} \in W_{T, \text { per }}\left(\Omega_{\varepsilon}\right)$ is called a weak solution to problem (5.45) if for any $\varphi \in H_{\text {per }}^{1}\left(\Omega_{\varepsilon}\right)$ and a.e. $t \in(0, T)$ the following identity holds:

$$
\begin{align*}
& \left\langle\partial_{t} u_{\varepsilon}, \varphi\right\rangle_{H_{\mathrm{per}}^{1}\left(\Omega_{\varepsilon}\right)}+\int_{\Omega_{\varepsilon}}\left(\nabla_{x} u_{\varepsilon} \cdot \nabla_{x} \varphi+\omega\left(u_{\varepsilon}\right) \varphi\right) d x+\varepsilon^{\alpha} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}} \kappa_{1}\left(u_{\varepsilon}\right) \varphi d \sigma_{x} \\
& +\varepsilon \int_{\partial \Omega_{\varepsilon}^{(2) \cap\left\{r_{0}<r<r_{2}\right\}}} \kappa_{2}\left(u_{\varepsilon}\right) \varphi d \sigma_{x}+\int_{\partial \Omega_{\varepsilon}^{(2) \cap\left\{r=r_{2}\right\}}} \kappa_{2}\left(u_{\varepsilon}\right) \varphi d \sigma_{x}=\mathrm{L}_{\varepsilon}(\varphi) \tag{5.46}
\end{align*}
$$

where the functional $L_{\varepsilon}$ is defined in (5.4).
Similarly as in $[92,131]$, we can show that for every fixed $\varepsilon>0$ there exists a unique weak solution of problem (5.45).

### 5.2.2 Formal Asymptotic Expansions

Here the approach of Sect. 5.1.2 is used, but now we have to account for the time variable $t$. The outer asymptotic expansion for the solution $u_{\varepsilon}$ in the domain $\Omega_{0}$ has the form (5.5) and in $\Omega_{\varepsilon}^{(i)}(j)$ has the form (5.6), where all terms additionally depend on $t$.

Substituting the expansion (5.5) into the first equation of problem (5.45), into the boundary conditions on $\partial \Omega_{0} \cap\left\{r<r_{0}\right\}$, and into the initial conditions, using (5.7), and collecting coefficients at the same powers of $\varepsilon$, we derive the relations for the function $u_{0}^{+}$:

$$
\begin{cases}\partial_{t} u_{0}^{+}(t, x)-\Delta_{x} u_{0}^{+}(t, x)+k_{0}\left(u_{0}^{+}(t, x)\right)=f_{0}(t, x), & (t, x) \in(0, T) \times \Omega_{0}, \\ \partial_{x_{2}}^{p} u_{0}^{+}\left(t, x_{1}, 0, x_{3}\right)=\partial_{x_{2}}^{p} u_{0}^{+}\left(t, x_{1}, l, x_{3}\right), & (t, x) \in \partial \Omega_{0} \cap\left\{r<r_{0}\right\}, p=0,1, \\ u_{0}^{+}(0, x)=0, & x \in \Omega_{0} .\end{cases}
$$

We rewrite expansion (5.6) in the form (5.8) and substitute it in problem (5.45) instead of $u_{\varepsilon}$. Bearing in mind (2.8), (5.10), and collecting coefficients at the same powers of $\varepsilon$, we arrive at problems with respect to the variable $\xi_{2}$ for $U_{k}^{i,-}$.

The functions $U_{1}^{i,-}, i=1,2$, are solutions to problems (5.11), whence we deduce that they are independent of $\xi_{2}$. Thus, $U_{1}^{i,-}$ is equal to some function $\varphi_{1}^{(i)}\left(t, x_{1}, \varepsilon(j+\right.$ $\left.l_{i}\right), x_{3}$ ), which will be defined later. According to (5.9), equality (5.12) takes place.

Problems for $U_{2}^{1,-}$ and $U_{2}^{2,-}$ look as follows:

$$
\begin{aligned}
& \partial_{\xi_{2} \xi_{2}}^{2} U_{2}^{1,-}=\left.\left(\partial_{t} u_{0}^{1,-}-\Delta_{\tilde{x}} u_{0}^{1,-}+k_{0}\left(u_{0}^{1,-}\right)-f_{0}\right)\right|_{x_{2}=\varepsilon\left(j+l_{1}\right)}, \quad \xi_{2} \in \varepsilon^{-1} I_{\varepsilon}^{(1)}\left(j, h_{1}(r)\right), \\
& \quad \pm\left.\partial_{\xi_{2}} U_{2}^{1,-}\right|_{\xi_{2}=j+l_{1} \pm \frac{h_{1}(r)}{2}}=\left.\left(2^{-1} \nabla_{\tilde{x}} h_{1} \cdot \nabla_{\tilde{x}} u_{0}^{1,-}-\delta_{\alpha, 1} \kappa_{1}\left(u_{0}^{1,-}\right)+\delta_{\beta, 1} g_{0}\right)\right|_{x_{2}=\varepsilon\left(j+l_{1}\right)},
\end{aligned}
$$

and

$$
\begin{aligned}
& \partial_{\xi_{2} \xi_{2}}^{2} U_{2}^{2,-}=\left.\left(\partial_{t} u_{0}^{2,-}-\Delta_{\tilde{x}} u_{0}^{2,-}+k_{0}\left(u_{0}^{2,-}\right)-f_{0}\right)\right|_{x_{2}=\varepsilon\left(j+l_{2}\right)}, \quad \xi_{2} \in \varepsilon^{-1} I_{\varepsilon}^{(2)}\left(j, h_{2}(r)\right), \\
& \quad \pm\left.\partial_{\xi_{2}} U_{2}^{2,-}\right|_{\xi_{2}=j+l_{2} \pm \frac{h_{2}(r)}{2}}=\left.\left(2^{-1} \nabla_{\tilde{x}} h_{2} \cdot \nabla_{\tilde{x}} u_{0}^{2,-}-\kappa_{2}\left(u_{0}^{2,-}\right)+\delta_{\beta, 1} g_{0}\right)\right|_{x_{2}=\varepsilon\left(j+l_{2}\right)},
\end{aligned}
$$

respectively. Solvability conditions for these problems read

$$
h_{1}(r) \partial_{t} u_{0}^{1,-}-\operatorname{div}_{\tilde{x}}\left(h_{1}(r) \nabla_{\tilde{x}} u_{0}^{1,-}\right)+h_{1}(r) k_{0}\left(u_{0}^{1,-}\right)+2 \delta_{\alpha, 1} \kappa_{1}\left(u_{0}^{1,-}\right)=h_{1}(r) f_{0}+2 \delta_{\beta, 1} g_{0}
$$

where $t \in(0, T), r \in\left(r_{0}, r_{1}\right), x_{2}=\varepsilon\left(j+l_{1}\right)$, and

$$
h_{2}(r) \partial_{t} u_{0}^{2,-}-\operatorname{div}_{\tilde{x}}\left(h_{2}(r) \nabla_{\tilde{x}} u_{0}^{2,-}\right)+h_{2}(r) k_{0}\left(u_{0}^{2,-}\right)+2 \kappa_{2}\left(u_{0}^{2,-}\right)=h_{2}(r) f_{0}+2 \delta_{\beta, 1} g_{0}
$$

where $t \in(0, T), r \in\left(r_{0}, r_{2}\right), x_{2}=\varepsilon\left(j+l_{2}\right)$, respectively.
Substituting (5.8) into the Robinr boundary conditions on $\partial \Omega_{\varepsilon}^{(i)} \cap\left\{r=r_{i}\right\}$ we get (5.15). Substituting (5.8) into the initial conditions of problem (5.45) we obtain

$$
u_{0}^{i,-}(0, x)=0, \quad r \in\left(r_{0}, r_{i}\right), x_{2}=\varepsilon\left(j+l_{i}\right), i=1,2
$$

In order to find relations on the joint zone $\Omega^{\prime}$, we use the method of matched asymptotic expansions.

We seek for the leading terms of the inner expansion for the $u_{\varepsilon}$ at a neighborhood of the joint zone $\Omega^{\prime}$ in the form

$$
\begin{align*}
& \left.u_{\varepsilon}(t, x) \approx u_{0}^{+}\right|_{\Omega^{\prime}}(t, x)+\varepsilon\left(\left.Z_{3}(\xi) \partial_{x_{2}} u_{0}^{+}\right|_{\Omega^{\prime}}(t, x)\right. \\
& \left.-\left.\left\{\eta\left(t, x_{2}, \theta\right) Z_{2}(\xi)+\left(1-\eta\left(t, x_{2}, \theta\right)\right) Z_{1}(\xi)\right\} \partial_{r} u_{0}^{+}\right|_{\Omega^{\prime}}(t, x)\right)\left.\right|_{\xi_{1}=-\frac{r-r_{0}}{\varepsilon}, \xi_{2}=\frac{x_{2}}{\varepsilon}}+\ldots, \tag{5.47}
\end{align*}
$$

where $Z_{1}, Z_{2}, Z_{3}$ are solutions to problem (5.18) and (5.19) with the asymptotics (5.20), (5.21), and (5.22), respectively.

Matching the outer expansions with the inner one and repeating assertions of Sect. 5.1.2, we derive the transmission conditions (5.30) and define the functions $\eta$ and $\varphi_{1}^{(i)}, i=1,2$, (see (5.29)) and (5.31)).

### 5.2.3 The Homogenized Problem

Obtained relations for the leading terms $u_{0}^{+}, u_{0}^{1,-}$, and $u_{0}^{2,-}$ constitute the homogenized problem for problem (5.45):

$$
\begin{cases}\partial_{t} u_{0}^{+}-\Delta_{x} u_{0}^{+}+k_{0}\left(u_{0}^{+}\right)=f_{0}, & (t, x) \in(0, T) \times \Omega_{0}, \\ \partial_{x_{2}}^{p} u_{0}^{+}\left(t, x_{1}, 0, x_{3}\right)=\partial_{x_{2}}^{p} u_{0}^{+}\left(t, x_{1}, l, x_{3}\right), p=0,1,(t, x) \in(0, T) \times \partial \Omega_{0} \cap\left\{r<r_{0}\right\}, \\ h_{1} \partial_{t} u_{0}^{1,-}-\operatorname{div}_{\tilde{x}}\left(h_{1} \nabla_{\tilde{x}} u_{0}^{1,-}\right)+h_{1} k_{0}\left(u_{0}^{1,-}\right) & (t, x) \in(0, T) \times \Omega^{(1)}, \\ +2 \delta_{\alpha, 1} \kappa_{1}\left(u_{0}^{1,-}\right)=h_{1} f_{0}+2 \delta_{\beta, 1} g_{0}, & (t, x) \in(0, T) \times \partial \Omega^{(1)} \cap\left\{r=r_{1}\right\}, \\ \partial_{\nu} u_{0}^{1,-}=0, & (t, x) \in(0, T) \times \Omega^{(2)}, \\ h_{2} \partial_{t} u_{0}^{2,-}-\operatorname{div}_{\tilde{x}}\left(h_{2} \nabla_{\tilde{x}} u_{0}^{2,-}\right)+h_{2} k_{0}\left(u_{0}^{2,-}\right) & (t, x) \in(0, T) \times \partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}, \\ +2 \kappa_{2}\left(u_{0}^{2,-}\right)=h_{2} f_{0}+2 \delta_{\beta, 1} g_{0}, & (t, x) \in(0, T) \times \Omega^{\prime}, \\ \partial_{\nu} u_{0}^{2,-}+\kappa_{2}\left(u_{0}^{2,-}\right)=0, & (t, x) \in(0, T) \times \Omega^{\prime}, \\ u_{0}^{+}=u_{0}^{1,-}=u_{0}^{2,-}, & \\ \partial_{r} u_{0}^{+}=\sum_{i=1}^{2} h_{i}\left(r_{0}\right) \partial_{r} u_{0}^{i,-}, & \\ \mathbf{u}_{0}(0, x)=\mathbf{0} . & \end{cases}
$$

where $\mathbf{u}_{0}=\left(u_{0}^{+}, u_{0}^{1,-}, u_{0}^{2,-}\right)$. Consider a space of multivalued functions

$$
\mathbf{W}_{T, \text { per }}:=\left\{\mathbf{p}=\left(p_{0}, p_{1}, p_{2}\right) \in L^{2}\left(0, T ; \widetilde{\mathbf{H}}_{\mathrm{per}}\right): \partial_{t} \mathbf{p}:=\mathbf{p}^{\prime} \in L^{2}\left(0, T ; \widetilde{\mathbf{H}}_{\mathrm{per}}^{*}\right)\right\} .
$$

Definition 5.4 A function $\mathbf{u}=\left(u_{0}, u_{1}, u_{2}\right) \in L^{2}\left(0, T ; \widetilde{\mathbf{H}}_{\text {per }}\right)$ is called a weak solution to problem (5.48) if the following integral identity holds for every $\mathbf{p} \in \mathbf{W}_{T, \text { per }}$ :

$$
\begin{gathered}
\int_{\Omega_{0}} u_{0}(T, x) p_{0}(T, x) d x+\sum_{i=1}^{2} \int_{\Omega^{(i)}} h_{i}(r) u_{i}(T, x) p_{i}(T, x) d x \\
+\int_{0}^{T}\left(-\left\langle u_{0}, \partial_{t} p_{0}\right\rangle_{H_{\mathrm{per}}^{1}\left(r_{0}\right)}-\sum_{i=1}^{2}\left\langle h_{i} u_{i}, \partial_{t} p_{i}\right\rangle_{\tilde{H}^{1}\left(\Omega^{(i)}\right)}+\int_{\Omega_{0}}\left(\nabla_{x} u_{0} \cdot \nabla_{x} p_{0}+k_{0}\left(u_{0}\right) p_{0}\right) d x\right. \\
+\sum_{i=1}^{2} \int_{\Omega^{(i)}} h_{i}(r)\left(\nabla_{\tilde{x}} u_{i} \cdot \nabla_{\tilde{x}} p_{i}+k_{0}\left(u_{i}\right) p_{i}\right) d x+h_{2}\left(r_{0}\right) \int_{\partial \Omega^{(2)} \cap\left\{r=r_{2}\right\}} \kappa_{2}\left(u_{2}\right) p_{2} d \sigma_{x} \\
\left.+2 \delta_{\alpha, 1} \int_{\Omega^{(1)}} \kappa_{1}\left(u_{1}\right) p_{1} d x+2 \int_{\Omega^{(2)}} \kappa_{2}\left(u_{2}\right) p_{2} d x\right) d t=\int_{0}^{T} \mathrm{~L}(\mathbf{p}) d t,
\end{gathered}
$$

where the space $\widetilde{\mathbf{H}}_{\text {per }}$ is defined in Sect. 3.4.1 and the functional

$$
\mathrm{L}(\mathbf{p})=\int_{\Omega_{0}} f_{0} p_{0} d x+\sum_{i=1}^{2} \int_{\Omega^{(i)}}\left(h_{i}(r) f_{0}+2 \delta_{\beta, 1} g_{0}\right) p_{i} d x
$$

Using the theory of monotone operators (see e.g. [92, 131]), we can state that there exists a unique weak solution to problem (5.48).

### 5.2.4 Asymptotic Approximation and Estimates

With the help of the solution $\mathbf{u}_{0}$ to the homogenized problem (5.48), the solutions $Z_{1}, Z_{2}, Z_{3}$ to problems (5.18) and (5.19), respectively, and the cut-off function $\chi_{0}$ defined in Sect.5.1.4, we construct the approximation function $R_{\varepsilon}(t, x)$ by formulas (5.33) and (5.34) (the dependence on the variable $t$ only in terms containing $u_{0}^{+}(t, x), u_{0}^{1,-}(t, x), u_{0}^{2,-}(t, x)$ and their derivatives $)$.

Theorem 5.2 Suppose that in addition to the assumptions made in Sect. 5.2.1, the following conditions hold: $f_{0} \in C^{3}\left([0, T] \times \overline{\Omega_{0} \cup \Omega^{(2)}}\right) ; g_{0} \in C^{3}\left([0, T] \times \overline{\Omega^{(2)}}\right)$ and it vanishes at a neighborhood of the joint zone $\Omega^{\prime} ; \partial_{x_{2}}^{p} f_{0}\left(t, x_{1}, 0, x_{3}\right)=$ $\partial_{x_{2}}^{p} f_{0}\left(t, x_{1}, l, x_{3}\right)$ for $(t, x) \in[0, T] \times \partial \Omega_{0} \cap\left\{r<r_{0}\right\}$ and $p=0,1 ; f_{0}(0, x)=$ $g_{0}(0, x)=0$. Then for any $\mu>0$ there exist positive constants $\varepsilon_{0}, C_{1}$ such that for all values $\varepsilon \in\left(0, \varepsilon_{0}\right)$

$$
\begin{align*}
& \left\|u_{\varepsilon}-R_{\varepsilon}\right\|_{L^{2}\left(0, T ; H^{1}\left(\Omega_{\varepsilon}\right)\right)}+\max _{t \in[0, T]}\left\|u_{\varepsilon}(t, \cdot)-R_{\varepsilon}(t, \cdot)\right\|_{L^{2}\left(\Omega_{\varepsilon}\right)} \leq C_{1}\left(\varepsilon^{1-\mu}+\varepsilon^{\alpha-1+\delta_{\alpha, 1}}\right. \\
& +\left(1-\delta_{\beta, 1)} \varepsilon^{\beta-1}+\left\|f_{0}-f_{\varepsilon}\right\|_{L^{2}\left((0, T) \times \Omega_{\varepsilon}\right)}+\delta_{\beta, 1}\left\|g_{0}-g_{\varepsilon}\right\|_{L^{2}\left((0, T) \times \Omega^{(2)}\right)}\right) \tag{5.49}
\end{align*}
$$

Proof 1. Similar as in the first item of the proof of Theorem 5.1 we verify that $R_{\varepsilon}^{+}$ satisfies all of the boundary conditions of problem (5.45) on $\partial \Omega_{\varepsilon} \cap \partial \Omega_{0}$.

Using (5.16), (5.36), and (5.48), we derive that

$$
\begin{aligned}
& \partial_{t} R_{\varepsilon}^{+}(t, x)-\Delta_{x} R_{\varepsilon}^{+}(t, x)-f_{\varepsilon}(t, x)=f_{0}(t, x)-f_{\varepsilon}(t, x)-k_{0}\left(u_{0}^{+}(t, x)\right) \\
+ & \left.\varepsilon \chi_{0}(r) \partial_{t} \mathscr{Z}^{+}\left(t, \xi, x_{2}, \theta\right)\right|_{\xi_{1}=-\frac{r-r_{0}}{\varepsilon}, \xi_{2}=\frac{x_{2}}{\varepsilon}}-\varepsilon \Delta_{x}\left(\chi_{0}(r) \mathscr{Z}^{+}\left(t,-\frac{r-r_{0}}{\varepsilon}, \frac{x_{2}}{\varepsilon}, x_{2}, \theta\right)\right)
\end{aligned}
$$

in $(0, T) \times \Omega_{0}$. Then we rewrite the last summand similarly as in Theorem 5.1, multiply the last identity by a test function $\psi \in W_{T, \text { per }}\left(\Omega_{\varepsilon}\right)$, and integrate it over $(0, \tau) \times \Omega_{0}$, where $\tau \in(0, T)$ is an arbitrary number. As a result, we get

$$
\begin{gathered}
\int_{\Omega_{0}} R_{\varepsilon}^{+}(\tau, x) \psi(\tau, x) d x+\int_{0}^{\tau}\left(-\left\langle R_{\varepsilon}^{+}, \partial_{t} \psi\right\rangle_{H_{\mathrm{per}}^{1}\left(r_{0}\right)}+\int_{\Omega_{0}}\left(\nabla_{x} R_{\varepsilon}^{+} \cdot \nabla_{x} \psi+k_{0}\left(R_{\varepsilon}^{+}\right) \psi\right) d x\right. \\
\left.-\int_{\Omega_{\varepsilon}^{(1)} \cap\left\{r=r_{0}\right\} \cup \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{0}\right\}} \partial_{r} R_{\varepsilon}^{+} \psi d \sigma_{x}-\int_{\Omega_{0}} f_{\varepsilon} \psi d x\right) d t \\
=\int_{0}^{\tau}\left(I_{0}^{+}(\varepsilon, \psi, t)+\ldots+I_{4}^{+}(\varepsilon, \psi, t)+I_{7}^{+}(\varepsilon, \psi, t)+I_{8}^{+}(\varepsilon, \psi, t)\right) d t .
\end{gathered}
$$

Here $I_{0}^{+}, \ldots, I_{4}^{+}$, and $I_{7}^{+}$are defined in item $\mathbf{1}$ of the proof of Theorem 5.1 and

$$
I_{8}^{+}(\varepsilon, \psi, t)=\varepsilon \int_{\Omega_{0}} \chi_{0} \partial_{t} \mathscr{Z}^{+} \psi d x
$$

2. Now we find discrepancies in the thin discs. Direct calculations show that for a.e. $t \in(0, T)$ equalities (5.38), (5.39), and (5.40) hold. Using relations (5.16), (5.48), and (5.36), we derive that

$$
\begin{aligned}
& \partial_{t} R_{\varepsilon}^{i,-}(t, x)-\Delta_{x} R_{\varepsilon}^{i,-}(t, x)-f_{\varepsilon}(t, x)=f_{0}(t, x)-f_{\varepsilon}(t, x)-k_{0}\left(u_{0}^{i,-}(t, x)\right) \\
& +\nabla_{\tilde{x}}\left(\ln h_{i}(r)\right) \cdot \nabla_{\tilde{x}} u_{0}^{i,-}(t, x)-2\left(\delta_{i, 1} \delta_{\alpha, 1}+\delta_{i, 2}\right) h_{i}^{-1}(r) \kappa_{i}\left(u_{0}^{i,-}(t, x)\right)+2 \delta_{\beta, 1} h_{i}^{-1}(r) g_{0}(t, x) \\
& \quad-\varepsilon \operatorname{div}_{x}\left(\left(Y_{i}\left(\frac{x_{2}}{\varepsilon}\right)+c_{3}^{(i)}\right) \nabla_{x}\left(\partial_{x_{2}} u_{0}^{i,-}(t, x)\right)\right) \\
& \quad+\varepsilon\left(\left(Y_{i}\left(\frac{x_{2}}{\varepsilon}\right)+c_{3}^{(i)}\right) \partial_{t x_{2}}^{2} u_{0}^{i,-}+\left.\chi_{0}(r) \partial_{t} \not \mathscr{Z}^{i,-}\left(t, \xi, x_{2}, \theta\right)\right|_{\xi_{1}=-\frac{r-r_{0}}{\varepsilon}, \xi_{2}=\frac{x_{2}}{\varepsilon}}\right) \\
& \quad-\varepsilon \Delta_{x}\left(\chi_{0}(r) \not \mathscr{Z}^{i,-}\left(t,-\frac{r-r_{0}}{\varepsilon}, \frac{x_{2}}{\varepsilon}, x_{2}, \theta\right)\right), \quad(t, x) \in(0, T) \times \Omega_{\varepsilon}^{(i)}, i=1,2 .
\end{aligned}
$$

We rewrite the last summand similarly as in Theorem 5.1, then multiply the resulting equality by a test function $\psi \in W_{T, \text { per }}\left(\Omega_{\varepsilon}\right)$, and integrate it over $(0, \tau) \times \Omega_{\varepsilon}^{(i)}$. As a result, by the same way as in $\mathbf{2}$ and $\mathbf{3}$ items of the proof of Theorem 5.1, we get

$$
\begin{aligned}
& \int_{\Omega_{\varepsilon}} R_{\varepsilon}(\tau, x) \psi(\tau, x) d x+\int_{0}^{\tau}\left(-\left\langle R_{\varepsilon}, \partial_{t} \psi\right\rangle_{H_{\mathrm{per}}^{1}\left(\Omega_{\varepsilon}\right)}+\int_{\Omega_{\varepsilon}}\left(\nabla_{x} R_{\varepsilon} \cdot \nabla_{x} \psi+k_{0}\left(R_{\varepsilon}\right) \psi\right) d x\right. \\
& \quad+\varepsilon^{\alpha} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}} \kappa_{1}\left(R_{\varepsilon}\right) \psi d \sigma_{x}+\varepsilon \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}} \kappa_{2}\left(R_{\varepsilon}\right) \psi d \sigma_{x}
\end{aligned}
$$

$$
\begin{gathered}
+\int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}} \kappa_{2}\left(R_{\varepsilon}\right) \psi d \sigma_{x}-\int_{\Omega_{\varepsilon}} f_{\varepsilon} \psi d x \\
\left.\left.-\varepsilon^{\beta} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\} \cup \partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}} g_{\varepsilon} \psi d \sigma_{x}\right) d t=\int_{0}^{\tau} \sum_{m=0}^{8} I_{i}(\varepsilon, \psi, t)\right) d t
\end{gathered}
$$

for every $\psi \in W_{T, \text { per }}\left(\Omega_{\varepsilon}\right)$ and any $\tau \in(0, T)$. Here $I_{m}=I_{m}^{+}+I_{m}^{-}, m \in\{0, \ldots, 4\} \cup$ $\{7,8\}, I_{k}^{-}=I_{k}^{1,-}+I_{k}^{2,-}, k \in\{0, \ldots, 7\}$, are defined similarly as in the proof of Theorem 5.1, and $I_{8}^{-}=I_{8}^{1,-}+I_{8}^{2,-}$,

$$
I_{8}^{i,-}(\varepsilon, \psi, t)=\varepsilon \int_{\Omega_{\varepsilon}^{(i)}}\left(\left(Y_{i}\left(\frac{x_{2}}{\varepsilon}\right)+z_{3}^{(i)}\right) \partial_{x_{2} t}^{2} u_{0}^{i,-}+\chi_{0} \partial_{t} \mathscr{Z}^{i,-}\right) \psi d x, \quad i=1,2
$$

3. Subtracting (5.46) from the integral identity above, we obtain

$$
\begin{gather*}
\int_{\Omega_{\varepsilon}}\left(R_{\varepsilon}(\tau, x)-u_{\varepsilon}(\tau, x)\right) \psi(\tau, x) d x+\int_{0}^{\tau}\left(-\left\langle R_{\varepsilon}-u_{\varepsilon}, \partial_{t} \psi\right\rangle_{H_{\text {per }}^{1}\left(\Omega_{\varepsilon}\right)}\right. \\
+\int_{\Omega_{\varepsilon}}\left(\nabla_{x}\left(R_{\varepsilon}-u_{\varepsilon}\right) \cdot \nabla_{x} \psi+\left(k_{0}\left(R_{\varepsilon}\right)-k_{0}\left(u_{\varepsilon}\right)\right) \psi\right) d x \\
+\varepsilon \int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r_{0}<r<r_{2}\right\}}\left(\kappa_{2}\left(R_{\varepsilon}\right)-\kappa_{2}\left(u_{\varepsilon}\right)\right) \psi d \sigma_{x}+\int_{\partial \Omega_{\varepsilon}^{(2)} \cap\left\{r=r_{2}\right\}}\left(\kappa_{2}\left(R_{\varepsilon}\right)-\kappa_{2}\left(u_{\varepsilon}\right)\right) \psi d \sigma_{x} \\
\left.+\varepsilon^{\alpha} \int_{\partial \Omega_{\varepsilon}^{(1)} \cap\left\{r>r_{0}\right\}}\left(\kappa_{1}\left(R_{\varepsilon}\right)-\kappa_{1}\left(u_{\varepsilon}\right)\right) \psi d \sigma_{x}\right) d t=P_{\varepsilon}(\psi, \tau) \tag{5.50}
\end{gather*}
$$

for all $\psi \in W_{T, \text { per }}\left(\Omega_{\varepsilon}\right)$ and $\tau \in(0, T)$. Here, $\left.P_{\varepsilon}(\psi, \tau)=\int_{0}^{\tau} \sum_{m=0}^{8} I_{i}(\varepsilon, \psi, t)\right) d t$. In fact it remains to estimate $I_{8}$. Subtracting the exponentially decreasing part, similarly as it was done for $I_{3}$ in the proof of Theorem 5.1, we deduce

$$
\left|I_{8}(\varepsilon, \psi, \tau)\right| \leq C_{2} \varepsilon\|\psi\|_{L^{2}\left((0, \tau) \times \Omega_{\varepsilon}\right)}
$$

Remark 5.3 The constant $C_{2}$ depends on

$$
\left.\sup _{(t, x) \in(0, T) \times \Omega^{\prime}}\left|\partial_{t x_{j}}^{2} u_{0}^{+}\right|_{\Omega^{\prime}}\left|, \quad \sup _{(t, x) \in(0, T) \times \Omega^{\prime}}\right| \partial_{t x_{j}}^{2} u_{0}^{i,-}\right|_{\Omega^{\prime}} \mid, \quad i=1,2, j=1,2,3 .
$$

These quantities are bounded, which is explained similarly as in the Remark 5.2 but now we should cite [132, Sect. 15] or [68, Chap. 5, Sects. 6 and 7].

Taking into account estimates obtained for $\left\{I_{m}\right\}$ in the proof of Theorem 5.1, we have that for any $\mu>0$ there exists $\varepsilon_{0}>0$ such that for any $\tau \in(0, T)$ and $\varepsilon \in\left(0, \varepsilon_{0}\right)$

$$
\begin{align*}
& \left|P_{\varepsilon}(\psi, \tau)\right| \leq C_{3}\left(\left\|f_{\varepsilon}-f_{0}\right\|_{L^{2}\left((0, T) \times \Omega_{\varepsilon}\right)}+\varepsilon^{1-\mu}+\varepsilon^{\alpha-1+\delta_{\alpha, 1}}\right. \\
& \left.\quad+\left(1-\delta_{\beta, 1}\right) \varepsilon^{\beta-1}+\delta_{\beta, 1}\left\|g_{\varepsilon}-g_{0}\right\|_{L^{2}\left((0, T) \times \Omega^{(2)}\right)}\right)\|\psi\|_{L^{2}\left(0, T ; H^{1}\left(\Omega_{\varepsilon}\right)\right)} \tag{5.51}
\end{align*}
$$

Setting $\psi:=R_{\varepsilon}-u_{\varepsilon}$ in (5.50), with the help of (5.44) we obtain

$$
\frac{1}{2}\left\|u_{\varepsilon}(\tau, \cdot)-R_{\varepsilon}(\tau, \cdot)\right\|_{L^{2}\left(\Omega_{\varepsilon}\right)}^{2}+\left\|u_{\varepsilon}-R_{\varepsilon}\right\|_{L^{2}\left(0, \tau ; H^{1}\left(\Omega_{\varepsilon}\right)\right)}^{2} \leq c_{0}\left|P_{\varepsilon}\left(R_{\varepsilon}-u_{\varepsilon}, \tau\right)\right|
$$

for all $\tau \in(0, T)$. From this inequality, thanks to (5.51) it follows (5.49).
Corollary 5.2 Let assumptions of Theorem 5.2 hold and let $\mathbf{u}=\left(u_{0}^{+}, u_{0}^{1,-}, u_{0}^{2,-}\right)$ be a weak solution to problem (5.48). Then estimate (5.49) implies that

$$
\begin{aligned}
\max _{t \in[0, T]}\left\|u_{\varepsilon}(t, \cdot)-\left.\mathbf{u}\right|_{\Omega_{\varepsilon}}(t, \cdot)\right\|_{L^{2}\left(\Omega_{\varepsilon}\right)} & \leq C_{4}\left(\left\|f_{0}-f_{\varepsilon}\right\|_{L^{2}\left((0, T) \times \Omega_{\varepsilon}\right)}+\varepsilon^{1-\mu}+\varepsilon^{\alpha-1+\delta_{\alpha, 1}}\right. \\
+ & \left.\left(1-\delta_{\beta, 1}\right) \varepsilon^{\beta-1}+\delta_{\beta, 1}\left\|g_{0}-g_{\varepsilon}\right\|_{L^{2}\left((0, T) \times \Omega^{(2)}\right)}\right)
\end{aligned}
$$

where $\left.\mathbf{u}\right|_{\Omega_{\varepsilon}}(t, x)$ is defined similarly as in Corollary 5.1.

### 5.3 Conclusions to this Chapter

In contrast to the results of Chaps. 2, 3, and 4, where only the convergence theorems were proved, here the approximation functions are constructed and asymptotic estimates in the proper Sobolev spaces are proved for the solutions both to elliptic and parabolic semilinear problems (5.32) and (5.48). Those estimates allow us to use the corresponding approximations for applied problems that model physical (or biological) processes in thick multilevel junctions of the type 3:2:2, especially at a neighborhood of the joint zone $\Omega^{\prime}$.

The obtained results are consistent with the results of Chaps. 2 and 4, namely, the main terms of the asymptotic approximations are solutions to the similar homogenized problems.

Asymptotic estimates (5.35) and (5.49) show us the influence of different components of the initial problems on the order of residuals from the asymptotic approximations. Summands $\left\|f_{\varepsilon}-f_{0}\right\|$ and $\delta_{\beta, 1}\left\|g_{\varepsilon}-g_{0}\right\|$ correspond to discrepancies of the right-hand sides of the initial problem and homogenized one. In many textbooks and monographs on the asymptotic analysis, such kind of asymptotic estimates is typical (see e.g., [124, Chap.2]). To formally improve estimates, in some articles there are special assumptions, namely, either the right-hand side is independent of $\varepsilon$, i.e., $f_{\varepsilon} \equiv f_{0}$, or $f_{\varepsilon}(x)=f_{0}(x)+\mathscr{O}(\varepsilon)$ as $\varepsilon \rightarrow 0$.

The summand $C_{1} \varepsilon^{1-\mu}$ bounds residuals left by the inner expansion. They are caused by the existence of non-energetic solutions with polynomial growth at infinity of junction-layer problems (5.18) and (5.19). As follows from Sect.5.1.2, the
behavior of such solutions is determined by the type $m: k: d$ of a thick junction. For instance, junction-layer non-energetic solutions have logarithmic growth at infinity for boundary-value problems in thick junctions of the type 3:1:1 (see [88, 109]).

The rest of the summands in (5.35) and (5.49) indicate the impact of the geometric structure of the thick junction and inhomogeneous perturbed Robin boundary conditions on the surfaces of the thin discs.

Boundary conditions on the bases of the cylinder $\Omega_{0}$ can be replaced by boundary conditions of another type. But in the case of nonperiodic boundary conditions on $\partial \Omega_{0} \cap\left\{r<r_{0}\right\}$ additional symmetry condition is needed, namely, the domain $\Pi$ described in Sect.5.1.2 has to be invariant with respect to the substitution $\xi_{2} \mapsto$ $1-\xi_{2}$.

Also in this chapter, we made special assumptions for the functions $h_{1}$ and $h_{2}$; they should be locally constant at a small enough neighborhood of the joint zone. This is a technical condition that allows to avoid additional bulky calculations.

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